Answer Set Programming: From Theory to Practice

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Outline

- Introduction
- 2 Foundations
- 3 Grounding
- 4 Solving
- 5 Modeling
- 6 Engineering
- 7 Applications

Full version https://teaching.potassco.org



Introduction: Overview

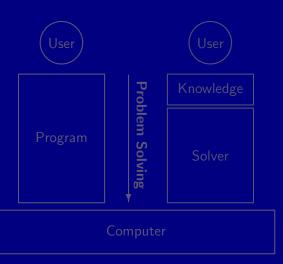
- 1 Motivation
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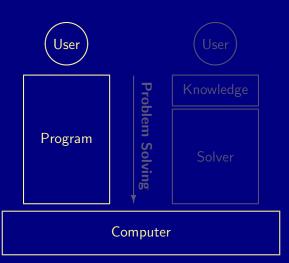
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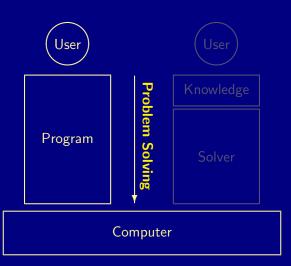




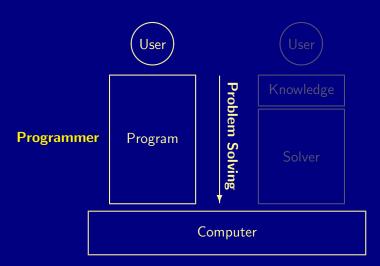




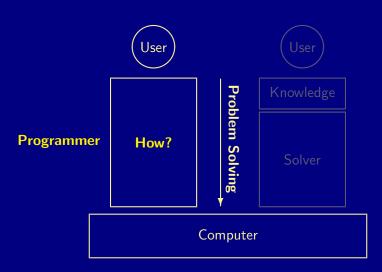




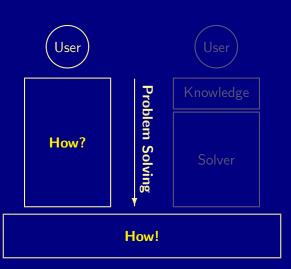






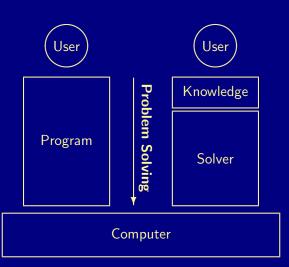




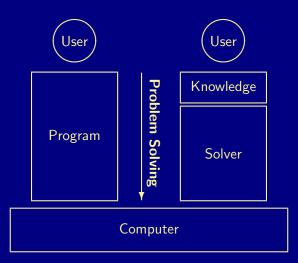




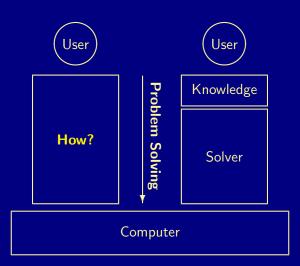
Declarative Software



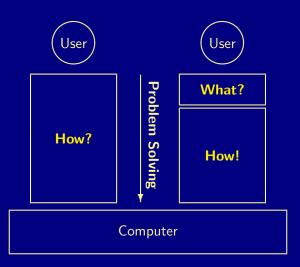




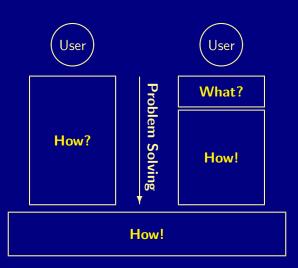




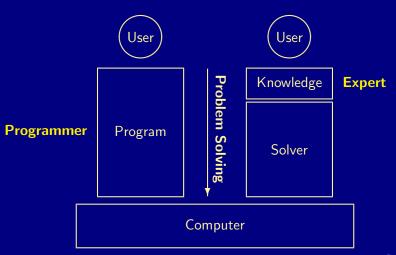














- + Transparency
- + Flexibility
- + Maintainability
- + Reliability
- + Generality
- + Efficiency
- + Optimality
- + Availability



Expert



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Natural Language

Expert



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Natural Language

Layperson



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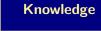
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Expert



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■ What is ASP?
ASP is an approach for declarative problem solving



- What is ASP?ASP is an approach for declarative problem solving
- Where is ASP from?
 - Databases
 - Logic programming
 - Knowledge representation and reasoning
 - Satisfiability solving



- What is ASP? ASP = DB+LP+KR+SAT!

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 Examples Sudoku, Configuration, Diagnosis, Music composition,
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 - Debian, Ubuntu: Linux package configuration
 - Exeura: Call routing
 - Fcc: Radio frequency auction
 - Gioia Tauro: Workforce management
 - Nasa: Decision support for Space Shuttle
 - Siemens: Partner units configuration
 - Variantum: Product configuration
 - US Navy: risk assessment



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Over 13 months in 2016–17 the US federal Communications Commission conducted an "incentive auction" to repurpose radio spectrum from broadcast television to wireless intenet. In the end, the auction yielded \$19.8 billion, \$10.05 billion of which was paid to 175 broadcasters for voluntarily relinquishing their licenses across 14 UHF channels. Stations that continued broadcasting were assigned potentially new channels to fit as densely as possible into the channels that remained. The government netted more than \$75 billion (used to pay down the national debt) after covering costs. A crucial element of the auction design was the construction of a solver, dubbed SATFC, that determined whether sets of stations could be "repacked" in this way; it needed or run every time a station was given a price quote. This



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- What are ASP's distinguishing features?
 - High level, versatile modeling language
 - High performance solvers
 - Qualitative and quantitative optimization



Answer Set Programming (ASP)

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 Problems consisting of (many) decisions and constraints
- What are ASP's distinguishing features?
 - High level, versatile modeling language
 - High performance solvers
 - Qualitative and quantitative optimization
- Any industrial impact?
 - ASP Tech companies: DLV Systems and Potassco Solutions
 - Increasing interest in (large) companies



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- '80 Capturing incomplete information
- '90 Amalgamation and computation
- '00 Applications and semantic rediscoveries
- '10 Customization and integration



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 - Databases Closed world assumption
 - Logic programming Negation as failure
 - Non-monotonic reasoning Auto-epistemic and Default logics, Circumscription
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 - Complex reasoning modes APIs, multi-shot solving
 - Hybridization Constraint ASP, theory solving

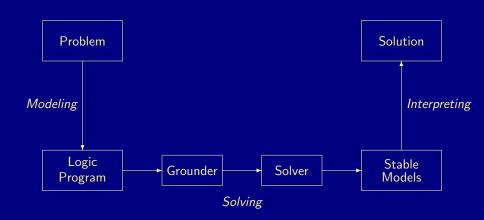


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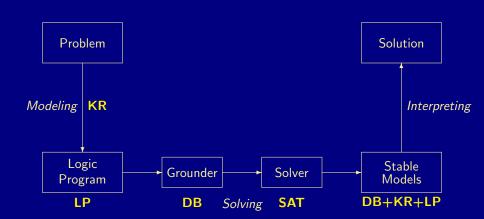


Modeling, grounding, and solving





Rooting ASP





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- ASP as High-level Language
 - Express problem instance as sets of facts
 - Encode problem class as a set of rules
 - Read off solutions from stable models of facts and rules
- ASP as Low-level Language
 - Compile a problem into a set of facts and rules
 - Solve the original problem by solving its compilation
- ASP and Imperative language
 Control continuously changing logic programs



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Two and a half sides of a coin

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Foundations: Overview

- 6 Reduct-based characterization
- 7 Axiomatic characterization
- 8 Logical characterization



- Reduct-based characterization
- Logical characterization
- Axiomatic characterization
- Operational characterization
- Proof-theoretic characterization
- Constraint-based characterization
- Algorithmic characterization
- C++-based characterization
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Propositional Normal Logic Programs

