

# Please Enroll for the Course in PULS

- Everyone, including Cognitive Systems students.
- We no longer support paper enrollment lists.
- Do it now.
- The hard deadline for resolving any issues is October 31.

Universität Potsdam  
Institut für Informatik  
Lehrstuhl Maschinelles Lernen



# Model Evaluation

Tobias Scheffer

# Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- Model selection

# Learning and Evaluation

- Learning problem
  - ◆ Input: data  $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
  - ◆ Output: model  $f_\theta: X \rightarrow Y$
  
- When model is applied, it is used to make predictions for new instances  $\mathbf{x}$ .
  
- How well will  $f_\theta$  perform at application time?
  - ◆ What does “well” even mean?
  - ◆ How can it be determined?

# Model Evaluation

- Central assumption about data: drawn according to single (unknown) distribution  $p(\mathbf{x}, y)$ .
- **“IID assumption”**: Instances  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$  are drawn independently and from an identical distribution.
- Independent:  $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$ .
- Identical distribution:  $\forall i: (\mathbf{x}_i, y_i) \sim p(\mathbf{x}, y)$

# Model Evaluation

- **“IID assumption”**: Instances  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$  are drawn independently and from an identical distribution.
- Independent:  $p\left((\mathbf{x}_{i+j}, y_{i+j}) | (\mathbf{x}_i, y_i)\right) = p\left((\mathbf{x}_{i+j}, y_{i+j})\right)$ .
  - ◆ Counter example: people who are surveyed at a random but fixed geographical location.
  - ◆ Consequence: a dependent sample contains less variance than an independent sample.
- Identical distribution:  $\forall i: (\mathbf{x}_i, y_i) \sim p(\mathbf{x}, y)$ 
  - ◆ Counter example: first half of the data generated under laboratory conditions, second half collected “in the wild”.
  - ◆ Consequence: model trained on laboratory data may perform less well on data “in the wild”.

# Loss Function

- Loss function: How bad is it if the model predicts value  $f_{\theta}(\mathbf{x}_i)$  when the true value of the target variable is  $y_i$ ?

$$\ell(f_{\theta}(\mathbf{x}_i), y_i)$$

- Example loss functions:

- ◆ Zero-one loss (classification):

$$\ell_{0/1}(f_{\theta}(\mathbf{x}_i), y_i) = \begin{cases} 0 & \text{if } f_{\theta}(\mathbf{x}_i) = y_i \\ 1 & \text{otherwise} \end{cases}$$

- ◆ Quadratic loss (regression):

$$\ell_2(f_{\theta}(\mathbf{x}_i), y_i) = (f_{\theta}(\mathbf{x}_i) - y_i)^2$$

- ◆ Perceptron loss, hinge loss,  $\varepsilon$ -insensitive loss, ...

# Risk

- Risk of model  $f_\theta$ : expected loss over underlying distribution  $p(\mathbf{x}, y)$ .

- Finite set  $Y$  (classification):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \sum_{y \in Y} \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x}$$

- Infinite  $Y$  (regression):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \int \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x} dy$$

- Expected zero-one loss (risk for zero-one loss function) is called **error rate**.
- 1-error rate is called **accuracy**.



# Risk

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- Infinite  $Y$  (regression):

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)}[\ell(\mathbf{x}, y)] = \int \int \ell(f_\theta(\mathbf{x}), y) p(\mathbf{x}, y) d\mathbf{x} dy$$

- It is generally impossible to determine the risk:
  - ◆  $p(\mathbf{x}, y)$  is not known.
  - ◆ Generally impossible to integrate over all instances  $\mathbf{x}$ .

# Empirical Risk

- Impossible to calculate risk

$$R(\theta) = E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)} [\ell(f_\theta(\mathbf{x}), y)]$$

- → Empirical risk: estimate on sample  $S \sim p(\mathbf{x}, y)^n$ .

$$\hat{R}_S(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(f_\theta(\mathbf{x}_i, y_i))$$

- Empirical risk is a random variable; depends on the instances  $S$  that are drawn.
- If  $S$  is drawn **IID**, then it is governed by  $p((\mathbf{x}_1, y_1) \times \cdots \times (\mathbf{x}_n, y_n)) = p(\mathbf{x}, y)^n$ .

# Estimators

- In statistics, an **estimator** is any rule for calculating an estimate of a quantity.
- A procedure for that determines the empirical risk is an estimator of the risk.

- An estimator is called unbiased if the expected value of the estimate is the true quantity:

$$\hat{R}(\theta) \text{ is unbiased} \Leftrightarrow E_{S \sim p(\mathbf{x}, y)^n} [\hat{R}_S(\theta)] = R(\theta)$$

- An estimator that is not unbiased has a bias:

$$B(\hat{R}(\theta)) = E_{S \sim p(\mathbf{x}, y)^n} [\hat{R}_S(\theta)] - R(\theta)$$

# Bias of the Empirical Risk

- Bias of the empirical risk:

$$B \left( \hat{R}(\theta) \right) = E_{S \sim p(\mathbf{x}, y)^n} \left[ \hat{R}_S(\theta) \right] - R(\theta)$$

- Empirical risk is unbiased estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[ \hat{R}_S(\theta) \right] = R(\theta)$$

- Empirical risk is optimistic estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[ \hat{R}_S(\theta) \right] - R(\theta) < 0$$

- Empirical risk is pessimistic estimator if:

$$E_{S \sim p(\mathbf{x}, y)^n} \left[ \hat{R}_S(\theta) \right] - R(\theta) > 0$$

# Bias of the Empirical Risk

- Bias of the empirical risk:

$$B \left( \hat{R}(\theta) \right) = E_{S \sim p(\mathbf{x}, y)^n} \left[ \hat{R}_S(\theta) \right] - R(\theta)$$

- The bias is a systematical offset between risk and empirical risk.
- It can be caused by a particular experimental setting used to determine the empirical risk.
- Large bias: risk is systematically estimated too low or too high.

# Variance of an Estimator

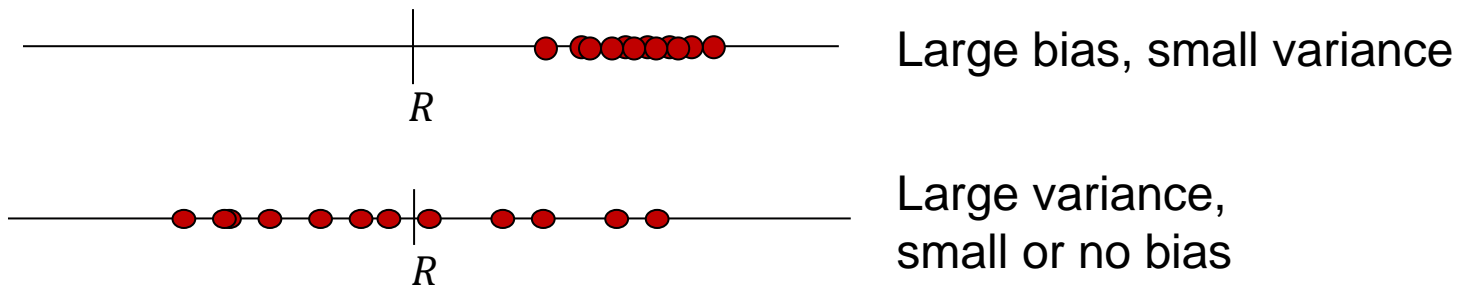
- Estimator  $\hat{R}_S(\theta)$  has a variance

$$\text{Var}[\hat{R}_S(\theta)] = E[\hat{R}_S(\theta)^2] - E[\hat{R}_S(\theta)]^2$$

- The variance is caused by the fact that the empirical risk is calculated on a finite sample.
- Zero-one loss: empirical risk  $\hat{R}_S(\theta)$  follows binomial distribution with mean value  $R(\theta)$ .
- High variance: empirical risk is a crude estimate of the risk.
- The larger a sample the empirical risk is based on, the lower its variance becomes.

# Bias and Variance of Empirical Risk

- Empirical risk  $\hat{R}_S(\theta)$  determined repeatedly on multiple samples  $S_1, \dots, S_k$ 
  - Value of  $\hat{R}_{S_i}$  for sample  $S_i$



# Estimation Error

- Estimation error: expected quadratic difference between empirical risk and risk.

$$E_{S \sim p(\mathbf{x}, y)^n} \left[ (\hat{R}_S(\theta) - R(\theta))^2 \right]$$

- Can be decomposed into bias and variance

$$\begin{aligned} & E_{S \sim p(\mathbf{x}, y)^n} \left[ (\hat{R}_S(\theta) - R(\theta))^2 \right] \\ &= E \left[ \hat{R}_S(\theta)^2 - 2R(\theta)\hat{R}_S(\theta) + R(\theta)^2 \right] \\ &= E \left[ \hat{R}_S(\theta)^2 \right] - 2R(\theta)E \left[ \hat{R}_S(\theta) \right] + R(\theta)^2 \\ &= E \left[ \hat{R}_S(\theta) \right]^2 - 2R(\theta)E \left[ \hat{R}_S(\theta) \right] + R(\theta)^2 + E \left[ \hat{R}_S(\theta)^2 \right] - E \left[ \hat{R}_S(\theta) \right]^2 \\ &= \left( E \left[ \hat{R}_S(\theta) \right] - R(\theta) \right)^2 + E \left[ \hat{R}_S(\theta)^2 \right] - E \left[ \hat{R}_S(\theta) \right]^2 \\ &= \text{Bias} \left[ \hat{R}(f) \right]^2 + \text{Var} \left[ \hat{R}(f) \right] \end{aligned}$$

Algebraic formula  
for the variance



# Alternative Measures to Risk

- Risk is not always a meaningful measure.
- Not always possible to specify a meaningful loss function
  - ◆ Mine detector: what is the cost of exploding?
  - ◆ On the other hand, a mine detector that always says “there could be a mine here” is useless.
- Error rate / accuracy are not meaningful for rare classes.
  - ◆ Earth quake prediction tool that always says “there will be no earthquake today” has accuracy of >99.9% (in most countries).

