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### Recommendation

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#### **Recommendation Engines**

- Recommendation of products, music, contacts, ..
- Based on user features, item features, and past transactions: sales, reviews, clicks, ...
- User-specific recommendations, no global ranking of items.
- Feedback loop: choice of recommendations influences available transaction and click data.

#### **Netflix Prize**

- Data analysis challenge, 2006-2009
- Netflix made rating data available: 500,000 users, 18,000 movies, 100 million ratings
- Challenge: predict ratings that were held back for evaluation; improve by 10% over Netflix's recommendation
- Award: \$ 1 million.

# Intelligent Data Analysis

#### **Problem Setting**

- Users  $U = \{1, ..., m\}$
- Items  $X = \{1, ..., m'\}$
- Ratings  $Y = \{(u_1, x_1, y_1) \dots, (u_n, x_n, y_n)\}$
- Rating space  $y_i \in Y$

• E.g.,  $Y = \{-1, +1\}, Y = \{\star, \dots, \star \star \star \star \}$ 

- Loss function  $\ell(y_i, y_j)$ 
  - E.g., missing a good movie is bad but watching a terrible movie is worse.
- Find rating model:  $f_{\theta}$ :  $(u, x) \mapsto y$ .

#### **Problem Setting: Matrix Notation**

• Users 
$$U = \{1, ..., m\}$$

• Items 
$$X = \{1, ..., m'\}$$

Incomplete matrix



• Loss function  $\ell(y_i, y_j)$ 

#### **Problem Setting**

- Model  $f_{\theta}(u, x)$
- Find model parameters that minimize risk  $\theta^* = \operatorname{argmin}_{\theta} \int \int \ell(y, f_{\theta}(u, x)) p(u, x, y) dx du dr$
- As usual: p(u, x, y) is unknown → minimize regularized empirical risk

 $\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^n \ell(y_i, f_{\theta}(u_i, x_i)) + \lambda \Omega(\theta)$ 

#### **Content-Based Recommendation**

- Idea: User may like movies that are similar to other movies which they like.
- Requirement: attributes of items, e.g.,
  - Tags,
  - Genre,
  - Actors,
  - Director,
  - **•** ...

#### **Content-Based Recommendation**

- Feature space for items
- E.g.,  $\Phi = (\text{comedy, action, year, dir tarantino, dir cameron})^T$
- $\phi(avatar) = (0, 1, 2009, 0, 1)^{\mathsf{T}}$

#### **Content-Based Recommendation**

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- Rating space  $y_i \in Y$ 
  - E.g.,  $\Upsilon = \{-1, +1\}, \Upsilon = \{\star, \dots, \star \star \star \star \star\}$
- Loss function  $\ell(y_i, y_j)$ 
  - E.g., missing a good movie is bad but watching a terrible movie is worse.
- Feature function for items:  $\phi: x \mapsto \mathbb{R}^d$
- Find rating model:  $f_{\theta}$ :  $(u, x) \mapsto y$ .

#### **Independent Learning Problems for Users**

Minimize regularized empirical risk

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^n \ell(y_i, f_{\theta}(u_i, x_i)) + \lambda \Omega(\theta)$$

• One model per user:

 $f_{\theta_u}(x)\mapsto \Upsilon$ 

• One learning problem per user:

$$\theta_u^* = \operatorname{argmin}_{\theta_u} \sum_{i:u_i=u} \ell(y_i, f_{\theta_u}(x_i)) + \lambda \Omega(\theta_u)$$

#### **Independent Learning Problems for Users**

• One learning problem per user:

 $\forall u: \theta_u^* = \operatorname{argmin}_{\theta_u} \sum_{i:u_i=u} \ell(y_i, f_{\theta_u}(x_i)) + \lambda \Omega(\theta_u)$ 

Use any model class and learning mechanism; e.g.,

•  $f_{\theta_u}(x_i) = \phi(x_i)^{\mathrm{T}} \theta_u$ 

- Logistic loss +  $\ell_2$  regularization: logistic regression
- Hinge loss +  $\ell_2$  regularization: SVM
- Squared loss +  $\ell_2$  regularization: ridge regression

#### **Independent Learning Problems for Users**

- Obvious disadvantages of independent problems:
  - Commonalities of users are not exploited,
  - User does not benefit from ratings given by other users,
  - Poor recommendations for users who gave few ratings.
- Rather use joint prediction model:
  - Recommendations for each user should benefit from other osers' ratings.