 \blacksquare A logic program P is a set of rules of the form

$$\underbrace{a}_{\mathsf{head}} \leftarrow \underbrace{b_1, \dots, b_m, \neg c_1, \dots, \neg c_n}_{\mathsf{body}}$$

- \blacksquare a and all b_i, c_i are atoms (propositional variables)
- \blacksquare \leftarrow , ,, \neg denote if, and, and negation
- intuitive reading: head must be true if body holds
- Semantics given by stable models, informally,
 models of P justifying each true atom by some rule in P

Logic Programs

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- Disclaimer The following formalities apply to normal logic programs



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a
 b
 c

$$(\neg b \rightarrow a) \land (b \rightarrow c)$$

 F
 F
 F

 F
 T
 F

 F
 T
 T

 T
 F
 T

 T
 T
 F

 T
 T
 T

 T
 T
 T

 T
 T
 T





abc
$$(\neg b \rightarrow a) \land (b \rightarrow c)$$
FFF $(T \rightarrow F) \land (F \rightarrow F)$ FFT $(T \rightarrow F) \land (F \rightarrow T)$ FTT $(F \rightarrow F) \land (T \rightarrow F)$ TFF $(T \rightarrow T) \land (F \rightarrow F)$ TFT $(T \rightarrow T) \land (F \rightarrow T)$ TT $(F \rightarrow T) \land (T \rightarrow F)$ TT $(F \rightarrow T) \land (T \rightarrow T)$









a	b	С	$(\lnot b ightarrow a) \wedge (b ightarrow c)$
F	F	F	F ∧ T
F	F	T	$m{F} \wedge m{T}$
F	T	F	$m{ au} \wedge m{ au}$
F	T	T	$T \wedge T$
T	F	F	$ au \wedge au$
T	F	T	$ au \wedge au$
T	T	F	$m{ au} \wedge m{ au}$
T	T	T	$T \wedge T$



a	b	С	$(\lnot b ightarrow a) \wedge (b ightarrow c)$
F	F	F	F
F	F	T	F
F	T	F	F
F	T	T	T
T	F	F	T
T	F	T	T
T	T	F	F
T	T	T	T



a	b	С	$(\lnot b ightarrow a) \wedge (b ightarrow c)$
F	F	F	F
F	F	T	F
F	T	F	F
F	T	T	T
T	F	F	T
T	F	T	T
T	T	F	F
T	T	T	T

■ We get four models: $\{b, c\}$, $\{a\}$, $\{a, c\}$, and $\{a, b, c\}$



Some truth tabling, and now ASP

a
 b
 c

$$(\neg b \rightarrow a) \land (b \rightarrow c)$$

 F
 F
 F

 F
 T
 F

 F
 T
 T

 T
 F
 F

 T
 T
 F

 T
 T
 T

 T
 T
 T

 T
 T
 T











a	b	С	$(\neg b ightarrow a) \wedge (b ightarrow c)$
F	F	F	$a \wedge (b \rightarrow c)$
F	F	T	$a \wedge (b ightarrow c)$
F	T	F	$m{T} \wedge (b ightarrow c)$
F	T	T	$m{T} \wedge (b ightarrow c)$
T	F	F	$a \wedge (b \rightarrow c)$
T	F	T	$a \wedge (b \rightarrow c)$
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T	T	T	$T \wedge (b \rightarrow c)$



a	b	С	$(\neg b ightarrow a) \wedge (b ightarrow c)$
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F	F	T	$a \wedge (b ightarrow c)$
F	T	F	(b ightarrow c)
F	T	T	(b o c)
T	F	F	$a \wedge (b \rightarrow c)$
T	F	T	$a \wedge (b \rightarrow c)$
T	T	F	(b ightarrow c)
T	T	T	(b ightarrow c)
			Reduct



a	b	С	$(\neg b ightarrow a) \wedge (b ightarrow c)$
F	F	F	$a \wedge (b \rightarrow c)$
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T	T	T	(b ightarrow c)
			Reduct



а	Ь	С	$(\lnot b ightarrow a) \land (b ightarrow c)$
		F	, , , ,
Г	r	Г	$a \wedge (b ightarrow c)$
F	F	T	$a \wedge (b ightarrow c)$
F	T	F	(b o c)
F	T	T	$(b ightarrow c)\models$
T	F	F	$a \wedge (b ightarrow c) \models a$
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			Reduct



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F	T	T	$(b ightarrow c) \models$
T	F	F	$a \wedge (b \rightarrow c) \models a$
T	F	T	$a \wedge (b \rightarrow c) \models a$
T	T	F	(b o c)
T	T	T	$(b ightarrow c) \models$
			Reduct





■ We get one stable model: $\{a\}$



- We get one stable model: $\{a\}$
- Stable models = Smallest models of (respective) reducts



Stable model

 \blacksquare A logic program P is a set of rules, r, of the form

$$a \leftarrow b_1, \ldots, b_m, \neg c_1, \ldots, \neg c_n$$

The reduct, P^X , of a program P relative to a set X of atoms is

$$P^X = \{a \leftarrow b_1, \dots, b_m \mid r \in P, \{c_1, \dots, c_n\} \cap X = \emptyset\}$$

- ightharpoonup Cn(P) stands for the smallest model of a positive program P
- A set X of atoms is a stable model of a program P if $Cn(P^X) = X$



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$$P = \{ a \leftarrow \neg b \quad b \leftarrow \neg a \quad x \leftarrow a, \neg c \quad x \leftarrow y \quad y \leftarrow x, b \}$$

$$CF(P) = \{ a \leftarrow \neg b \quad b \leftarrow \neg a \quad x \leftarrow (a \land \neg c) \lor y \quad y \leftarrow x \land b \}$$

$$\cup \{ c \leftrightarrow \bot \}$$

$$LF(P) = \{ (x \lor y) \rightarrow a \land \neg c \}$$

Classical models of CF(P):

$$\{b\}, \{b,c\}, \{b,x,y\}, \{b,c,x,y\}, \{a,c\}, \{a,b,c\}, \{a,x\}, \{a,c,x\}$$

 $\{a,x,y\}, \{a,c,x,y\}, \{a,b,x,y\}, \{a,b,c,x,y\}$

- Unsupported atoms
 - Unfounded atoms



$$P = \{ a \leftarrow \neg b \quad b \leftarrow \neg a \quad x \leftarrow a, \neg c \quad x \leftarrow y \quad y \leftarrow x, b \}$$

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Classical models of
$$RF(P)$$
: (only true atoms shown) $\{b\}, \{b,c\}, \{b,x,y\}, \{b,c,x,y\}, \{a,c\}, \{a,b,c\}, \{a,x\}, \{a,c,x\}, \{a,x,y\}, \{a,c,x,y\}, \{a,b,x,y\}, \{a,b,c,x,y\}$

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Classical models of RF(P):

$$\{b\}, \{b,c\}, \{b,x,y\}, \{b,c,x,y\}, \{a,c\}, \{a,b,c\}, \{a,x\}, \{a,c,x\}, \{a,x,y\}, \{a,c,x,y\}, \{a,b,x,y\}, \{a,b,c,x,y\}$$

- Unsupported atoms
- Unfounded atoms



$$P = \left\{ a \leftarrow \neg b \quad b \leftarrow \neg a \quad x \leftarrow a, \neg c \quad x \leftarrow y \quad y \leftarrow x, b \right\}$$

$$CF(P) = \left\{ a \leftrightarrow \neg b \quad b \leftrightarrow \neg a \quad x \leftrightarrow (a \land \neg c) \lor y \quad y \leftrightarrow x \land b \right\}$$

$$\cup \left\{ c \leftrightarrow \bot \right\}$$

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Classical models of $CF(P) \cup LF(P)$:

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$$CF(P) = \left\{ a \leftrightarrow \left(\bigvee_{(a \leftarrow B) \in P} BF(B) \right) \mid a \in A(P) \right\}$$

$$BF(B) = \bigwedge_{b \in B \cap A(P)} b \land \bigwedge_{\neg c \in B} \neg c$$

$$LF(P) = \left\{ \left(\bigvee_{a \in L} a \right) \rightarrow \left(\bigvee_{a \in L, (a \leftarrow B) \in P, B \cap L = \emptyset} BF(B) \right) \mid L \in loop(P) \right\}$$
Classical models of $CF(P) \sqcup LF(P)$:

Theorem (Lin and Zhao)

Let P be a normal logic program and $X \subseteq A(P)$. Then, X is a stable model of P iff $X \models CF(P) \cup LF(P)$.