# Alternative Measures to Risk

- Alternative performance measures for binary classification.
- Let decision function  $f_\theta(\mathbf{x})$  return continuous value.
- Decision rule for binary classification:

$$y_\theta(\mathbf{x}) = \begin{cases} +1 & \text{if } f_\theta(\mathbf{x}) \geq \theta_0 \\ -1 & \text{if } f_\theta(\mathbf{x}) < \theta_0 \end{cases}$$

- By adjusting threshold  $\theta_0$  decision rule can be made more sensitive or more conservative.
- We will now study measures that quantify how well the decision function separates positive from negative instances, independent of any threshold value  $\theta_0$ .
  - ◆ Precision-recall curves
  - ◆ ROC curves

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# Precision and Recall

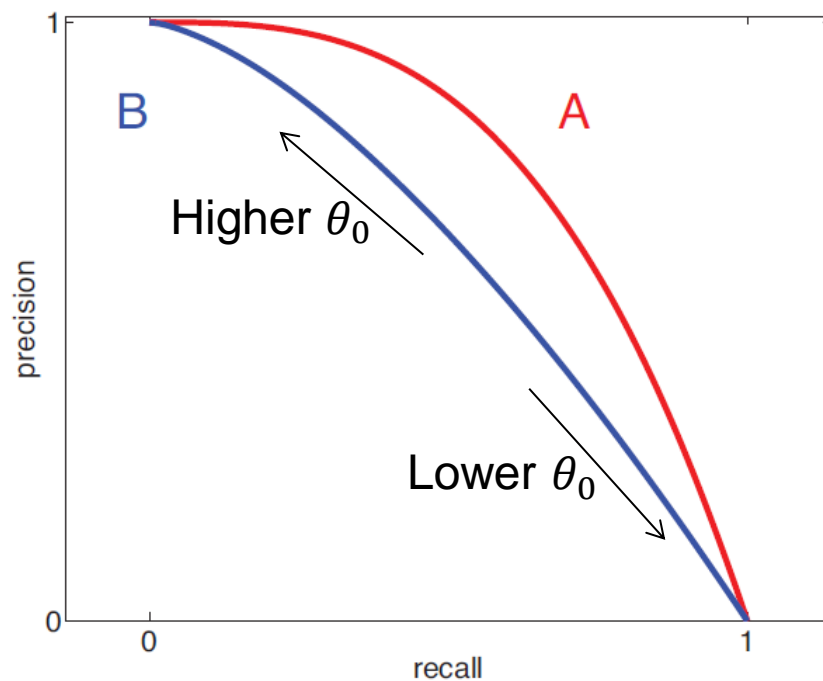
- Alternative performance measure for binary classification.
  - ◆ Example: diagnosis of rare disease.
  - ◆ Patient  $\mathbf{x}_i$  has disease if  $y_i = +1$ .
  - ◆ Classifier diagnoses disease for patient  $\mathbf{x}$  if  $y_\theta(\mathbf{x}_i) = +1$ .
- True positives:
  - ◆ Patient has disease ( $y_i = +1$ ), classifier recognizes ( $y_\theta(\mathbf{x}_i) = +1$ )
- False positives:
  - ◆ Patient is healthy ( $y_i = -1$ ), but classifier diagnoses disease ( $y_\theta(\mathbf{x}_i) = +1$ )
- True negatives:
  - ◆ Patient is healthy ( $y_i = -1$ ), classifier recognizes ( $y_\theta(\mathbf{x}_i) = -1$ )
- False negatives:
  - ◆ Patient has disease ( $y_i = +1$ ), classifier misses ( $y_\theta(\mathbf{x}_i) = -1$ )

# Precision and Recall

- Let  $n_{TP}$  be the number of true positives.
- Let  $n_{FP}$  be the number of false positives.
- Let  $n_{TN}$  be the number of true negatives.
- Let  $n_{FN}$  be the number of false negatives.
- Precision:  $P = \frac{n_{TP}}{n_{TP} + n_{FP}}$ 
  - ◆ “Rate of true positives among all instances that are classified as positives”
  - ◆ Answers: “How accurate is classifier when it says +1?”
- Recall:  $R = \frac{n_{TP}}{n_{TP} + n_{FN}}$ 
  - ◆ “Rate of true positives among all positive instances”
  - ◆ Answers: “How many of the positive instances does the classifier detect?”

# Precision-Recall Curves

- Evaluates decision function  $f_{\theta}(\mathbf{x})$  independent of threshold  $\theta_0$ .
- Shows which pairs of precision and recall can be obtained by varying threshold  $\theta_0$ .
- Each point on the curve is a classification rule with a particular values of  $\theta_0$ .
- Which decision function is better – A or B?



# F Measures

- $F_\alpha$  measures combine precision and recall values into single value:

$$F_\alpha = \frac{n_{TP}}{\alpha(n_{TP} + n_{FP}) + (1 - \alpha)(n_{TP} + n_{FN})}$$

- $\alpha = 1$ : Precision
- $\alpha = 0$ : Recall
- $\alpha = 0.5$ : “F-measure”, harmonic mean of precision and recall.
- Alternative definition:  $F_\beta$  measures.
  - ◆ Relationship:  $\alpha = \frac{1}{1+\beta}$

# Side Note on F Measures

- $F_\alpha$  measures (incl. precision and recall) are defined as empirical quantities.

- What do F-measures estimate?

- Generalized risk:

$$G = \frac{\sum_y \int \ell(f_\theta(\mathbf{x}), y) w(\mathbf{x}, y, f_\theta) p(\mathbf{x}, y) d\mathbf{x}}{\sum_y \int w(\mathbf{x}, y, f_\theta) p(\mathbf{x}, y) d\mathbf{x}}$$

- $F_\alpha$  measures are estimates of special cases.

- Special cases:

- ◆ Risk:  $w(\mathbf{x}, y, f_\theta) = 1$ .
- ◆ Precision:  $w(\mathbf{x}, y, f_\theta) = 1$  if  $f_\theta(\mathbf{x}) = 1$ , 0 otherwise
- ◆ ...

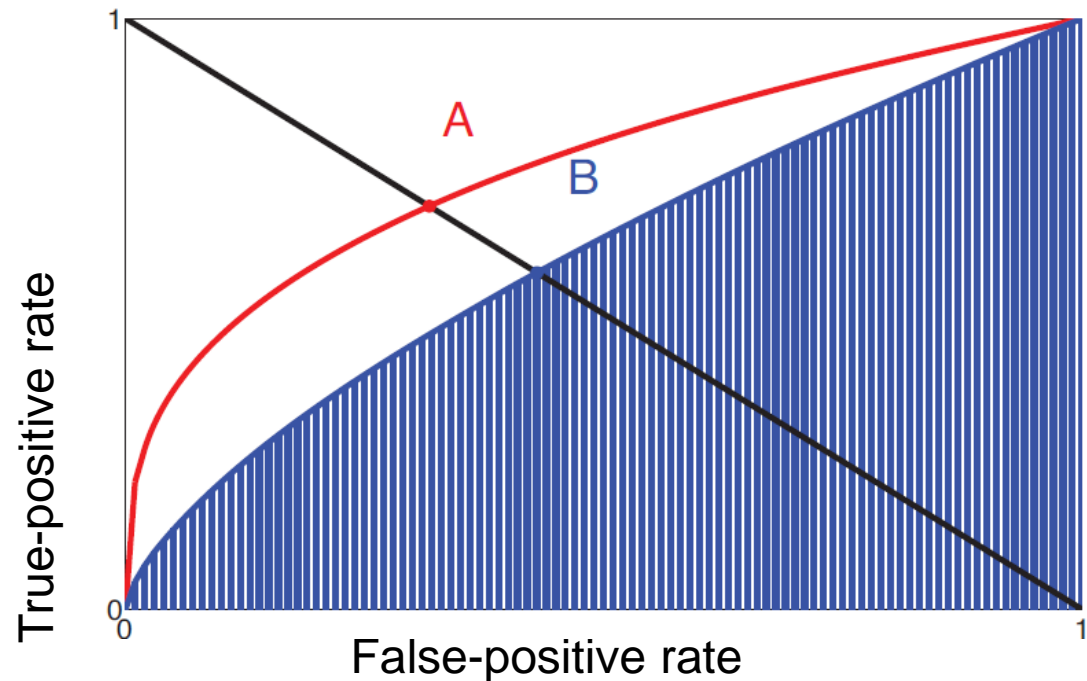


# Overview

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# ROC Analysis

- Alternative measure of how well the decision function separates positive from negative instances, independent of any threshold value  $\theta_0$ .

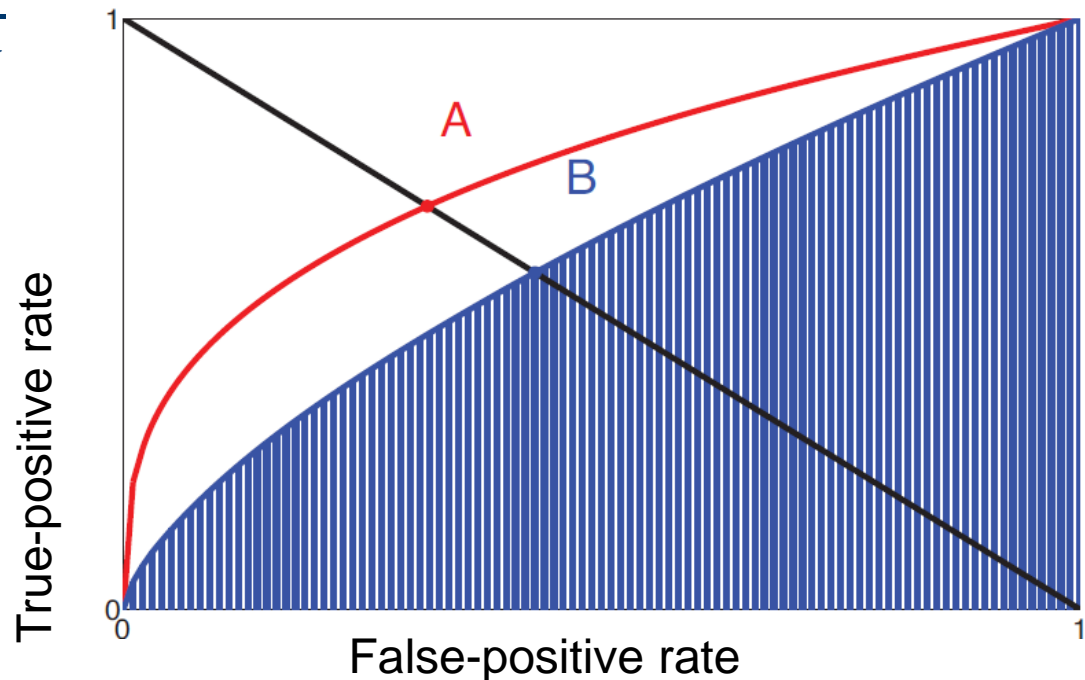


# ROC Analysis

- Each curve characterizes a decision function  $f_{\theta}$ .
- Each point is a classification rule for a value of  $\theta_0$ .
- Which is better, A or B?