#### **Independent Learning Problems**





- Standard l<sub>2</sub> regularization follows from the assumption that model parameters are governed by normal distribution with mean vector zero.
- Instead assume that there is a non-zero population mean vector.



Graphical model of hierarchical prior

Population mean vector

$$\bar{\theta} \sim N\left[0, \frac{1}{\bar{\lambda}}I\right]$$

User-specific mean vector:

$$\theta_u \sim N\left[\bar{\theta}, \frac{1}{\lambda}I\right]$$

- Substitution:  $\theta_u = \overline{\theta} + \theta'_u$ ; now  $\overline{\theta}$  and  $\theta'_u$  have mean vector zero.
- -Log-prior = regularizer

$$\Omega(\bar{\theta} + \theta'_{u}) = \bar{\lambda} \left| \left| \bar{\theta} \right| \right|^{2} + \lambda \left| \left| \theta'_{u} \right| \right|^{2}$$

Joint optimization problem:

- Parameters  $\theta'_u$  are independent,  $\overline{\theta}$  is shared.
- Hence,  $\theta_u$  are coupled.

#### Discussion

- Each user benefits from other users' ratings.
- Does not take into account that users have different tastes.
- Two sci-fi fans may have similar preferences, but a horror-movie fan and a romantic-comedy fan do not.
- Idea: look at ratings to determine how similar users are.

#### **Collaborative Filtering**

- Idea: People like items that are liked by people who have similar preferences.
- People who give similar ratings to items probably have similar preferences.
- This is independent of item features.

#### **Collaborative Filtering**

- Users  $U = \{1, ..., m\}$
- Items  $X = \{1, ..., m'\}$
- Ratings  $Y = \{(u_1, x_1, y_1) \dots, (u_n, x_n, y_n)\}$
- Rating space  $y_i \in \Upsilon$ 
  - E.g.,  $\Upsilon = \{-1, +1\}, \Upsilon = \{\star, \dots, \star \star \star \star \star\}$
- Loss function  $\ell(y_i, y_j)$
- Find rating model:  $f_{\theta}$ :  $(u, x) \mapsto y$ .

#### **Collaborative Filtering by Nearest Neighbor**

• Define distance function on users: d(u, u')

Predicted rating:



- Predicted rating is the average rating of the k nearest neighbors in terms of d(u, u').
- No learning involved.
- Performance hinges on d(u, u').

#### **Collaborative Filtering by Nearest Neighbor**

Define distance function on users:

$$d(u,u') = \sqrt{\frac{1}{m'} \sum_{x=1}^{m'} (y_{u',x}, -y_{u,x})^2}$$

- Euclidean distance between ratings for all items.
- Skip items that have not been rated by both users.

#### **Extensions**

- Normalize ratings (subtract mean rating of user, divide by user's standard deviation)
- Weight influence of neighbors by inverse of distance.
- Weight influence of neighbors with number of jointly rated items.

$$f_{\theta}(u, x) = \frac{\sum_{\substack{k \text{ nearest} \\ \text{neighbors } u_i \text{ of } u}}{\sum_{\substack{k \text{ nearest} \\ \text{neighbors } u_i \text{ of } u}} \frac{1}{d(u, u_i)} y_{u_i, x}}$$



How much would Alice enjoy Zombiland?