- Size of CF(P) is linear in the size of P
- Size of LF(P) may be exponential in the size of P



- \blacksquare SAT = ASP + Law of the excluded middle
- ASP = SAT + Completion and Loop formulas

Note Checking whether a propositional formula has a stable model is Σ_P^2 -complete



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■ Note Checking whether a propositional formula has a stable model is Σ_P^2 -complete



Outline

- 6 Reduct-based characterization
- 7 Axiomatic characterization
- 8 Logical characterization



- An interpretation is a pair $\langle H, T \rangle$ of sets of atoms with $H \subseteq T$
 - *H* is called "here" and
 - *T* is called "there"
- lacksquare Note $\langle H, T \rangle$ is a simplified Kripke structure
- Intuition
 - H represents provably true atoms
 - T represents possibly true atoms
 - atoms not in T are false
- Idea
 - \blacksquare $\langle H, T \rangle \models \varphi \sim \varphi$ is provably true
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Satisfaction

$$\blacksquare$$
 $\langle H, T \rangle \models a \text{ if } a \in H$

for any atom a

- lacksquare $\langle H, T \rangle \models \varphi \wedge \psi$ if $\langle H, T \rangle \models \varphi$ and $\langle H, T \rangle \models \psi$
- $\bullet \ \, \langle H,T\rangle \models \varphi \rightarrow \psi \text{ if } \langle X,T\rangle \models \varphi \text{ implies } \langle X,T\rangle \models \psi \\ \text{for both } X=H,T$
- \blacksquare Note $\langle H, T \rangle \models \neg \varphi$ if $\langle T, T \rangle \not\models \varphi$

since $\neg \varphi = \varphi \rightarrow \bot$

 \blacksquare An interpretation $\langle H, T \rangle$ is a model of φ , if $\langle H, T \rangle \models \varphi$



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Classical tautologies

Н	T	а	$\neg a$	$a \lor \neg a$	$\neg \neg a$	$a \leftarrow \neg \neg a$
{a}	{a}	T	F	T	T	T
Ø	{a}	F	F	F	T	F
Ø	Ø	F	T	T	F	T



- A total interpretation $\langle T, T \rangle$ is an equilibrium model of a formula φ , if
 - 1 $\langle T, T \rangle \models \varphi$, 2 $\langle H, T \rangle \not\models \varphi$ for all $H \subset T$
- \blacksquare ${\cal T}$ is called a stable model of φ
- \blacksquare Note $\langle T, T \rangle$ acts as a classical model
- Note $\langle H, T \rangle \models P$ iff $H \models P^T$ (P^T is the reduct of P by T

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 $(P^T \text{ is the reduct of } P \text{ by } T)$



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Grounding: Overview

- 9 Ground instantiation
- 10 Stable models
- 11 Grounding safe programs



Outline

- 9 Ground instantiation
- 10 Stable models
- 11 Grounding safe programs



- \blacksquare Let $\mathcal T$ be a set of (variable-free) terms
- lacksquare Let ${\mathcal A}$ be a set of (variable-free) atoms constructible from ${\mathcal T}$
- A variable-free atom is also called ground
- Ground instances of a rule r are obtained by replacing all variables in r by elements from \mathcal{T} :

$$\mathsf{ground}(r) = \{r heta \mid heta : \mathsf{var}(r)
ightarrow \mathcal{T} \; \mathsf{and} \; \mathsf{var}(r heta) = \emptyset \}$$

where var(r) stands for the set of all variables occurring in r and θ is a (ground) substitution

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 - Examples 42, "coucou", Zorro, grandfather(leon), 3 + X
- lacktriangle Let ${\mathcal A}$ be a set of (variable-free) atoms constructible from ${\mathcal T}$
 - Examples q(42), married(grandfather(leon)), prime(3 + X)
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- Let \mathcal{T} be a set of variable-free terms (also called Herbrand universe)
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$$P = \{ \ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

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$$P = \{ r(a,b) \leftarrow, r(b,c) \leftarrow, t(X,Y) \leftarrow r(X,Y) \}$$

$$\mathcal{T} = \{a,b,c\}$$

$$\mathcal{A} = \begin{cases} r(a,a), r(a,b), r(a,c), r(b,a), r(b,b), r(b,c), r(c,a), r(c,b), r(c,c), \\ t(a,a), t(a,b), t(a,c), t(b,a), t(b,b), t(b,c), t(c,a), t(c,b), t(c,c) \end{cases}$$

$$ground(P) = \begin{cases} r(a,b) \leftarrow, \\ r(b,c) \leftarrow, \\ t(a,a) \leftarrow r(a,a), t(b,a) \leftarrow r(b,a), t(c,a) \leftarrow r(c,a), \\ t(a,b) \leftarrow, t(b,b) \leftarrow r(b,b), t(c,b) \leftarrow r(c,b), \\ t(a,c) \leftarrow r(a,c), t(b,c) \leftarrow r(b,c), t(c,c) \leftarrow r(c,c) \end{cases}$$



Outline

- 9 Ground instantiation
- 10 Stable models
- II Grounding safe programs



Stable models of programs with Variables

- \blacksquare Let P be a normal logic program with variables
- A set X of (ground) atoms is a stable model of P if X is a stable model of ground(P)



Stable models of programs with Variables

- Let P be a normal logic program with variables
- A set X of (ground) atoms is a stable model of P, if X is a stable model of ground(P)



Outline

- 9 Ground instantiation
- 10 Stable models
- 11 Grounding safe programs



- A normal rule is safe, if all its variables occur in its positive body
- Examples
 - $p(a) \leftarrow p(X) \leftarrow p(X) \leftarrow p(X) \leftarrow q(X) \qquad p(X) \leftarrow \neg q(X) \qquad p(X) \leftarrow \neg q(X), r(X)$
 - $p(X) \leftarrow \neg q(X), r(X)$
- A normal program is safe, if all of its rules are safe



- A normal rule is safe, if all its variables occur in its positive body
- Examples

$$\begin{array}{c} \hspace{0.2cm} \hspace{0.$$

A normal program is safe, if all of its rules are safe



- A normal rule is safe, if all its variables occur in its positive body
- Examples

 - $p(X) \leftarrow q(X)$
 - $p(X) \leftarrow \neg q(X)$
- A normal program is safe, if all of its rules are safe



- A normal rule is safe, if all its variables occur in its positive body
- Examples

$$p(a) \leftarrow \checkmark$$

$$p(X) \leftarrow$$

$$p(X) \leftarrow q(X)$$

$$p(X) \leftarrow \neg q(X)$$

$$p(X) \leftarrow \neg q(X), r(X)$$

A normal program is safe, if all of its rules are safe



- A normal rule is safe, if all its variables occur in its positive body
- Examples
 - . $p(a) \leftarrow \checkmark$ $p(X) \leftarrow \checkmark$ $p(X) \leftarrow \checkmark$ $p(X) \leftarrow q(X)$ $p(X) \leftarrow \neg q(X)$ $p(X) \leftarrow \neg q(X), r(X)$
- A normal program is safe, if all of its rules are safe



- A normal rule is safe, if all its variables occur in its positive body
- Examples

$$p(a) \leftarrow \checkmark$$

$$p(X) \leftarrow \checkmark$$

$$p(X) \leftarrow \varphi$$

$$p(X) \leftarrow q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X)$$

$$p(X) \leftarrow \neg q(X), r(X)$$

A normal program is safe, if all of its rules are safe



Safety

- A normal rule is safe, if all its variables occur in its positive body
- Examples