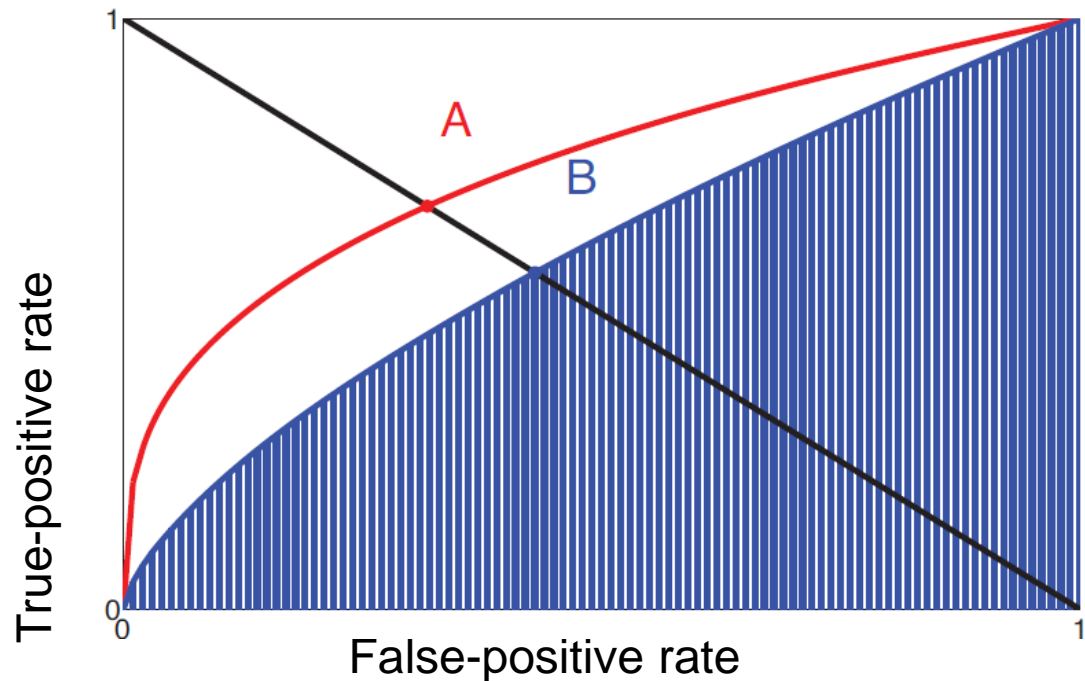
- $$r_{TP} = \frac{n_{TP}}{n_{TP} + n_{FN}}$$

- $$r_{FP} = \frac{n_{FP}}{n_{FP} + n_{TP}}$$



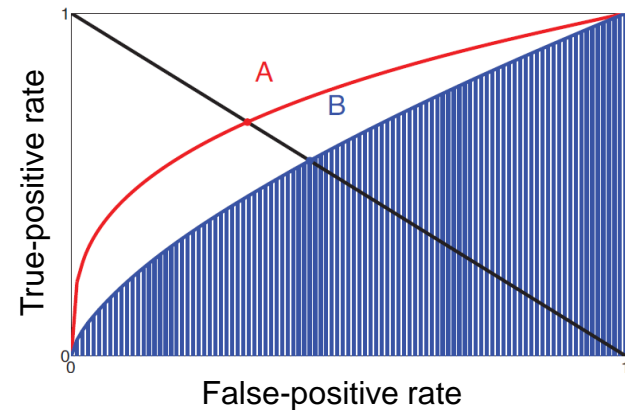
# ROC Analysis

- Equal error rate (EER): value  $r_{TP} = 1 - r_{FP}$ .
- Scalar aggregate of curve: Area under ROC curve (AUC).



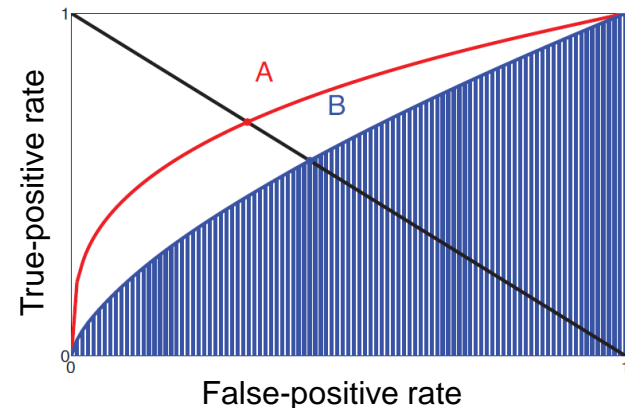
# ROC Analysis

- Area under the ROC curve (AUC):
  - ◆ Let  $\mathbf{x}_+$  be a randomly drawn positive instance.
  - ◆ Let  $\mathbf{x}_-$  be a randomly drawn negative instance.
  - ◆  $AUC(\theta) = P(f_\theta(\mathbf{x}_+) > f_\theta(\mathbf{x}_-))$ .



# ROC Analysis

- ROC analysis is often used
  - ◆ When positive instances are rare (accuracy of 99.9% is meaningless if positive class is extremely rare)
  - ◆ When no meaningful probability of meeting positive instances can be defined (probability of stepping on a mine varies by country).



# Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
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# Evaluation Protocols

- Usually, model  $f_\theta$  is not given and evaluation data cannot be drawn from  $p(\mathbf{x}, y)$ .
- Typical case, data  $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$  and learning method are given.
- Data  $S$  have to be used for training and evaluation.
- Desired output: model  $f_\theta$  and risk estimate.

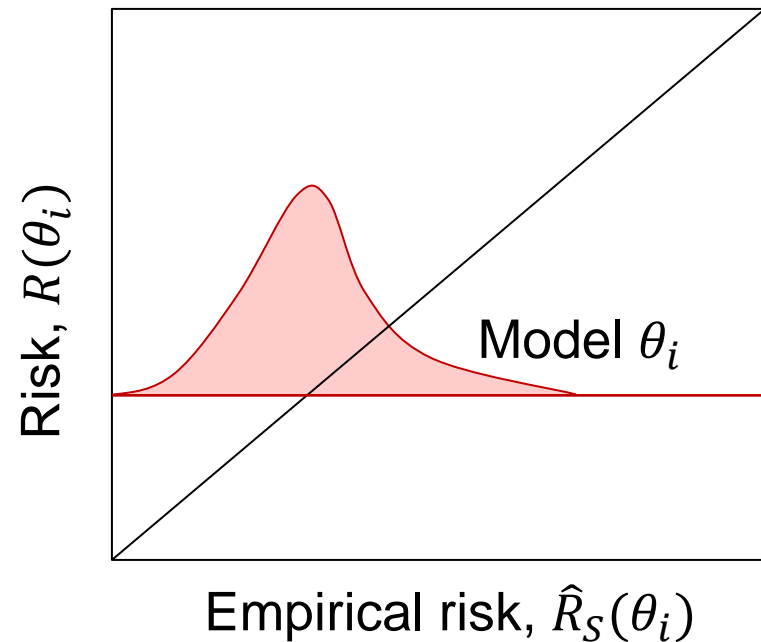


# Evaluation Protocols

- Can we first train model  $f_\theta$  on  $S$  and then evaluate the model on the same data?
- Will  $\hat{R}_S(\theta)$  be unbiased, optimistic, or pessimistic?

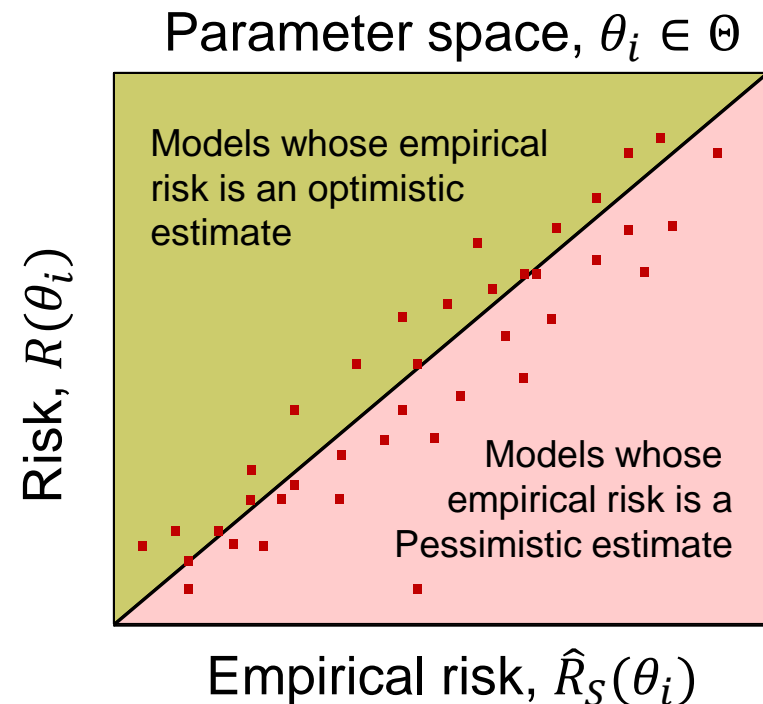
# Evaluation Protocols

- Every model  $\theta_i \in \Theta$  has a risk  $R(\theta_i)$ .
- Its empirical risk  $\hat{R}_S(\theta_i)$  follows a distribution with mean value  $R(\theta_i)$ .



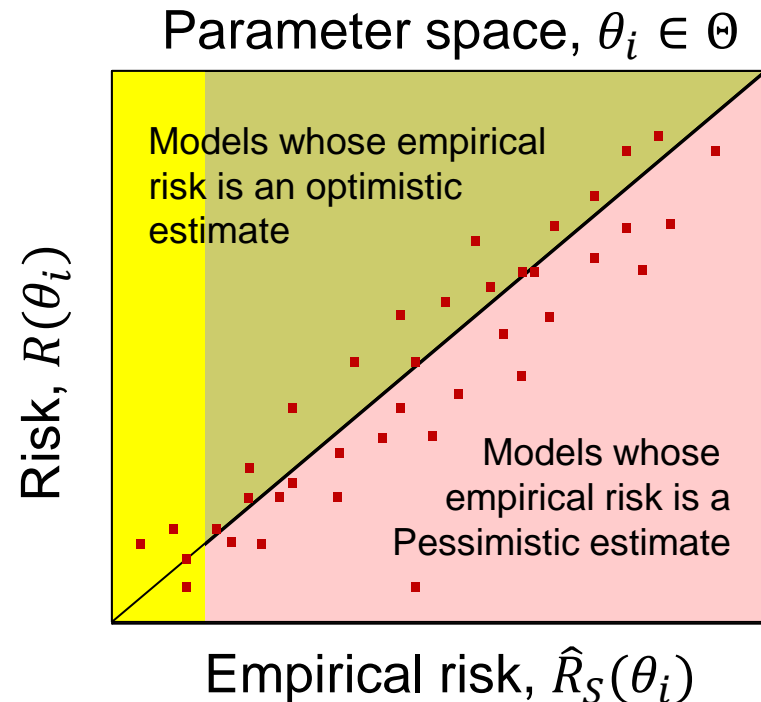
# Evaluation Protocols

- Some models get lucky (upper-left area), some are unlucky (lower-right area).



