

Domain-specific Heuristics in Answer Set Programming

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Outline

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Motivation

- Answer Set Programming (ASP)
 - General purpose approach to declarative problem solving
 - Combination of a rich yet simple modeling language with highly performant solving capacities
- Sometimes it is advantageous to take a more application-oriented approach by including domain-specific information
 - domain-specific knowledge can be added for improving propagation
 - domain-specific heuristics can be used for making better choices
- Proposal A declarative framework for incorporating domain-specific heuristics into ASP by extending its
 - input language for expressing domain-specific heuristics
 - solving capacities for integrating domain-specific heuristics

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Basic CDCL decision algorithm

loop

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propagate           // compute deterministic consequences
if no conflict then
    if all variables assigned then return variable assignment
    else decide          // non-deterministically assign some literal
else
    if top-level conflict then return unsatisfiable
    else
        analyze           // analyze conflict and add a conflict constraint
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Inside *decide*

■ Basic concepts

- Atoms, \mathcal{A}
- Assignments, $A : \mathcal{A} \rightarrow \{\mathbf{T}, \mathbf{F}\}$

$$A^{\mathbf{T}} = \{a \in \mathcal{A} \mid a \mapsto \mathbf{T} \in A\} \quad \text{and} \quad A^{\mathbf{F}} = \{a \in \mathcal{A} \mid a \mapsto \mathbf{F} \in A\}$$

■ Heuristic functions

$$h : \mathcal{A} \rightarrow [0, +\infty) \quad \text{and} \quad s : \mathcal{A} \rightarrow \{\mathbf{T}, \mathbf{F}\}$$

■ Algorithmic scheme

- 1 $h(a) := \alpha \times h(a) + \beta(a)$ for each $a \in \mathcal{A}$
- 2 $U := \mathcal{A} \setminus (A^{\mathbf{T}} \cup A^{\mathbf{F}})$
- 3 $C := \operatorname{argmax}_{a \in U} h(a)$
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Heuristic language elements

- Heuristic predicate `_heuristic`
- Heuristic modifiers (atom, a , and integer, v)
 - init for initializing the heuristic value of a with v
 - factor for amplifying the heuristic value of a by factor v
 - level for ranking all atoms; the rank of a is v
 - sign for attributing the sign of v as truth value to a

- Heuristic atoms

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_heuristic(occurs(A,T),factor,T) :- action(A), time(T).
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```

# Simple STRIPS planner

```
time(1..t).
```

```
holds(P,0) :- init(P).
```

```
1 { occurs(A,T) : action(A) } 1 :- time(T).
:- occurs(A,T), pre(A,F), not holds(F,T-1).
```

```
holds(F,T) :- holds(F,T-1), not nolds(F,T), time(T).
```

```
holds(F,T) :- occurs(A,T), add(A,F).
```

```
nolds(F,T) :- occurs(A,T), del(A,F).
```

```
:- query(F), not holds(F,t).
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holds(F,T) :- occurs(A,T), add(A,F).
nolds(F,T) :- occurs(A,T), del(A,F).

:- query(F), not holds(F,t).

_heuristic(occurs(A,T),factor,2) :- action(A), time(T).
```