■
$$p(a) \leftarrow \checkmark$$

■ $p(X) \leftarrow \checkmark$
■ $p(X) \leftarrow (A) \checkmark$

A normal program is safe, if all of its rules are safe



Safety

- A normal rule is safe, if all its variables occur in its positive body
- Examples

$$p(a) \leftarrow \checkmark$$

$$p(X) \leftarrow \checkmark$$

$$p(X) \leftarrow q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X), r(X) \checkmark$$

A normal program is safe, if all of its rules are safe



Safety

- A normal rule is safe, if all its variables occur in its positive body
- Examples

$$p(a) \leftarrow \checkmark$$

$$p(X) \leftarrow \checkmark$$

$$p(X) \leftarrow (X) \checkmark$$

$$p(X) \leftarrow q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X) \checkmark$$

$$p(X) \leftarrow \neg q(X), r(X) \checkmark$$

■ A normal program is safe, if all of its rules are safe



$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

- Grounding intuitively
 - Partition program along predicate dependencies

$$P_1 = \{ r(a,b) \leftarrow, r(b,c) \leftarrow \}$$

$$P_2 = \{ t(X,Y) \leftarrow r(X,Y) \}$$

Ground P_1

Rules:
$$\{r(a,b)\leftarrow, r(b,c)\leftarrow\}$$

Atoms: $\{r(a,b),r(b,c)\}$

- Ground P_2 relative to $\{r(a,b),r(b,c)\}$
 - Rules: $\{t(a,b) \leftarrow r(a,b), t(b,c) \leftarrow r(b,c)\}$

Atoms: $\{ r(a, b), r(b, c), t(a, b), t(b, c) \}$

Resulting ground rules

$$\{r(a,b)\leftarrow,\ r(b,c)\leftarrow\}\cup\{t(a,b)\leftarrow r(a,b),\ t(b,c)\leftarrow r(b,c)\}$$



$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

■ Grounding intuitively

Partition program along predicate dependencies

$$P_1 = \{ r(a,b) \leftarrow, r(b,c) \leftarrow P_2 = \{ t(X,Y) \leftarrow r(X,Y) \}$$

- \blacksquare Ground P_1
 - Rules: $\{ r(a,b) \leftarrow, r(b,c) \leftarrow \}$
 - Atoms: $\{r(a,b),r(b,c)\}$
- 2 Ground P_2 relative to $\{r(a,b),r(b,c)\}$
 - Rules: $\{t(a,b) \leftarrow r(a,b), t(b,c) \leftarrow r(b,c)\}$
 - Atoms: $\{r(a,b), r(b,c), t(a,b), t(b,c)\}$
- Resulting ground rules



$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

- Grounding intuitively
 - Partition program along predicate dependencies

■
$$P_1 = \{ r(a, b) \leftarrow, r(b, c) \leftarrow \}$$

■ $P_2 = \{ t(X, Y) \leftarrow r(X, Y) \}$

- \blacksquare Ground P_1
 - Rules: $\{r(a,b)\leftarrow, r(b,c)\leftarrow\}$
 - Atoms: $\{r(a,b), r(b,c)\}$
- \square Ground P_2 relative to $\{r(a,b),r(b,c)\}$
 - Rules: $\{t(a,b) \leftarrow r(a,b), t(b,c) \leftarrow r(b,c)\}$
 - Atoms: $\{r(a, b), r(b, c), t(a, b), t(b, c)\}$
- 3 Resulting ground rules

$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

- Grounding intuitively
 - Partition program along predicate dependencies.

■
$$P_1 = \{ r(a, b) \leftarrow, r(b, c) \leftarrow \}$$

■ $P_2 = \{ t(X, Y) \leftarrow r(X, Y) \}$

- 1 Ground P_1
 - Rules: $\{r(a,b) \leftarrow r(b,c) \leftarrow \}$
 - Atoms: $\{r(a,b), r(b,c)\}$
- Resulting ground rules



$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

- Grounding intuitively
 - Partition program along predicate dependencies

■
$$P_1 = \{ r(a, b) \leftarrow, r(b, c) \leftarrow \}$$

■ $P_2 = \{ t(X, Y) \leftarrow r(X, Y) \}$

- 1 Ground P_1
 - Rules: $\{r(a,b) \leftarrow , r(b,c) \leftarrow \}$
 - Atoms: $\{r(a,b), r(b,c)\}$
- Ground P_2 relative to $\{r(a,b),r(b,c)\}$
 - Rules: $\{t(a,b) \leftarrow r(a,b), t(b,c) \leftarrow r(b,c)\}$
 - Atoms: $\{r(a,b), r(b,c), t(a,b), t(b,c)\}$
- Resulting ground rules



$$\blacksquare P = \{ r(a,b) \leftarrow, \ r(b,c) \leftarrow, \ t(X,Y) \leftarrow r(X,Y) \}$$

- Grounding intuitively
 - O Partition program along predicate dependencies

■
$$P_1 = \{ r(a,b) \leftarrow, r(b,c) \leftarrow \}$$

■ $P_2 = \{ t(X,Y) \leftarrow r(X,Y) \}$

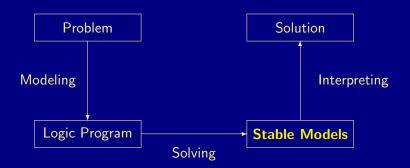
- 1 Ground P_1
 - Rules: $\{r(a,b)\leftarrow, r(b,c)\leftarrow\}$
 - Atoms: $\{r(a, b), r(b, c)\}$
- 2 Ground P_2 relative to $\{r(a,b), r(b,c)\}$
 - Rules: $\{t(a,b) \leftarrow r(a,b), t(b,c) \leftarrow r(b,c)\}$
 - Atoms: $\{r(a,b), r(b,c), t(a,b), t(b,c)\}$
- 3 Resulting ground rules

Solving: Overview

- 12 Conflict-driven constraint learning
- 13 Engine



Reasoning modes





Reasoning modes

- Satisfiability
- Enumeration[†]
- Projection[†]
- Intersection[‡]
- Union[‡]
- Optimization
- and combinations of them

† without solution recording † without solution enumeration



Outline

- 12 Conflict-driven constraint learning
- 13 Engine



Towards conflict-driven search

Boolean constraint solving algorithms pioneered for SAT led to

- Traditional DPLL-style approach
 - (DPLL stands for 'Davis-Putnam-Logemann-Loveland')
 - Unit propagation
 - Backtracking
 - in ASP, eg smodels
- Modern CDCL-style approach

(CDCL stands for 'Conflict-Driven Constraint Learning')

- Unit propagation
- Conflict analysis (via resolution)
- Learning + Backjumping + Assertion
- in ASP, eg clasp



DPLL-style solving

```
loop
                                           // deterministically assign literals
    propagate
    if no conflict then
         if all variables assigned then return solution
         else decide
                                 // non-deterministically assign some literal
    else
         if top-level conflict then return unsatisfiable
         else
              backtrack // unassign literals propagated after last decision
               flip
                               // assign complement of last decision literal
```



CDCL-style solving

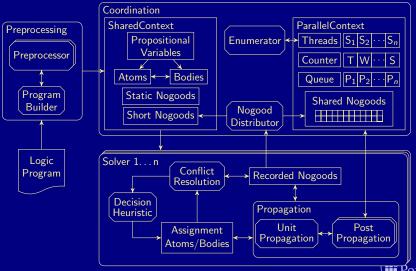
```
loop
                                           // deterministically assign literals
    propagate
    if no conflict then
         if all variables assigned then return solution
         else decide
                                 // non-deterministically assign some literal
    else
         if top-level conflict then return unsatisfiable
         else
                             // analyze conflict and add conflict constraint
               backjump // unassign literals until conflict constraint is unit
```