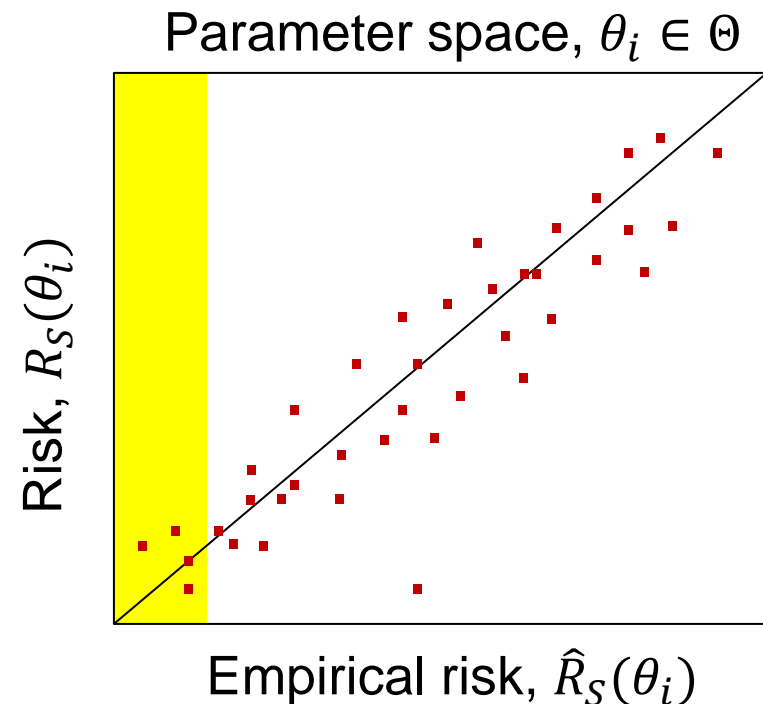
# Evaluation Protocols

- Learning algorithm will choose a model with small empirical risk (on the far left).
- In this area, most models' empirical risk is an optimistic estimate.



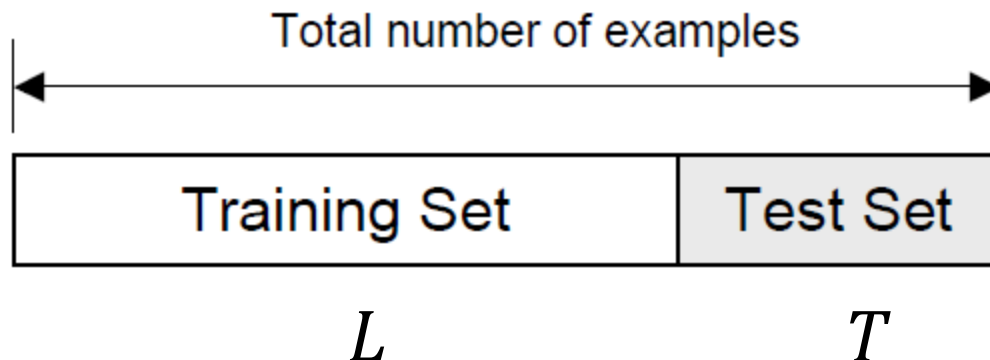
# Evaluation Protocols

- Learning algorithm will choose a model with small empirical risk (on the far left).
- For those  $\theta_*$  on the left:  $E_S[\hat{R}_S(\theta_*)] < R(\theta_*)$  (otherwise they would be further right).
- This is called **selection bias**.
- **Empirical risk on training data is optimistic.**



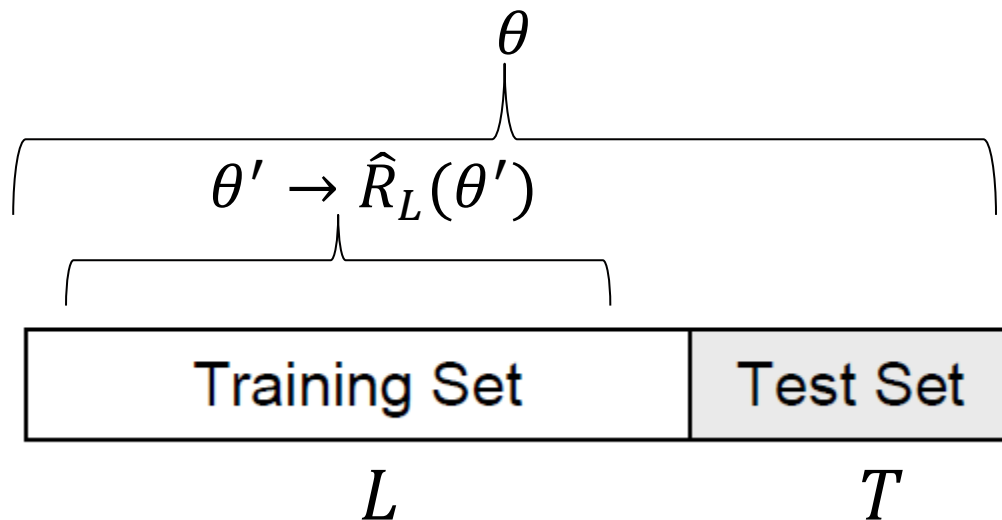
# Holdout Testing

- Idea: error estimation on independent test data
- Given: data  $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
- Divide the data into
  - ◆ Training data  $L = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$  and
  - ◆ Test data  $T = (\mathbf{x}_{m+1}, y_{m+1}), \dots, (\mathbf{x}_n, y_n)$



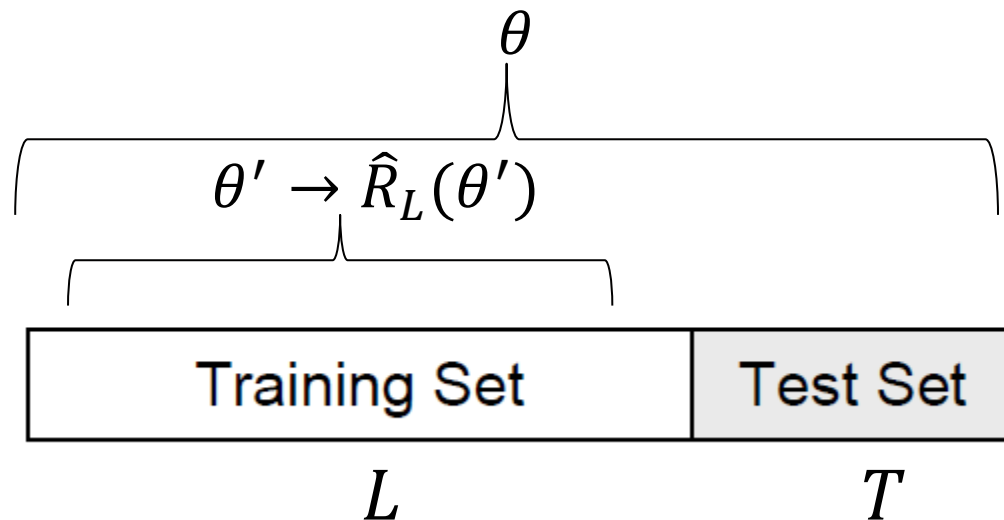
# Holdout Testing

- Start learning algorithm with data  $L$  and obtain model  $f_{\theta'}$  from it.
- Determine empirical risk  $\hat{R}_T(\theta')$  from data  $T$ .
- Start learning algorithm with all data  $S$  and obtain Model  $f_{\theta}$  from it.
- Output: model  $f_{\theta}$  &  $\hat{R}_T(\theta')$  as the estimator of  $R(\theta)$ .



# Holdout Testing: Analysis

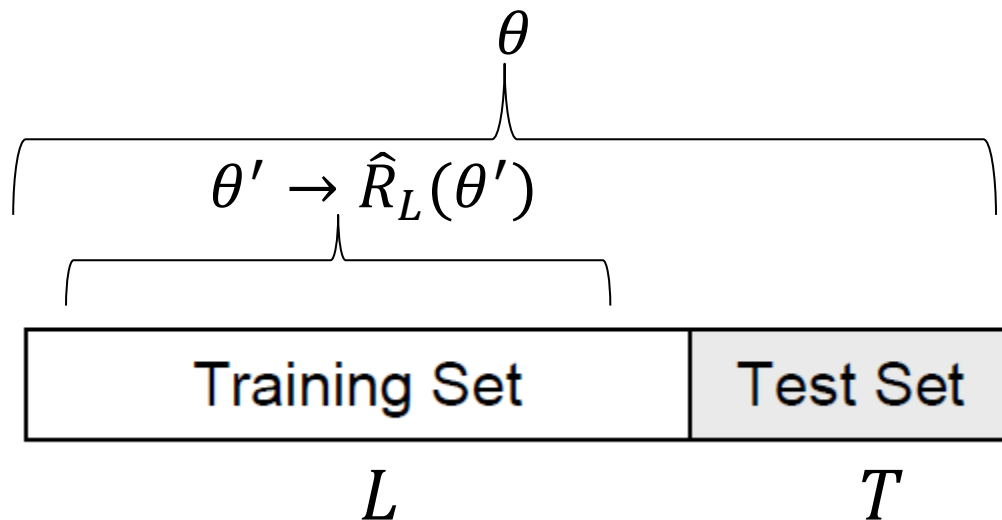
- Is the estimator  $\hat{R}_T(\theta')$  of the risk of model  $R(\theta)$ 
  - ◆ unbiased,
  - ◆ optimistic,
  - ◆ pessimistic?
- Hint: the more training data, the better the model.





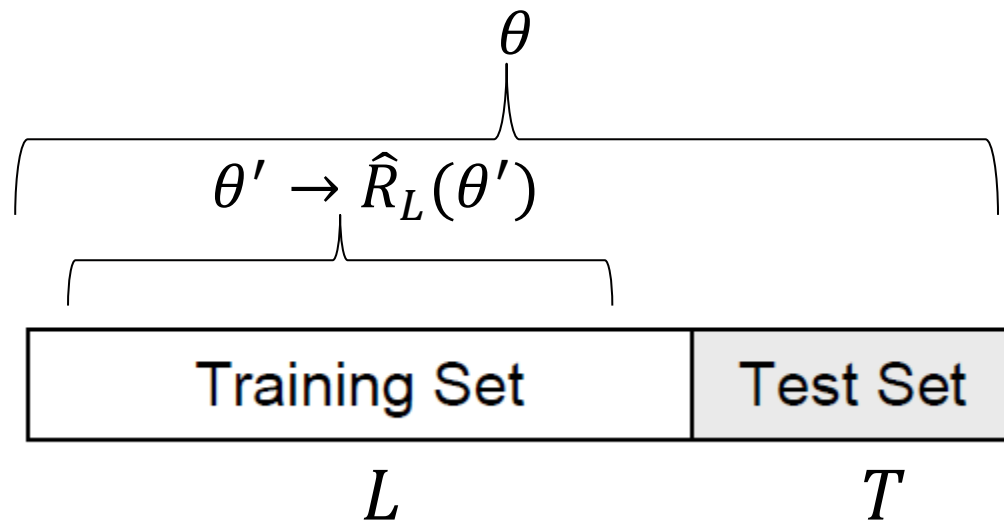
# Holdout Testing: Analysis

- Estimate  $\hat{R}_T(\theta')$  is obtained on a small part of the available data.
- Therefore, its variance is relatively high, especially if the overall sample is small.
- Holdout testing is used in practice for large available samples.



