Claspar A Distributed Conflict-Driven Answer Set Solver

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1 Introduction

2 Search Topologies

3 Knowledge Exchange



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Overview claspar

- Is a parallel answer set solver based on MPI and *clasp*
- Builds upon *clasp*'s interfaces
 - Incremental interface
 - Extensible propagation
 - No changes to the *clasp* library itself!
- Supports a subset of *clasp*'s reasoning modes
 - Enumeration
 - Optimization
- Inherits all of *clasp*'s options related to search strategies!
- Offers different search topologies
 - Search space splitting using guiding paths
 - Competitive search using solver portfolios
 - Combinations of both
- Configurable knowledge exchange between solver instances



2 Search Topologies

3 Knowledge Exchange



Search Topologies

Master Worker Topology

- Master divides search space among workers using the guiding path technique
- Solver instances work on disjoint search spaces
- Maximum work sharing
- Competition Topology
 - Extends master worker topology
 - Worker and a set of competitors solve the same subproblem
 - Different search strategies for workers and competitors
 - More robust

Hierarchical Master Worker

- Extends master worker topology
- Superior master controls set of inferior masters
- Inferior masters control workers
- Better scaling than master worker topology

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	Guiding Path				
ASP	174,661 (24)	154,504 (22)	103,283 (14)	85,578 (11)	
SAT	89,428 (8)	42,491 (5)	38,293 (6)	30,515 (4)	
	Uniform Portfolio				
ASP	174,661 (24)	149,157 (17)	133,147 (18)	113,309 (16)	
SAT	89,428 (8)	57,694 (3)	40,555 (2)	31,734 (2)	
Non-uniform Portfolio					
ASP	174,661 (24)	141,890 (16)	98,160 (11)	92,331 (11)	
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Knowledge Exchange

- No nogood exchange per default
- All-to-all Nogood Exchange
 - No scaling
- Local Nogood Exchange
 - Exchange depends on topology
 - Competition Worker + associated competitors Hierarchical Workers sharing a Master Master Worker Equivalent to all-to-all exchange
 - Localize exchange
- Hypercube Nogood Exchange
 - Solver instances organized in hypercube
 - Exchange along edges
 - Better scaling/ still some locality
- Nogood Filtering Heuristics
 - Nogood length
 - Literal Blocking Distance

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SAT	89,428 (8)	29,067 (0)	28,324 (3)	14,373 (1)	
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ASP	174,661 (24)	92,108 (10)	82,388 (13)	64,028 (9)	
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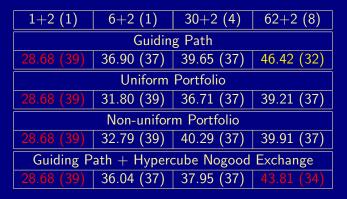


Optimization

Branch and bound optimization

- Lower bounds sent to dedicated process
- Then broadcasted and incorporated if relevant
- Lowest reported bound corresponds to optimum
- Compatible with all search topologies

1+2 (1)	6+2 (1)	30+2 (4)	62+2 (8)		
	Guidin	g Path			
28.68 (39)	36.90 (37)	39.65 (37)	46.42 (32)		
	Uniform	Portfolio			
28.68 (39)	31.80 (39)	36.71 (37)	39.21 (37)		
	Non-uniform Portfolio				
28.68 (39)	32.79 (39)	40.29 (37)	39.91 (37)		
Guiding Path + Hypercube Nogood Exchange					
28.68 (39)	36.04 (37)	37.95 (37)	43.81 (34)		



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Summary

Available at

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claspar is adjustable to various physical architectures through

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- claspar might be valuable to solve challenging problems
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