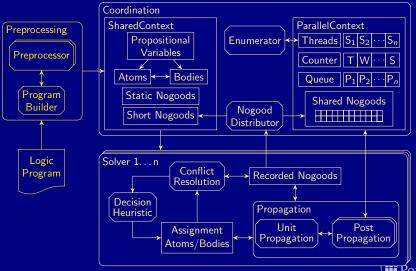


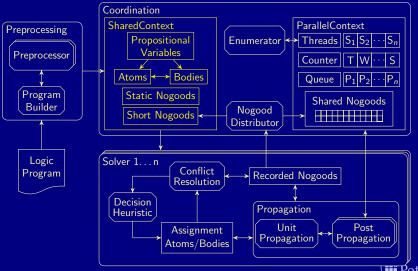
Outline

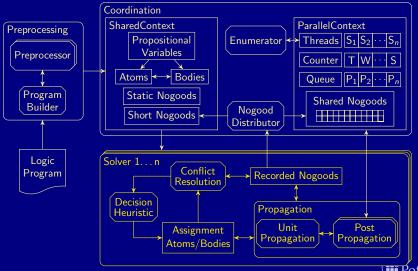
- 12 Conflict-driven constraint learning
- 13 Engine

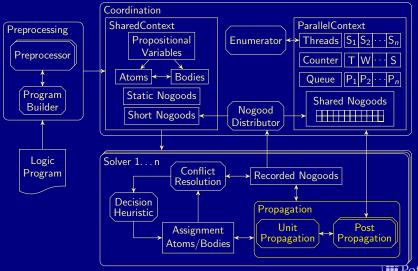


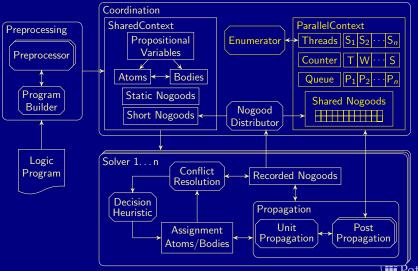










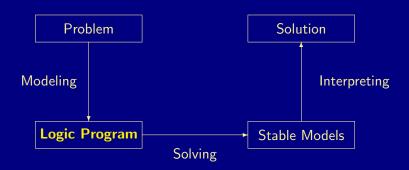


Modeling: Overview

- 14 Elaboration tolerance
- 15 ASP solving process
- 16 Methodology
- 17 Case studies



Extended syntax





```
Potassco
```

```
Facts
                                                                 q(42).
Rules
                                           p(X) := q(X), \text{ not } r(X).
```

```
Facts
                                                           q(42).
Rules
                                    p(42) := q(42), \text{ not } r(42).
                                           p(X) ; q(X) := r(X).
                                                        Potassco
```

```
Facts
                                                            q(42).
Rules
                                        p(X) := q(X), \text{ not } r(X).
Conditional literals
                                               p := q(X) : r(X).
                                                         Potassco
```

```
Facts
                                                                q(42).
Rules
                                           p(X) := q(X), \text{ not } r(X).
Conditional literals
                                                  p := q(X) : r(X).
                                              p(X); q(X) := \underline{r(X)}.
Disjunction
                                                             ( Potassco
```

```
Facts
                                                               q(42).
Rules
                                          p(X) := q(X), \text{ not } r(X).
Conditional literals
                                                 p := q(X) : r(X).
                                             p(X); q(X) := \underline{r(X)}.
Disjunction
                                                     := q(X), p(X).
Integrity constraints
                                                            Potassco
```

```
Facts
                                                          q(42).
Rules
                                       p(X) := q(X), \text{ not } r(X).
Conditional literals
                                             p := q(X) : r(X).
                                          p(X); q(X):- r(X).
Disjunction
                                                 := q(X), p(X).
Integrity constraints
                               2 \{ p(X,Y) : q(X) \} 7 := r(Y).
Choice
                                      :\sim q(X), p(X,C). [C@42]
                                                       Potassco
```

```
Facts
                                                            q(42).
Rules
                                        p(X) := q(X), \text{ not } r(X).
Conditional literals
                                              p := q(X) : r(X).
                                           p(X); q(X) := \underline{r(X)}.
Disjunction
                                                  := q(X), p(X).
Integrity constraints
                                2 \{ p(X,Y) : q(X) \} 7 := r(Y).
Choice
■ Aggregates s(Y) := r(Y), 2 \#sum\{X : p(X,Y), q(X)\} 7.
                                        :\sim q(X), p(X,C). [C@42]
```

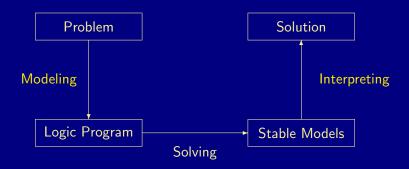
```
Rules
                                       p(X) := q(X), \text{ not } r(X).
                                             p := q(X) : r(X).
Conditional literals
                                          p(X); q(X):- r(X).
Disjunction
                                                := q(X), p(X).
Integrity constraints
                              2 \{ p(X,Y) : q(X) \} 7 : -r(Y).
Choice
■ Aggregates s(Y) := r(Y), 2 \#sum\{X : p(X,Y), q(X)\} 7.
                                      \sim q(X), p(X,C). [C042]
■ Multi-objective optimization
```

Facts

q(42).

- Facts q(42).
- Rules p(X) := q(X), not r(X).
- Conditional literals p := q(X) : r(X).
- Disjunction p(X); q(X):- r(X).
- Integrity constraints :- q(X), p(X). ■ Choice 2 { p(X,Y) : q(X) } 7 :- r(Y).
- Aggregates s(Y) :- r(Y), 2 #sum{ X : p(X,Y), q(X) } 7.
- Multi-objective optimization $:\sim q(X), p(X,C)$. [C@42]
 - #minimize { C@42 : q(X), p(X,C) }

Modeling and Interpreting





Outline

- 14 Elaboration tolerance
- 15 ASP solving process
- 16 Methodology
- 17 Case studies



Guiding principle

■ Elaboration Tolerance (McCarthy, 1998)

"A formalism is elaboration tolerant [if] it is convenient to modify a set of facts expressed in the formalism to take into account new phenomena or changed circumstances."

Uniform problem representation

For solving a problem instance I of a problem class C,

- \blacksquare I is represented as a set of facts P_{I} ,
- **C** is represented as a set of rules P_{C} , and
- \blacksquare $P_{\mathbf{C}}$ can be used to solve all problem instances in \mathbf{C}



Guiding principle

■ Elaboration Tolerance (McCarthy, 1998)

"A formalism is elaboration tolerant [if] it is convenient to modify a set of facts expressed in the formalism to take into account new phenomena or changed circumstances."

■ Uniform problem representation

For solving a problem instance I of a problem class C,

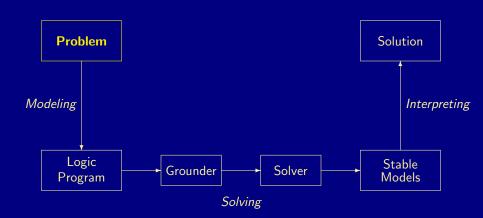
- \blacksquare I is represented as a set of facts P_{I} ,
- **C** is represented as a set of rules $P_{\mathbf{C}}$, and
- \blacksquare $P_{\mathbf{C}}$ can be used to solve all problem instances in \mathbf{C}



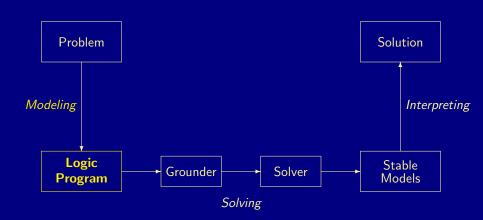
Outline

- 14 Elaboration tolerance
- 15 ASP solving process
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- 17 Case studies