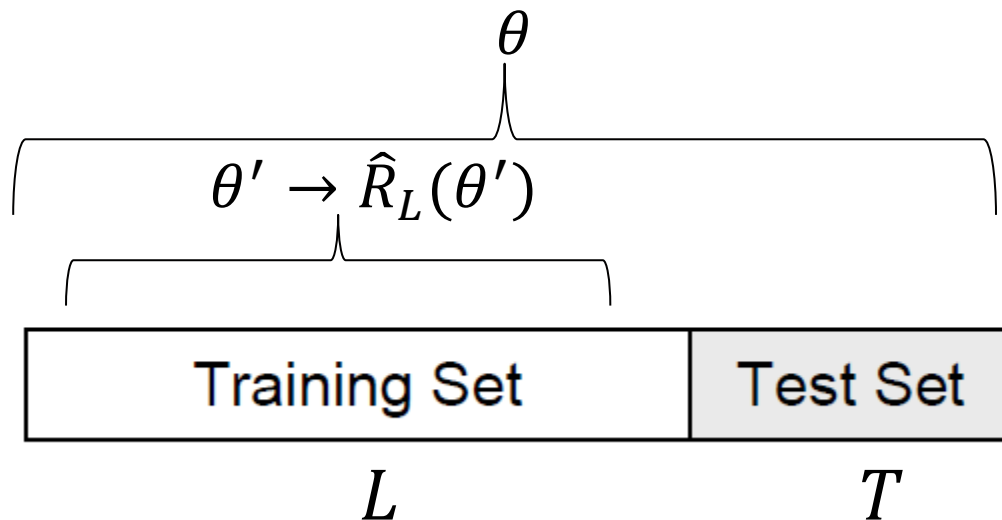
# Holdout Testing: Analysis

- Using empirical risk  $\hat{R}_T(\theta')$  is an **optimistic** estimator of the risk  $R(\theta)$ .
- Because  $\theta'$  is trained with fewer training instances than  $\theta$ .



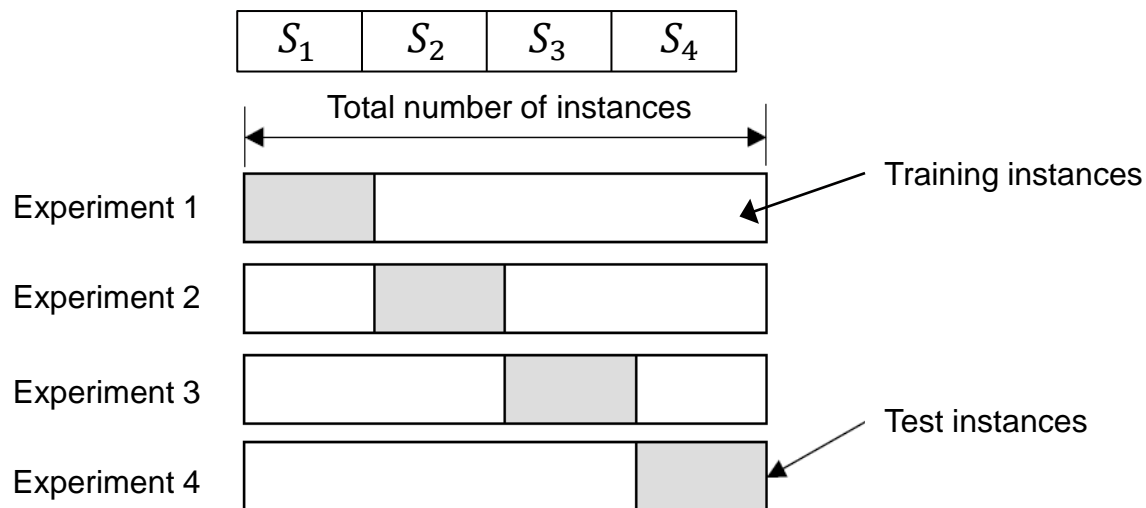
# Holdout Testing: Analysis

- One could instead return model  $\theta'$ .
- Empirical risk  $\hat{R}_T(\theta')$  would be an unbiased estimate of  $R(\theta')$ .
- But since  $\theta'$  was trained on fewer data, it would result in an inferior model.



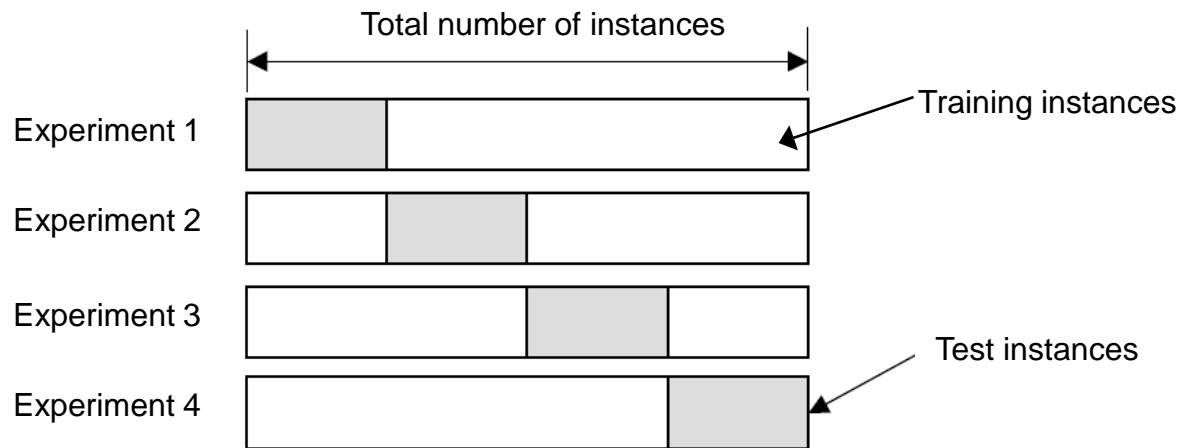
# K-Fold Cross Validation

- Given: data  $S = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
- Partition  $S$  into  $k$  equally sized portions  $S_1, \dots, S_k$ .
- Repeat for  $i = 1 \dots k$ 
  - ◆ Train  $f_{\theta_i}$  with training set  $S = S \setminus S_i$ .
  - ◆ Calculate empirical risk  $\hat{R}_{S_i}(\theta_i)$  on  $S_i$ .
- Calculate average  $\hat{R}_S = \frac{1}{k} \sum_i \hat{R}_{S_i}(\theta_i)$



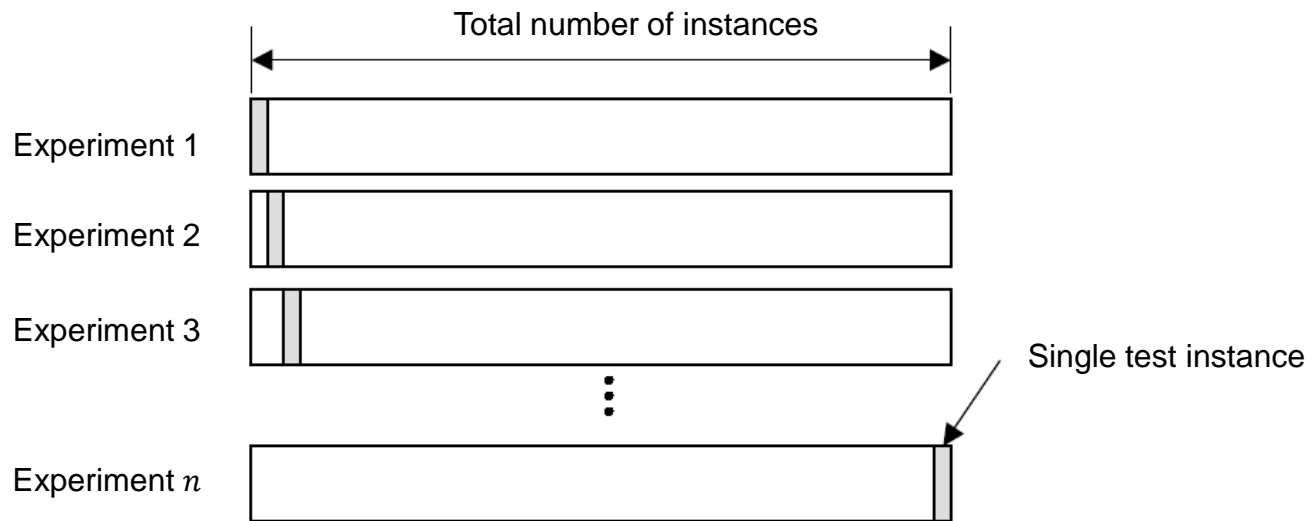
# Cross Validation

- Then, train  $f_\theta$  on all data  $S$ .
- Return model  $f_\theta$  and estimator  $\hat{R}_S$ .



# Leave-One-Out Cross Validation

- Special case  $k = n$  is also called *leave-one-out* error estimation

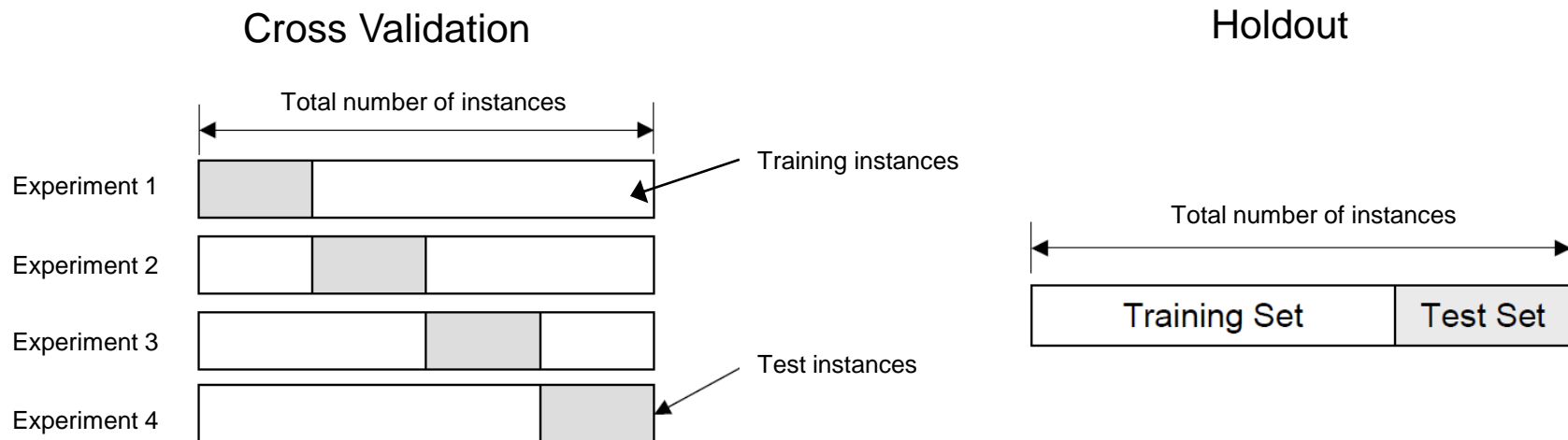


# Cross Validation: Analysis

- Is the estimator
  - ◆ optimistic / pessimistic / unbiased?