• 
$$d(u, u') = \sqrt{\frac{1}{m'} \sum_{x=1}^{m'} (y_{u',x}, -y_{u,x})^2}$$

- d(A,B) =
- d(A,C) =
- d(B,C) =

• 
$$d(u, u') = \sqrt{\frac{1}{m'} \sum_{x=1}^{m'} (y_{u',x}, -y_{u,x})^2}$$

$$\bullet \quad d(A,B) = 2.9$$

$$\bullet \quad d(A,C) = 1$$

$$\bullet \quad d(B,C) = 1.4$$

$$\sum N \vdash \Omega$$

$$Y = \begin{bmatrix} 4 & 5 & 4 \\ 5 & 5 & 1 \\ 5 & 3 & 4 \end{bmatrix}$$
Alice
Bob
Carol
$$f_{\theta}(A, Z) = \frac{\sum_{\substack{n \text{ eighbors } u_i \text{ of } A} \frac{1}{d(A, u_i)} y_{u_i, Z}}{\sum_{\substack{n \text{ eighbors } u_i \text{ of } A} \frac{1}{d(A, u_i)}} =$$

$$\sum N \vdash \Omega$$

$$Y = \begin{bmatrix} 4 & 5 & 4 \\ 5 & 5 & 1 \\ 5 & 3 & 4 \end{bmatrix}$$
Alice
Bob
Carol
$$f_{\theta}(A, Z) = \frac{\sum_{\substack{n \text{ eighbors } u_i \text{ of } A} \frac{1}{d(A, u_i)} y_{u_i, Z}}{\sum_{\substack{n \text{ eighbors } u_i \text{ of } A} \frac{1}{d(A, u_i)}} = \frac{\frac{1}{2.9} 5}{\frac{1}{2} (A, U)}$$

2 nearest  $\overline{d(A,u_i)}$ neighbors  $u_i$  of A  $\frac{1}{2.9}$  +  $\frac{1}{1}$ 

#### **Collaborative Filtering: Discussion**

- K nearest neigbor and similar methods are called memory-based approaches.
  - There are no model parameters, no optimization criterion is being optimized.
  - Each prediction reuqires an iteration over all training instances → impractical!
- Better to train a model by minimizing an appropriate loss function over a space of model parameter, then use model to make predictions quickly.

- Idea: Instead of ad-hoc definition of distance between users, learn features that actually represent preferences.
- If, for every user u, we had a feature vector  $\psi_u$  that describes their preferences,
- Then we could learn parameters  $\theta_x$  for item x such that  $\theta_x^T \psi_u$  quantifies how much u enjoys x.

- Or, turned around,
  - If, for every item x we had a feature vector  $\phi_x$  that characterizes its properties,
  - We could learn parameters  $\theta_u$  such that  $\theta_u^T \phi_x$  quantifies how much u enjoys x.
- In practice some user attributes  $\psi_u$  and item attributes  $\phi_x$  are usually available, but they are insufficient to understand *u*'s preferences and *x*'s relevant properties.

- Idea: construct user attributes  $\psi_u$  and item attributes  $\phi_x$  such that ratings in training data can be predicted accurately.
- Decision function:

$$f_{\Psi,\Phi}(u,x) = \psi_u^{\mathrm{T}} \phi_x$$

- Prediction is product of user preferences and item properties.
- Model parameters:
  - Matrix  $\Psi$  of user features  $\psi_u$  for all users,
  - Matrix  $\Phi$  of item features  $\phi_x$  for all items.

 Optimization criterion: (Ψ\*, Φ\*)

$$= \operatorname{argmin}_{\Psi,\Phi} \sum_{x,u} \ell(y_{u,x}, f_{\Psi,\Phi}(u,x) + \lambda \left[ \sum_{u} ||\psi_{u}||^{2} + \sum_{x} ||\phi_{x}||^{2} \right]$$

Feature vectors of all users and all Items are regularized

- Both item and user features are the solution of an optimization problem.
- Number of features k has to be set.
- Meaning of the features is not pre-determined.
- Sometimes they turn out to be interpretable.