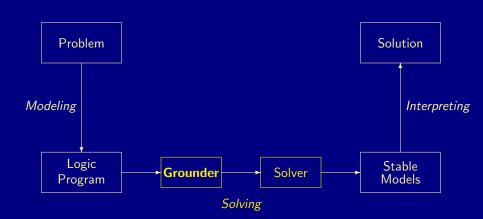




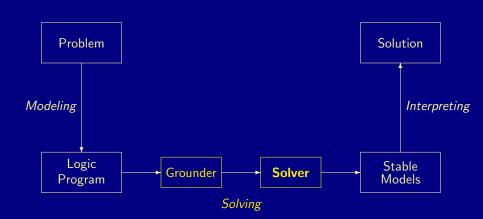




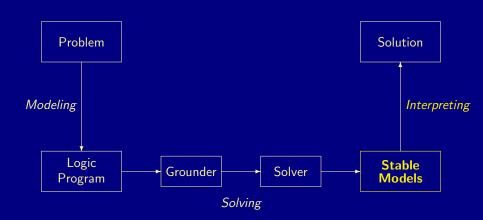




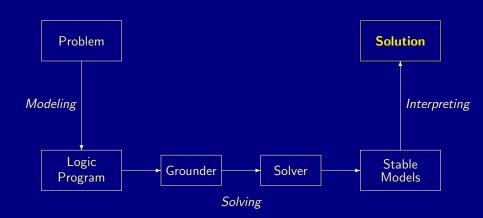




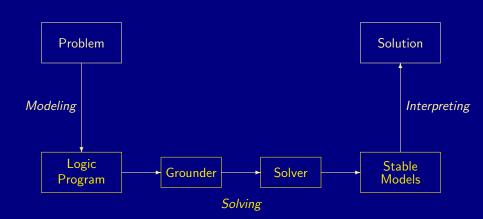




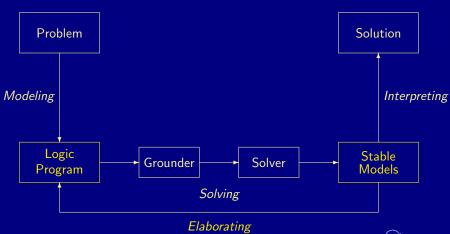


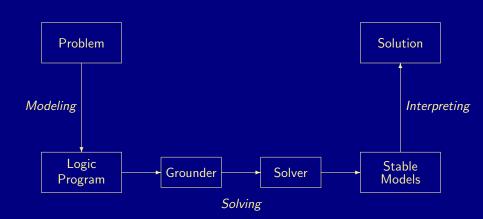






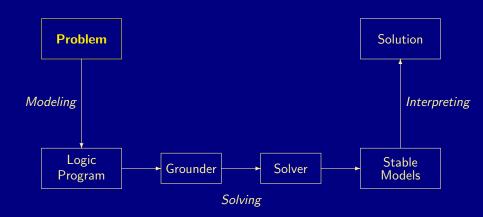








ASP workflow: Problem





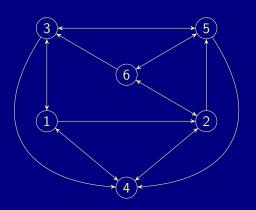
Problem instance A graph consisting of nodes and edges



■ Problem instance A graph consisting of nodes and edges

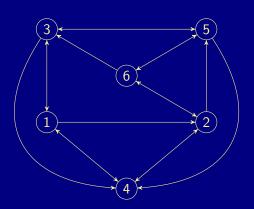


■ Problem instance A graph consisting of nodes and edges





- Problem instance A graph consisting of nodes and edges
 - facts formed by predicates node/1 and edge/2





- Problem instance A graph consisting of nodes and edges
 - facts formed by predicates node/1 and edge/2
 - facts formed by predicate color/1



- Problem instance A graph consisting of nodes and edges
 - facts formed by predicates node/1 and edge/2
 - facts formed by predicate color/1
- Problem class Assign each node one color such that no two nodes connected by an edge have the same color



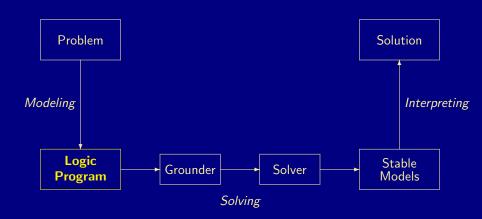
- Problem instance A graph consisting of nodes and edges
 - facts formed by predicates node/1 and edge/2
 - facts formed by predicate color/1
- Problem class Assign each node one color such that no two nodes connected by an edge have the same color

In other words,

- 1 Each node has one color
- 2 Two connected nodes must not have the same color



ASP workflow: Problem representation





Problem instance

Problem encoding
Potassco

```
node(1..6).
```

Problem instance

Problem encoding
Potassco

```
node(1..6).
edge(1,2).
            edge(1,3).
                         edge(1,4).
edge(2,4).
            edge(2,5).
                         edge(2,6).
edge(3,1).
            edge(3,4).
                         edge(3,5).
edge(4,1).
            edge(4,2).
edge(5,3).
            edge(5,4).
                         edge(5,6).
edge(6,2).
            edge(6,3).
                         edge(6,5).
```

Problem nstance

Problem encoding Potassco

```
node(1..6).
edge(1,2).
            edge(1,3).
                         edge(1,4).
edge(2,4).
            edge(2,5).
                         edge(2,6).
edge(3,1).
            edge(3,4).
                         edge(3,5).
edge(4,1).
            edge(4,2).
edge(5,3).
            edge(5,4).
                         edge(5,6).
edge(6,2).
            edge(6,3).
                         edge(6,5).
            color(b).
                         color(g).
color(r).
```

Problem instance

```
{ assign(N,C) : color(C) } = 1 :- node(N).
:- edge(N,M), assign(N,C), assign(M,C).
```

Problem encoding Potassco

```
node(1..6).
edge(1,2).
            edge(1,3).
                         edge(1,4).
edge(2,4).
            edge(2,5).
                         edge(2,6).
edge(3,1).
            edge(3,4).
                         edge(3,5).
                                                Problem
edge(4,1).
            edge(4,2).
                                                instance
            edge(5,4).
edge(5,3).
                         edge(5,6).
edge(6,2).
            edge(6,3).
                         edge(6,5).
                         color(g).
color(r).
            color(b).
```

Potassco

```
edge(1,2).
              edge(1,3).
                             edge(1,4).
edge(2,4).
              edge(2,5).
                             edge(2,6).
edge(3,1).
              edge(3,4).
                             edge(3,5).
                                                        Problem
edge(4,1).
              edge(4,2).
              edge(5,4).
edge(5,3).
                             edge(5,6).
edge(6,2).
              edge(6,3).
                             edge(6,5).
color(r).
            color(b).
                             color(g).
\{ \operatorname{assign}(N,C) : \operatorname{color}(C) \} = 1 :- \operatorname{node}(N).
                                                         (#Potassco
```

node(1..6).

```
edge(1,2).
             edge(1,3).
                            edge(1,4).
edge(2,4).
             edge(2,5).
                            edge(2,6).
edge(3,1).
             edge(3,4).
                            edge(3,5).
                                                     Problem
edge(4,1).
             edge(4,2).
edge(5,3).
             edge(5,4).
                            edge(5,6).
edge(6,2).
             edge(6,3).
                            edge(6,5).
color(r).
           color(b).
                            color(g).
\{ \operatorname{assign}(N,C) : \operatorname{color}(C) \} = 1 :- \operatorname{node}(N).
                                                     Problem
:- edge(N,M), assign(N,C), assign(M,C).
                                                       Potassco
```

node(1..6).

```
node(1..6).
edge(1,2).
              edge(1,3).
                            edge(1,4).
edge(2,4).
              edge(2,5).
                            edge(2,6).
edge(3,1).
             edge(3,4).
                            edge(3,5).
edge(4,1).
             edge(4,2).
edge(5,3).
             edge(5,4).
                            edge(5,6).
edge(6,2).
              edge(6,3).
                            edge(6,5).
color(r).
           color(b).
                            color(g).
\{ \operatorname{assign}(N,C) : \operatorname{color}(C) \} = 1 :- \operatorname{node}(N).
```

:- edge(N,M), assign(N,C), assign(M,C).