# Cross Validation: Analysis

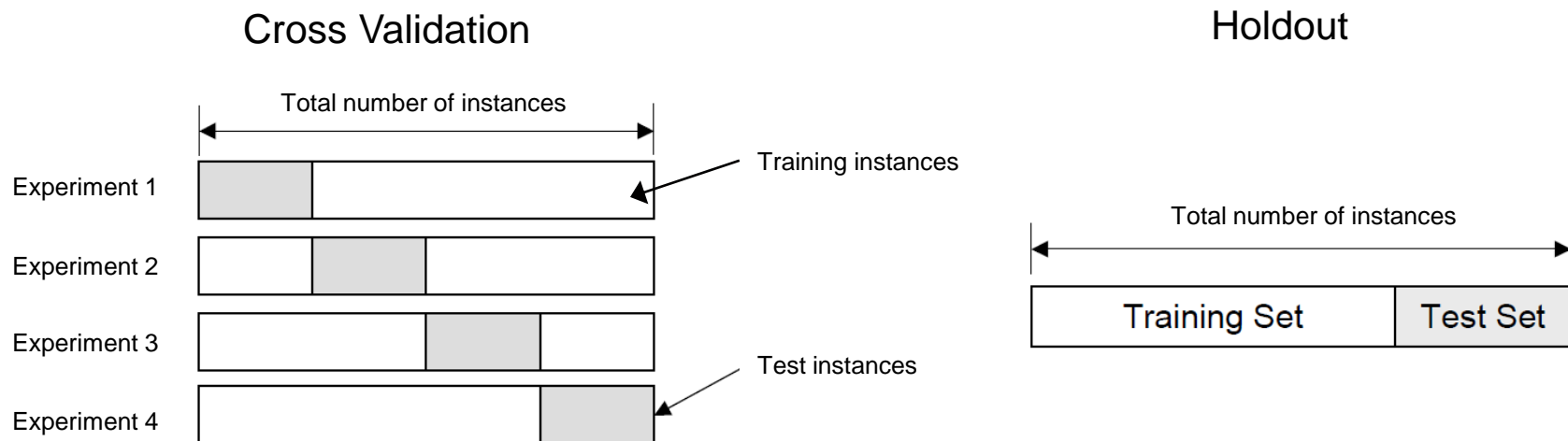
- Is the estimator
  - ◆ optimistic / pessimistic / unbiased?
- Estimator is slightly pessimistic:
  - ◆ Model  $f_{\theta_i}$  is trained on a  $(k - 1)/k$ -th fraction of the available data.
  - ◆ Model  $f_{\theta}$  is trained on the entire data.





# Cross Validation: Analysis

- Bias/Variance compared to holdout testing?
- Variance is lower than with holdout testing
  - ◆ Averaging over several holdout experiments reduces the estimator's variance.
  - ◆ All data is incorporated into the estimator.
- Bias similar to holdout testing, depending on the split ratios.



# Overview

- Risk, empirical risk
- Precision, recall
- ROC curves
- Evaluation protocols
- **Model selection**

# Model Selection

- Compare several different learning approaches
  - ◆ Should one use decision trees?
  - ◆ SVMs? Logistic Regression?
- Set regularization parameter for a learning approach
  - ◆ For instance, set value for  $\lambda$  for regularized empirical risk minimization.

# Model Selection: Example

- Regularization parameter  $\lambda$  in optimization criterion

$$\theta^* = \operatorname{argmin}_{\theta} \sum_i \ell(f_{\theta}(\mathbf{x}_i), y_i) + \lambda \|\theta\|^2 \quad \lambda = ?$$

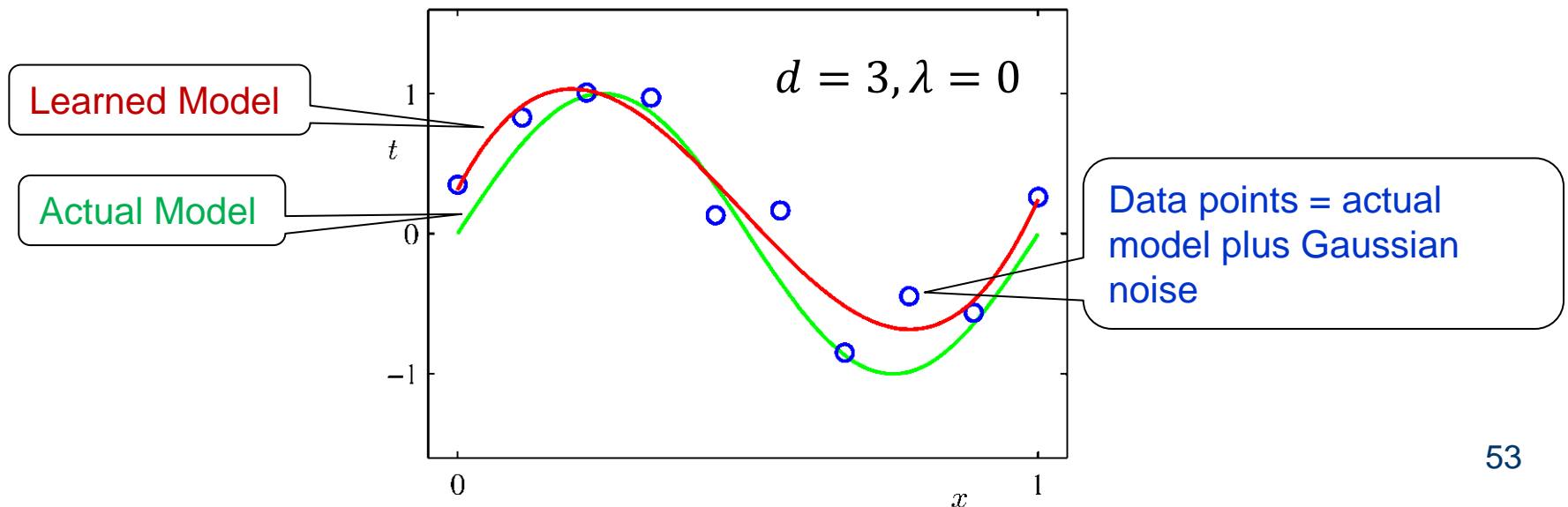
- (Hyper)parameters that specify the model class; e.g. the degree for polynomial regression

$$f_{\theta}(x) = \sum_{j=0}^d w_j x^j \quad d = ?$$

- Desired output: hyperparameter  $(\lambda, d)$ , model  $f_{\theta}$ , and estimate of the model's risk.
- How do we use available data to achieve this?

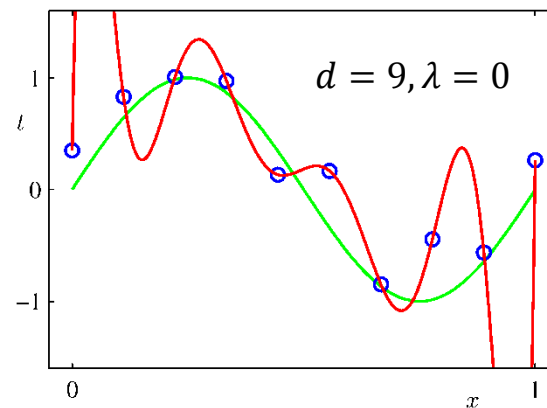
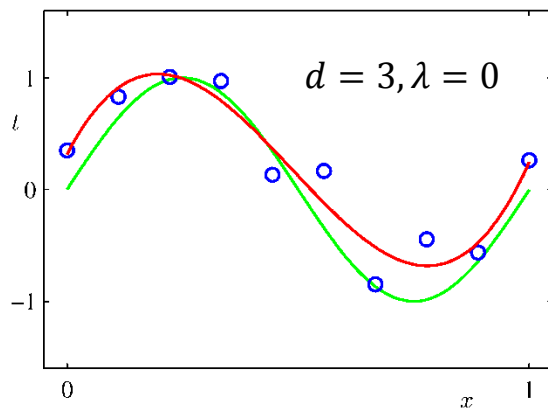
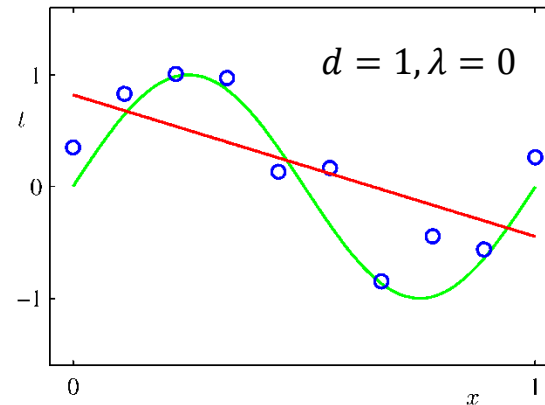
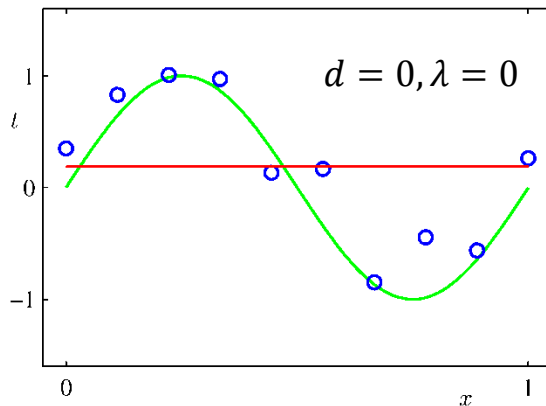
# Example: Polynomial Regression