Decision function:

$$f_{\Psi,\Phi}(u,x) = \psi_u^{\mathrm{T}} \phi_x$$

In matrix notation:

$$\widehat{Y}_{\Psi,\Phi} = \Psi \Phi^{\mathrm{T}}$$

Matrix elements:

$$\begin{bmatrix} \hat{y}_{11} & \cdots & \hat{y}_{1m'} \\ & \ddots & \\ \hat{y}_{m1} & & \hat{y}_{mm'} \end{bmatrix}$$

$$= \begin{bmatrix} \psi_{11} & \cdots & \psi_{1k} \\ & \ddots & \\ & \psi_{m1} & & \psi_{mk} \end{bmatrix} \begin{bmatrix} \phi_{11} & \cdots & \phi_{m'1} \\ & \ddots & \\ & \phi_{1k} & & \phi_{m'k} \end{bmatrix}$$

Decision function in matrix notation:



Decision function in matrix notation:



Optimization criterion:

(Ψ<sup>\*</sup>, Φ<sup>\*</sup>)

$$= \operatorname{argmin}_{\Psi,\Phi} \sum_{x,u} \ell(y_{u,x}, f_{\Psi,\Phi}(u,x)) + \lambda \left( \left| |\Psi| \right|^2 + \left| |\Phi| \right|^2 \right)$$

- Criterion is not convex:
  - For instance, multiplying all feature vectors with -1 gives an equally good solution:  $f_{\Psi,\Phi}(u,x) = \psi_u^T \phi_x = (-\psi_u^T)(-\phi_x)$
- Limiting the number of latent features to k restricts the rank of matrix  $\hat{Y}$ .

Optimization criterion:
 (Ψ\*, Φ\*)

$$= \operatorname{argmin}_{\Psi,\Phi} \sum_{x,u} \ell(y_{x,u}, f_{\Psi,\Phi}(u,x)) + \lambda \left( \left| |\Psi| \right|^2 + \left| |\Phi| \right|^2 \right)$$

- Optimization by
  - Stochastic gradient descent or
  - Alternating least squares.

## Matrix Factorization by Stochastic Gradient Descent

• Iterate through ratings  $y_{u,x}$  in training sample

• Let 
$$\psi'_u \leftarrow \psi_u - \alpha \frac{\partial f_{\Psi,\Phi}(u,x)}{\partial \psi_u}$$
  
• Let  $\phi'_x \leftarrow \phi_x - \alpha \frac{\partial f_{\Psi,\Phi}(u,x)}{\partial \phi_x}$ 

- Until convergence.
- Requires differentiable loss function; e.g., squared loss, …

- For squared loss and parallel architectures.
- Alternate between 2 optimization processes:
  - Keep  $\Phi$  fixed, optimize  $\psi_u$  in parallel for all u.
  - Keep  $\Psi$  fixed, optimize  $\phi_x$  in parallel for all x.

- For squared loss and parallel architectures.
- Alternate between 2 optimization processes:
  - Keep  $\Phi$  fixed, optimize  $\psi_u$  in parallel for all u.
  - Keep  $\Psi$  fixed, optimize  $\phi_x$  in parallel for all x.
- Optimization criterion for  $\Psi$ :

$$\psi_{u}^{*} = \operatorname{argmin}_{\psi_{u}}(y_{u} - \hat{y}_{u})^{2} - \lambda ||\psi_{u}||^{2}$$
$$= \operatorname{argmin}_{\psi_{u}}(y_{u} - \psi_{u}^{T}\Phi^{T})^{2} - \lambda ||\psi_{u}||^{2}$$

$$[\hat{y}_{u1} \ \dots \ \hat{y}_{um'}] = [\psi_{u1} \ \dots \ \psi_{uk}] \begin{bmatrix} \phi_{11} \ \dots \ \phi_{m'1} \\ & \ddots \\ & \\ \phi_{1k} \ & \phi_{m'k} \end{bmatrix}$$