Problem nstance

Problem encoding Potassco

```
node(1..6).
edge(1,2).
              edge(1,3).
                            edge(1,4).
edge(2,4). edge(2,5).
                            edge(2,6).
edge(3,1). edge(3,4).
                            edge(3,5).
edge(4,1). edge(4,2).
edge(5,3). edge(5,4).
                            edge(5,6).
edge(6,2). edge(6,3).
                            edge(6,5).
color(r). color(b). color(g).
\{ \operatorname{assign}(N,C) : \operatorname{color}(C) \} = 1 :- \operatorname{node}(N).
```

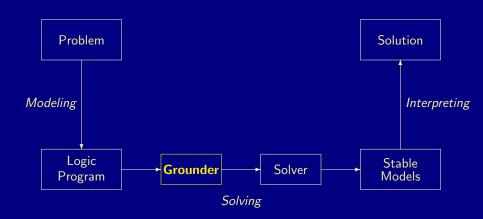
Problem instance

Problem encoding Potassco

:- edge(N,M), assign(N,C), assign(M,C).

```
node(1..6).
edge(1,2).
             edge(1,3).
                           edge(1,4).
edge(2,4). edge(2,5).
                           edge(2,6).
edge(3,1). edge(3,4).
                           edge(3,5).
                                                    graph.lp
edge(4,1). edge(4,2).
edge(5,3). edge(5,4).
                           edge(5,6).
edge(6,2). edge(6,3).
                           edge(6,5).
color(r). color(b). color(g).
\{ \operatorname{assign}(N,C) : \operatorname{color}(C) \} = 1 :- \operatorname{node}(N).
                                                    color.lp
:- edge(N,M), assign(N,C), assign(M,C).
                                                        Potassco
```

ASP workflow: Grounding





Graph coloring: Grounding

```
$ gringo --text graph.lp color.lp
                                                   :- assign(6,g) Potassco
```

Graph coloring: Grounding

```
$ gringo --text graph.lp color.lp
                   node(3). node(4). node(5).
node(1).
         node(2).
                                                 node(6).
edge(1,2).
            edge(2,4).
                       edge(3,1).
                                                           edge(6,2).
                                    edge(4,1).
                                               edge(5,3).
edge(1,3).
           edge(2,5).
                       edge(3,4).
                                   edge(4,2).
                                               edge(5,4).
                                                           edge(6,3).
edge(1,4).
            edge(2,6).
                       edge(3,5).
                                               edge(5,6).
                                                           edge(6,5).
color(r).
          color(b).
                     color(g).
                                                               :- assign(6,g) Potassco
```

Graph coloring: Grounding

```
$ gringo --text graph.lp color.lp
                    node(3). node(4). node(5).
node(1). node(2).
                                                  node(6).
edge(1,2).
            edge(2,4).
                        edge(3,1).
                                                             edge(6,2).
                                    edge(4,1).
                                                 edge(5,3).
edge(1,3).
            edge(2,5).
                        edge(3,4).
                                    edge(4,2).
                                                 edge(5,4).
                                                             edge(6,3).
edge(1,4).
            edge(2,6).
                        edge(3,5).
                                                 edge(5,6).
                                                             edge(6,5).
color(r).
           color(b).
                      color(g).
\{assign(1,r); assign(1,b); assign(1,g)\} = 1. \{assign(4,r); assign(4,b); assign(4,g)\} = 1.
\{assign(2,r); assign(2,b); assign(2,g)\} = 1. \{assign(5,r); assign(5,b); assign(5,g)\} = 1.
\{assign(3,r); assign(3,b); assign(3,g)\} = 1. \{assign(6,r); assign(6,b); assign(6,g)\} = 1.
                                                                 :- assign(6,g) Potassco
```

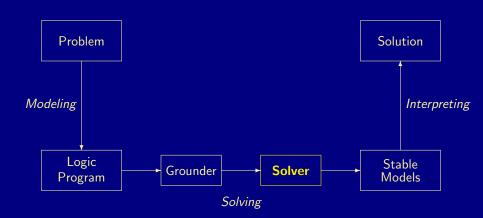
Graph coloring: Grounding

```
$ gringo --text graph.lp color.lp
node(1). node(2). node(3). node(4). node(5). node(6).
edge(1,2).
            edge(2,4).
                        edge(3,1).
                                                 edge(5,3).
                                                              edge(6,2).
                                     edge(4,1).
edge(1,3).
            edge(2,5).
                        edge(3,4).
                                     edge(4,2).
                                                 edge(5,4).
                                                              edge(6,3).
edge(1,4).
            edge(2,6).
                        edge(3,5).
                                                 edge(5,6).
                                                              edge(6,5).
color(r). color(b). color(g).
\{assign(1,r); assign(1,b); assign(1,g)\} = 1. \{assign(4,r); assign(4,b); assign(4,g)\} = 1.
\{assign(2,r); assign(2,b); assign(2,g)\} = 1. \{assign(5,r); assign(5,b); assign(5,g)\} = 1.
\{assign(3,r); assign(3,b); assign(3,g)\} = 1. \{assign(6,r); assign(6,b); assign(6,g)\} = 1.
:- assign(1,r), assign(2,r).
                              :- assign(2,r), assign(4,r). [...]
                                                                  :- assign(6,r), assign(2,r).
:- assign(1,b), assign(2,b).
                              :- assign(2,b), assign(4,b).
                                                                  :- assign(6,b), assign(2,b).
:- assign(1,g), assign(2,g).
                              :- assign(2,g), assign(4,g).
                                                                  :- assign(6,g), assign(2,g).
                                                                  :- assign(6,r), assign(3,r).
:- assign(1,r), assign(3,r).
                              :- assign(2.r), assign(5.r).
:- assign(1,b), assign(3,b).
                              :- assign(2,b), assign(5,b).
                                                                  :- assign(6,b), assign(3,b).
:- assign(1,g), assign(3,g).
                              :- assign(2,g), assign(5,g).
                                                                  :- assign(6,g), assign(3,g).
:- assign(1.r), assign(4.r).
                              :- assign(2.r), assign(6.r).
                                                                  :- assign(6,r), assign(5,r).
:- assign(1,b), assign(4,b).
                              :- assign(2,b), assign(6,b).
                                                                  :- assign(6,b), assign(5,b).
:- assign(1,g), assign(4,g).
                              :- assign(2,g), assign(6,g).
                                                                  :- assign(6,g) Potassco
```

Graph coloring: Grounding

```
$ clingo --text graph.lp color.lp
node(1). node(2). node(3). node(4). node(5). node(6).
edge(1,2).
            edge(2,4).
                        edge(3,1).
                                                 edge(5,3).
                                                              edge(6,2).
                                     edge(4,1).
edge(1,3).
            edge(2,5).
                        edge(3,4).
                                     edge(4,2).
                                                 edge(5,4).
                                                              edge(6,3).
edge(1,4).
            edge(2,6).
                        edge(3,5).
                                                 edge(5,6).
                                                              edge(6,5).
color(r). color(b). color(g).
\{assign(1,r); assign(1,b); assign(1,g)\} = 1. \{assign(4,r); assign(4,b); assign(4,g)\} = 1.
\{assign(2,r); assign(2,b); assign(2,g)\} = 1. \{assign(5,r); assign(5,b); assign(5,g)\} = 1.
\{assign(3,r); assign(3,b); assign(3,g)\} = 1. \{assign(6,r); assign(6,b); assign(6,g)\} = 1.
:- assign(1,r), assign(2,r).
                              :- assign(2,r), assign(4,r). [...]
                                                                  :- assign(6,r), assign(2,r).
:- assign(1,b), assign(2,b).
                              :- assign(2,b), assign(4,b).
                                                                  :- assign(6,b), assign(2,b).
:- assign(1,g), assign(2,g).
                              :- assign(2,g), assign(4,g).
                                                                  :- assign(6,g), assign(2,g).
                                                                  :- assign(6,r), assign(3,r).
:- assign(1,r), assign(3,r).
                              :- assign(2.r), assign(5.r).
:- assign(1,b), assign(3,b).
                              :- assign(2,b), assign(5,b).
                                                                  :- assign(6,b), assign(3,b).
:- assign(1,g), assign(3,g).
                              :- assign(2,g), assign(5,g).
                                                                  :- assign(6,g), assign(3,g).
:- assign(1.r), assign(4.r).
                              :- assign(2.r), assign(6.r).
                                                                  :- assign(6,r), assign(5,r).
:- assign(1,b), assign(4,b).
                              :- assign(2,b), assign(6,b).
                                                                  :- assign(6,b), assign(5,b).
:- assign(1,g), assign(4,g).
                              :- assign(2,g), assign(6,g).
                                                                  :- assign(6,g) Potassco
```