- Polynomial model of degree  $d$ :  $f_{\theta}^d(x) = \sum_{j=0}^d w_j x^j$
- Regularized empirical risk minimization:  
$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^n (f_{\theta}^d(x_i) - y_i)^2 + \lambda \|\theta\|^2$$



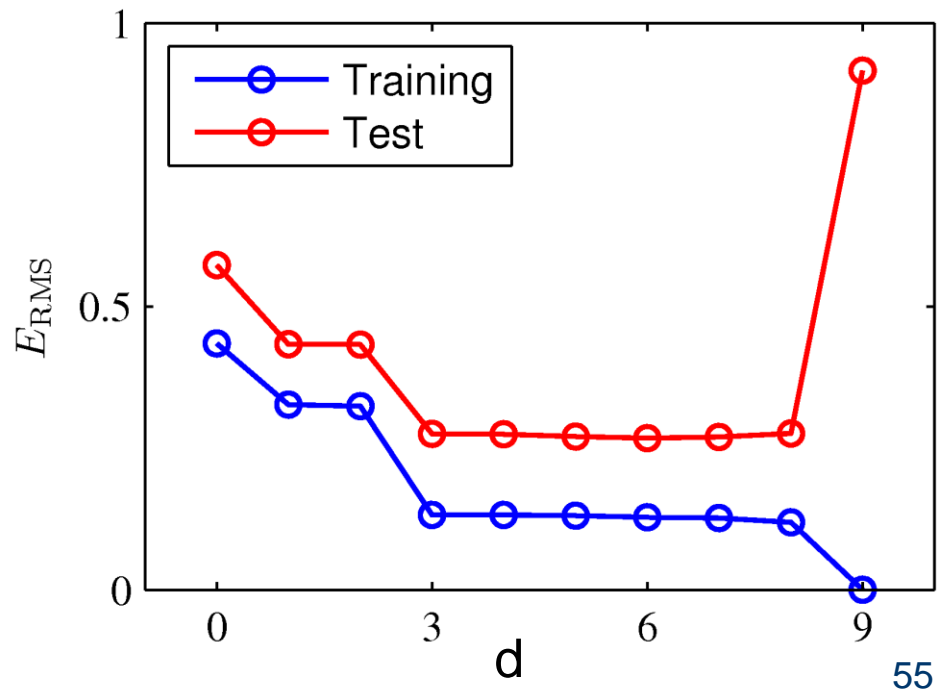
# Polynomial Regression

- Success of the learning depends on the selected polynomial degree  $d$ , which controls the complexity of the model.



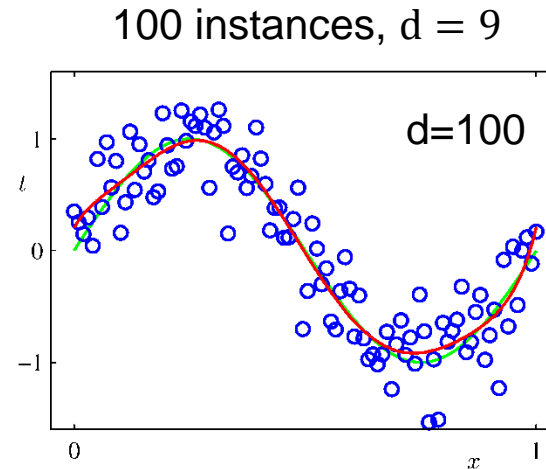
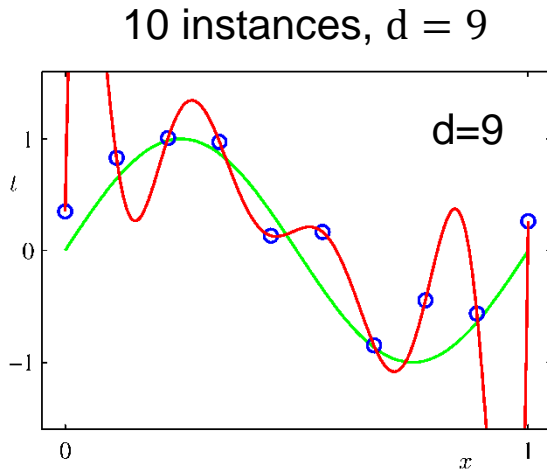
# Polynomial Regression: Empirical Risk on Training vs. Test Sample

- Empirical risk on training vs. test data for different polynomial degrees.
- “Overfitting”: empirical risk on training data decreases as  $d$  is increased. Empirical risk on test data has a minimum, then increases again.



# Example: Polynomial Regression

- If more data are available, more complex models can be fitted.

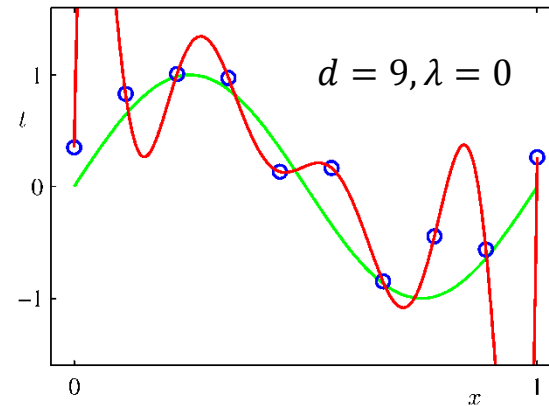
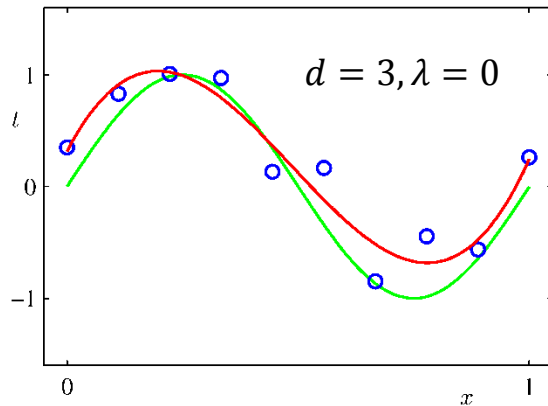


- Given fixed amount of data, optimal  $d$  has to be found.

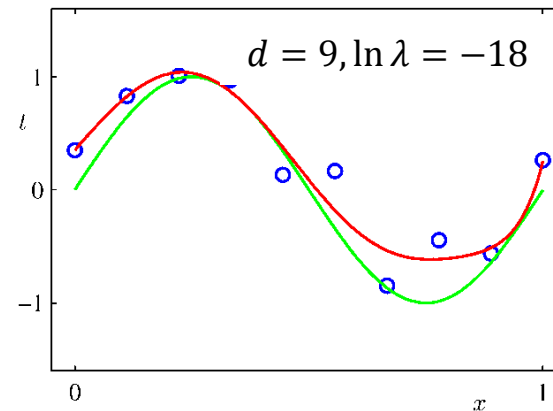


# Example: Polynomial Regression

- Regularization factor  $\lambda$  has a similar effect to  $d$ .

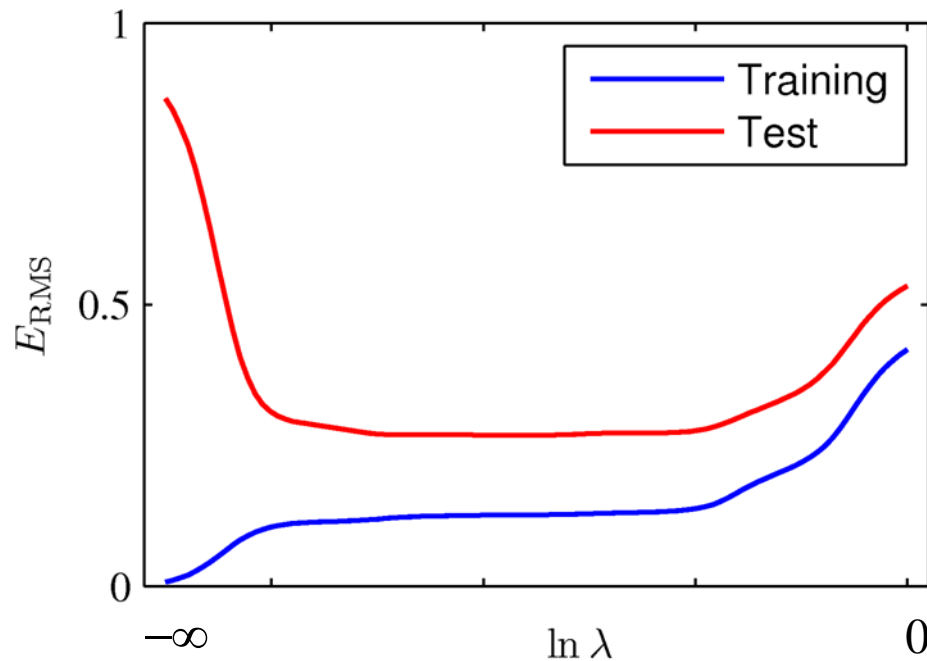


- Both  $\lambda$  and  $d$  constrain the model complexity.



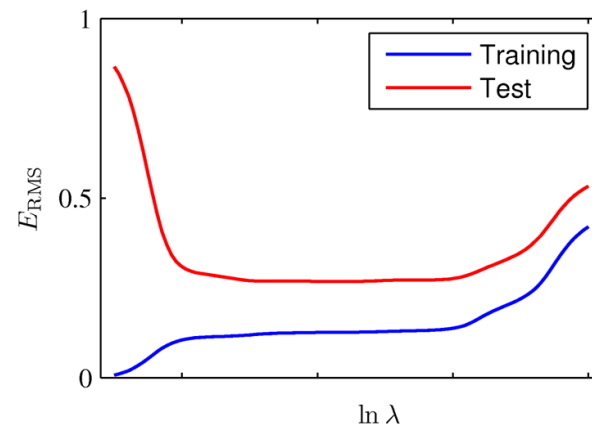
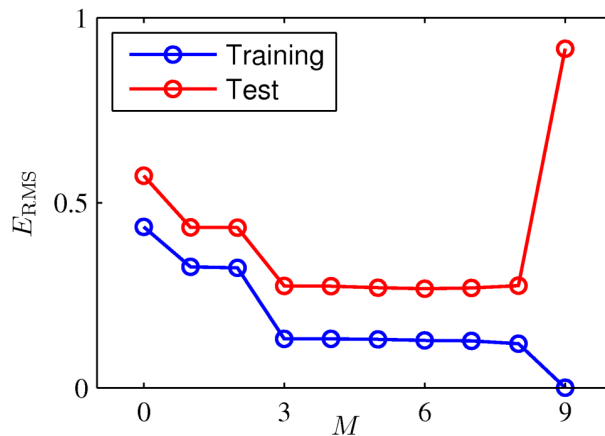
# Regularized Polynomial Regression

- Empirical risk on training vs. test sample.
- Empirical risk on training sample decreases when regularization decreases.
- There is a regularization factor that minimizes the risk.