- For squared loss and parallel architectures.
- Alternate between 2 optimization processes:
  - Keep  $\Phi$  fixed, optimize  $\psi_u$  in parallel for all u.
  - Keep  $\Psi$  fixed, optimize  $\phi_x$  in parallel for all x.
- Optimization criterion for  $\Psi$ :

 $\psi_{u}^{*} = \operatorname{argmin}_{\psi_{u}} (y_{u} - \psi_{u}^{\mathrm{T}} \Phi^{\mathrm{T}})^{2} - \lambda ||\psi_{u}||^{2}$  $\psi_{u}^{*} = (\Phi \Phi^{\mathrm{T}} + \lambda I)^{-1} \Phi y_{u}$ 

- For squared loss and parallel architectures.
- Alternate between 2 optimization processes:
  - Keep  $\Phi$  fixed, optimize  $\psi_u$  in parallel for all u.
  - Keep  $\Psi$  fixed, optimize  $\phi_x$  in parallel for all x.
- Optimization criterion for  $\Psi$ :

 $\psi_{u}^{*} = \operatorname{argmin}_{\psi_{u}} (y_{u} - \psi_{u}^{\mathrm{T}} \Phi^{\mathrm{T}})^{2} - \lambda ||\psi_{u}||^{2}$  $\psi_{u}^{*} = (\Phi \Phi^{\mathrm{T}} + \lambda I)^{-1} \Phi y_{u}$ 

Optimization criterion for Φ:

$$\phi_{x}^{*} = \operatorname{argmin}_{\phi_{x}} (y_{x} - \phi_{x}^{\mathrm{T}} \Psi^{\mathrm{T}})^{2} - \lambda ||\phi_{x}||^{2}$$
  
$$\phi_{x}^{*} = (\Psi \Psi^{\mathrm{T}} + \lambda I)^{-1} \Psi y_{x}$$

- For squared loss and parallel architectures.
- Initialize  $\Psi$ ,  $\Phi$  randomly.
- Repeat until convergence:
  - Keep  $\Psi$  fixed, for all u in parallel:

 $\star \psi_u = \left(\Phi \Phi^{\mathrm{T}} + \lambda I\right)^{-1} \Phi y_u$ 

• Keep  $\Phi$  fixed, for all x in parallel:

$$\star \phi_u = \left(\Psi \Psi^{\mathrm{T}} + \lambda I\right)^{-1} \Psi y_{\chi}$$

#### **Extensions: Biases**

• Some users just give optimistic or pessimistic ratings; some items are hyped. Decision function:  $f_{\Psi,\Phi,B_u,B_x}(u,x) = b_u + b_x + \psi_u^T \phi_x$ 

Optimization criterion:

 $(\Psi^{*}, \Phi^{*}, B_{u}, B_{x})$   $= \operatorname{argmin}_{\Psi, \Phi} \sum_{x, u} \ell(y_{x, u}, f_{\Psi, \Phi, B_{u}, B_{x}}(u, x))$   $+ \lambda \left( \left| |\Psi| \right|^{2} + \left| |\Phi| \right|^{2} + \left| |B_{u}| \right|^{2} + \left| |B_{x}| \right|^{2} \right)$ 

#### **Extensions: Explicit Features**

- Often, explicit user and item features are available.
- Concatenate vectors  $\psi_u$  and  $\phi_x$ ; explicit features are fixed, latent features are free paremeters.

#### **Extensions: Temporal Dynamics**

- How much a user likes an item depends on the point in time when the rating takes place.
  - $f_{\Psi,\Phi,B_{u},B_{\chi},t}(u,x) = b_{u}(t) + b_{\chi}(t) + \psi_{u}(t)^{\mathrm{T}}\phi_{\chi}$



#### **Summary**

- Purely content-based recommendation: users don't benefit from other users' ratings.
- Collaborative filtering by nearest neighbors: fixed definition of similarity of users. No model parameters, no learning. Has to iterate over data to make recommendation.
- Latent factor models, matrix factorization: user preferences and item properties are free parameters, optimized to minimized discrepancy between inferred and actual ratings.