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_heuristic(occurs(A,T),level,1) :- action(A), time(T).
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_heuristic(A,level,V) :- _heuristic(A,false,V).
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_heuristic(holds(F,T-1),true, t-T+1) :- holds(F,T).
_heuristic(holds(F,T-1),false,t-T+1) :-
 fluent(F), time(T), not holds(F,T).
```

# Heuristic modifications to functions $h$ and $s$

- $\nu(V_{a,m}(A))$  — “value for modifier  $m$  on atom  $a$  wrt assignment  $A$ ”

- init and

$$d_0(a) = \nu(V_{a,\text{init}}(A_0)) + h_0(a)$$

$$d_i(a) = \begin{cases} \nu(V_{a,\text{factor}}(A_i)) \times h_i(a) & \text{if } V_{a,\text{factor}}(A_i) \neq \emptyset \\ h_i(a) & \text{otherwise} \end{cases}$$

- sign

$$t_i(a) = \begin{cases} \mathbf{T} & \text{if } \nu(V_{a,\text{sign}}(A_i)) > 0 \\ \mathbf{F} & \text{if } \nu(V_{a,\text{sign}}(A_i)) < 0 \\ s_i(a) & \text{otherwise} \end{cases}$$

- level      $\ell_{A_i}(\mathcal{A}') = \text{argmax}_{a \in \mathcal{A}'} \nu(V_{a,\text{level}}(A_i))$       $\mathcal{A}' \subseteq \mathcal{A}$

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# Abductive problems with optimization

| <i>Setting</i>            | <i>Diagnosis</i> | <i>Expansion</i> | <i>Repair (H)</i> | <i>Repair (S)</i> |
|---------------------------|------------------|------------------|-------------------|-------------------|
| <i>base configuration</i> | 111.1s (115)     | 161.5s (100)     | 101.3s (113)      | 33.3s (27)        |
| <i>sign,-1</i>            | 324.5s (407)     | 7.6s (3)         | 8.4s (5)          | 3.1s (0)          |
| <i>sign,-1 factor,2</i>   | 310.1s (387)     | 7.4s (2)         | 3.5s (0)          | 3.2s (1)          |
| <i>sign,-1 factor,8</i>   | 305.9s (376)     | 7.7s (2)         | 3.1s (0)          | 2.9s (0)          |
| <i>sign,-1 level,1</i>    | 76.1s (83)       | 6.6s (2)         | 0.8s (0)          | 2.2s (1)          |
| <i>level,1</i>            | 77.3s (86)       | 12.9s (5)        | 3.4s (0)          | 2.1s (0)          |

(abducibles subject to optimization via `#minimize` statements)

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# Planning Competition Benchmarks

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|----------------------|---------------------------|-------------------|----------------------|---------------------|
| <i>Blocks'00</i>     | 134.4s (180/61)           | 9.2s (239/3)      | 163.2s (59)          | 2.6s (0)            |
| <i>Elevator'00</i>   | 3.1s (279/0)              | 0.0s (279/0)      | 3.4s (0)             | 0.0s (0)            |
| <i>Freecell'00</i>   | 288.7s (147/115)          | 184.2s (194/74)   | 226.4s (47)          | 52.0s (0)           |
| <i>Logistics'00</i>  | 145.8s (148/61)           | 115.3s (168/52)   | 113.9s (23)          | 15.5s (3)           |
| <i>Depots'02</i>     | 400.3s (51/184)           | 297.4s (115/135)  | 389.0s (64)          | 61.6s (0)           |
| <i>Driverlog'02</i>  | 308.3s (108/143)          | 189.6s (169/92)   | 245.8s (61)          | 6.1s (0)            |
| <i>Rovers'02</i>     | 245.8s (138/112)          | 165.7s (179/79)   | 162.9s (41)          | 5.7s (0)            |
| <i>Satellite'02</i>  | 398.4s (73/186)           | 229.9s (155/106)  | 364.6s (82)          | 30.8s (0)           |
| <i>Zenotravel'02</i> | 350.7s (101/169)          | 239.0s (154/116)  | 224.5s (53)          | 6.3s (0)            |
| <i>Total</i>         | 252.8s (1225/1031)        | 158.9s (1652/657) | 187.2s (430)         | 17.1s (3)           |

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# Planning Competition Benchmarks

```

_heuristic(holds(F,T-1),true, t-T+1) :- holds(F,T).
_heuristic(holds(F,T-1),false,t-T+1) :-
 fluent(F), time(T), not holds(F,T).

```

| Problem              | <i>base configuration</i> | <i>_heuristic</i> | <i>base c. (SAT)</i> | <i>_heur. (SAT)</i> |
|----------------------|---------------------------|-------------------|----------------------|---------------------|
| <i>Blocks'00</i>     | 134.4s (180/61)           | 9.2s (239/3)      | 163.2s (59)          | 2.6s (0)            |
| <i>Elevator'00</i>   | 3.1s (279/0)              | 0.0s (279/0)      | 3.4s (0)             | 0.0s (0)            |
| <i>Freecell'00</i>   | 288.7s (147/115)          | 184.2s (194/74)   | 226.4s (47)          | 52.0s (0)           |
| <i>Logistics'00</i>  | 145.8s (148/61)           | 115.3s (168/52)   | 113.9s (23)          | 15.5s (3)           |
| <i>Depots'02</i>     | 400.3s (51/184)           | 297.4s (115/135)  | 389.0s (64)          | 61.6s (0)           |
| <i>Driverlog'02</i>  | 308.3s (108/143)          | 189.6s (169/92)   | 245.8s (61)          | 6.1s (0)            |
| <i>Rovers'02</i>     | 245.8s (138/112)          | 165.7s (179/79)   | 162.9s (41)          | 5.7s (0)            |
| <i>Satellite'02</i>  | 398.4s (73/186)           | 229.9s (155/106)  | 364.6s (82)          | 30.8s (0)           |
| <i>Zenotravel'02</i> | 350.7s (101/169)          | 239.0s (154/116)  | 224.5s (53)          | 6.3s (0)            |
| <i>Total</i>         | 252.8s (1225/1031)        | 158.9s (1652/657) | 187.2s (430)         | 17.1s (3)           |

# Outline

# Summary

- A declarative framework for incorporating domain-specific heuristics into ASP
  - seamless integration into ASP's input language
  - general and flexible tool for expressing domain-specific heuristics
  - new possibilities of applying, experimenting, and studying domain-specific heuristics in a uniform setting
- <http://potassco.sourceforge.net/labs.html#hclasp>