# Regularized Polynomial Regression

- Regularizer acts like a limitation on the model complexity and prevents overfitting.
- In practice it is best to control model complexity through regularization (direct parameters like the polynomial degree often are not available).
- Regularizer has to be tuned on available data.

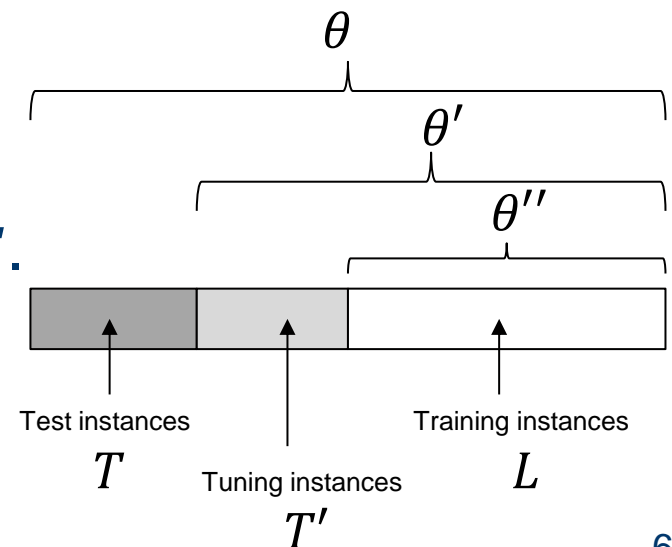


# Model Selection, Setting Hyperparameters

- Desired output: hyperparameter  $(\lambda, d)$ , model  $f_\theta$ , and estimate of the model's risk.
- Idea: Iterate over values of  $(\lambda, d)$ , train model, evaluate; take best values and train final model.
- Cannot tune hyperparameters on training data because low regularization leads to low empirical risk on training data but high risk on test data.
- Evaluating multiple models (for different values of  $\lambda, d$ ) on the same test set results in an optimistic bias.
- Therefore, triple or nested cross validation.

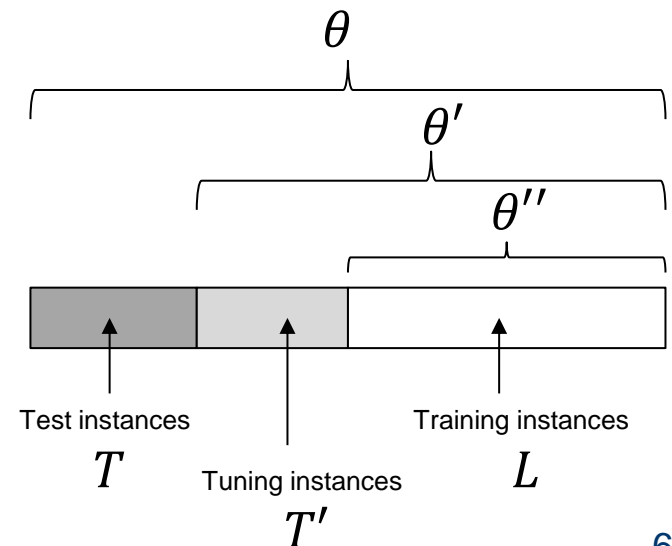
# Triple Cross Validation

- Iterate over all values of the hyperparameters  $\lambda$  (grid search)
  - ◆ Train model  $f_{\theta''}^{\lambda}$  on  $L$ .
  - ◆ Evaluate  $f_{\theta''}^{\lambda}$  on  $T'$  by calculating  $\hat{R}_{T'}(f_{\theta''}^{\lambda})$
- Use hyperparameter  $\lambda^*$  that gave lowest  $\hat{R}_{T'}(f_{\theta''}^{\lambda^*})$ .
- Train model  $f_{\theta'}^{\lambda^*}$  on  $L \cup T'$ .
- Determine  $\hat{R}_T(\theta')$ .
- Train model  $f_{\theta}^{\lambda^*}$  on  $L \cup T' \cup T$ .
- Return model  $f_{\theta}^{\lambda^*}$  and estimate  $\hat{R}_T(f_{\theta}^{\lambda^*})$ .



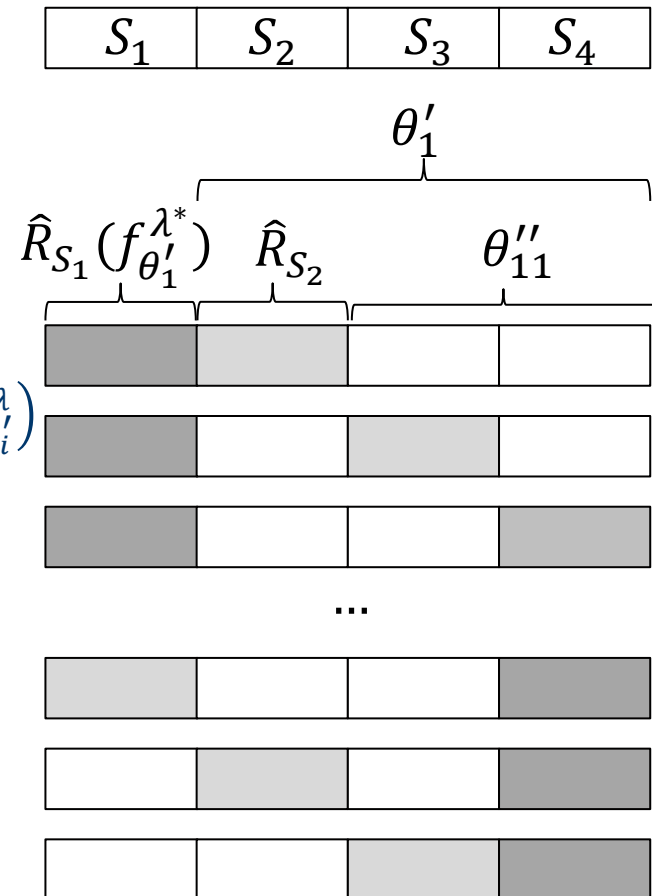
# Triple Cross Validation: Analysis

- Empirical risk  $\hat{R}_T(\theta')$  is a pessimistic estimator for  $R(\theta)$  because  $\theta'$  is trained on less data than  $\theta$ .
- $\lambda^*$  may be a poor estimate of the optimal parameters because  $T'$  may be small.
- The variance of  $\hat{R}_T(\theta')$  may high because  $T$  may be small.
- Protocol is used when the total sample  $S$  is very large.



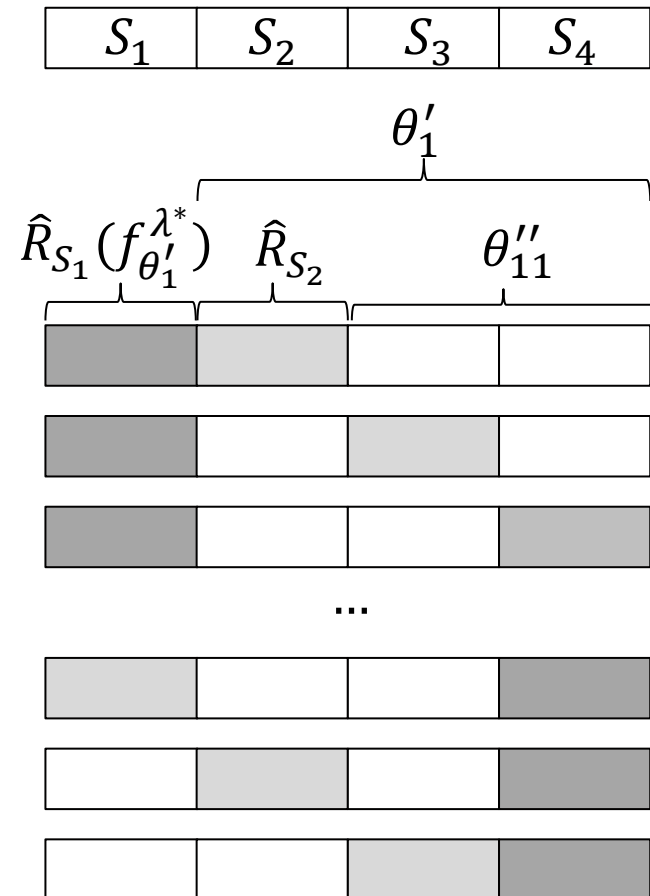
# Nested Cross Validation

- For  $i = 1 \dots k$ 
  - ◆ Iterate over values  $\lambda$ 
    - ★ For  $j = 1 \dots k \setminus i$ 
      - Train  $f_{\theta_{ij}}^\lambda$  on  $S \setminus S_i \setminus S_j$
      - Determine  $\hat{R}_{S_j}(f_{\theta_{ij}}^\lambda)$
    - ★ Average  $\hat{R}_{S_j}$  to determine  $\hat{R}_{S \setminus S_i}(f_{\theta_i'}^\lambda)$
  - ◆ Choose  $\lambda_i^*$  that minimizes  $\hat{R}_{S \setminus S_i}(f_{\theta_i'}^\lambda)$
  - ◆ Train  $f_{\theta_i}^{\lambda_i^*}$  on  $S \setminus S_i$
  - ◆ Determine  $\hat{R}_{S_i}(f_{\theta_i}^{\lambda_i^*})$
- Average  $\hat{R}_{S_i}(f_{\theta_i}^{\lambda_i^*})$  to determine  $\hat{R}_S(f_{\theta^*}^{\lambda^*})$
- Determine  $\lambda^*$  by averaging  $\lambda_i^*$
- Train  $f_{\theta}^{\lambda^*}$  on  $S$
- Return  $f_{\theta}^{\lambda^*}$  and  $\hat{R}_S(f_{\theta^*}^{\lambda^*})$



# Nested Cross Validation: Analysis

- Complexity:  $k^2$  models have to be trained and evaluated
- Slightly pessimistic because  $f_{\theta}^{\lambda^*}$  has been trained on more data than the  $f_{\theta_i}^{\lambda_i^*}$ .
- Lower variance than triple cross validation because all data is used for evaluation
- Better estimate of  $\lambda^*$  because almost all data is used for tuning.
- Best tuning protocol when few data are available.





# Summary

- Risk: expected loss over input distribution  $p(\mathbf{x}, y)$ .
- Empirical risk: estimate of risk on data.
- Precision-recall curves and ROC curves characterize decision function. Each point on curve is classifier for some threshold  $\theta_0$ .
- Evaluation protocols:
  - ◆ Hold-out testing: good for large samples
  - ◆ K-fold Cross Validation: good for small samples.
- Model selection: tune model hyperparameters.
  - ◆ Triple cross validation: good for large samples.
  - ◆ Nested cross validation: good for small samples.