ASP workflow: Solving





Graph coloring: Solving

\$ gringo graph.lp color.lp | clasp 0

Models : 6

Time : 0.002s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)



Graph coloring: Solving

\$ gringo graph.lp color.lp | clasp 0

```
clasp version 2.1.0
Reading from stdin
Solving...
Answer: 1
node(1) [...] assign(6,b) assign(5,g) assign(4,b) assign(3,r) assign(2,r) assign(1,g)
Answer: 2
node(1) [...] assign(6,r) assign(5,g) assign(4,r) assign(3,b) assign(2,b) assign(1,g)
Answer: 3
node(1) [...] assign(6,g) assign(5,b) assign(4,g) assign(3,r) assign(2,r) assign(1,b)
Answer: 4
node(1) [...] assign(6,r) assign(5,b) assign(4,r) assign(3,g) assign(2,g) assign(1,b)
Answer: 5
node(1) [...] assign(6,g) assign(5,r) assign(4,g) assign(3,b) assign(2,b) assign(1,r)
Answer: 6
node(1) [...] assign(6,b) assign(5,r) assign(4,b) assign(3,g) assign(2,g) assign(1,r)
SATISFIABLE
```

Models : 6

Time : 0.002s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)



Graph coloring: Solving

```
$ clingo graph.lp color.lp 0
```

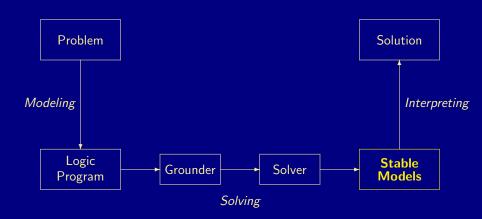
```
clasp version 2.1.0
Reading from stdin
Solving...
Answer: 1
node(1) [...] assign(6,b) assign(5,g) assign(4,b) assign(3,r) assign(2,r) assign(1,g)
Answer: 2
node(1) [...] assign(6,r) assign(5,g) assign(4,r) assign(3,b) assign(2,b) assign(1,g)
Answer: 3
node(1) [...] assign(6,g) assign(5,b) assign(4,g) assign(3,r) assign(2,r) assign(1,b)
Answer: 4
node(1) [...] assign(6,r) assign(5,b) assign(4,r) assign(3,g) assign(2,g) assign(1,b)
Answer: 5
node(1) [...] assign(6,g) assign(5,r) assign(4,g) assign(3,b) assign(2,b) assign(1,r)
Answer: 6
node(1) [...] assign(6,b) assign(5,r) assign(4,b) assign(3,g) assign(2,g) assign(1,r)
SATISFIABLE
```

Models : 6

Time : 0.002s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)



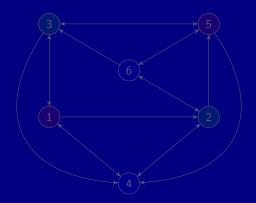
ASP workflow: Stable models





A coloring

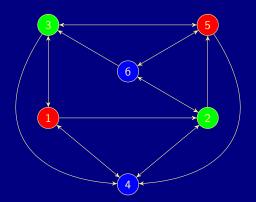
```
Answer: 6
node(1) [...] \
assign(6,b) assign(5,r) assign(4,b) assign(3,g) assign(2,g) assign(1,r)
```





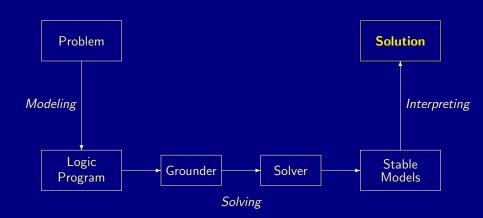
A coloring

```
Answer: 6
node(1) [...] \
assign(6,b) assign(5,r) assign(4,b) assign(3,g) assign(2,g) assign(1,r)
```





ASP workflow: Solutions





Outline

- 14 Elaboration tolerance
- 15 ASP solving process
- 16 Methodology
- 17 Case studies



Basic methodology

Methodology

Generate and Test (or: Guess and Check)

```
Generator Generate potential stable model candidates (typically through non-deterministic constructs)
```

Tester Eliminate invalid candidates (typically through integrity constraints)

Nutshell

Logic program = Data + Generator + Tester (+ Optimizer)



Basic methodology

Methodology

Generate and Test (or: Guess and Check)

Generator Generate potential stable model candidates (typically through non-deterministic constructs)

Tester Eliminate invalid candidates (typically through integrity constraints)

Nutshell

Logic program = Data + Generator + Tester (+ Optimizer)



Graph coloring

```
node(1..6).
edge(1,2).
           edge(1,3).
                       edge(1,4).
edge(2,4). edge(2,5). edge(2,6).
edge(3,1). edge(3,4). edge(3,5).
edge(4,1). edge(4,2).
edge(5,3). edge(5,4). edge(5,6).
edge(6,2). edge(6,3). edge(6,5).
color(r). color(b). color(g).
\{ assign(N,C) : color(C) \} = 1 :- node(N).
```

:- edge(N,M), assign(N,C), assign(M,C).

Problem instance

Problem encoding Potassco

Graph coloring

```
node(1..6).
edge(1,2).
           edge(1,3).
                      edge(1,4).
edge(2,4). edge(2,5). edge(2,6).
edge(3,1). edge(3,4). edge(3,5).
                                             Data
edge(4,1). edge(4,2).
edge(5,3). edge(5,4). edge(5,6).
edge(6,2). edge(6,3). edge(6,5).
color(r). color(b). color(g).
\{ assign(N,C) : color(C) \} = 1 :- node(N).
```

Problem encoding Potassco

:- edge(N,M), assign(N,C), assign(M,C).

Graph coloring

```
node(1..6).
edge(1,2).
           edge(1,3).
                       edge(1,4).
edge(2,4). edge(2,5). edge(2,6).
edge(3,1). edge(3,4). edge(3,5).
                                             Data
edge(4,1). edge(4,2).
edge(5,3). edge(5,4). edge(5,6).
edge(6,2). edge(6,3). edge(6,5).
color(r). color(b). color(g).
\{ assign(N,C) : color(C) \} = 1 :- node(N).
                                             Generator
:- edge(N,M), assign(N,C), assign(M,C).
```

Outline

- 14 Elaboration tolerance
- 15 ASP solving process
- 16 Methodology
- 17 Case studies



Outline

- 14 Elaboration tolerance
- 15 ASP solving process
- 16 Methodology
- 17 Case studies
 - Satisfiability
 - Queens
 - Traveling salespersor
 - Reviewer Assignment
 - Planning



- lacktriangle Problem Instance A propositional formula ϕ in CNF
- Problem Class Is there an assignment of propositional variables to true and false such that a given formula ϕ is true
- Example Consider formula

$$(a \lor \neg b) \land (\neg a \lor b)$$

■ Logic Program

Generator	Tester	Stable models
{a}.	:- not a, b.	$X_1 = \{a,b\}$
{b}.	:- a, not b.	$X_2 = \{\}$

Note The generator puts a and b under the open world assumption

The tester eliminates interpretations; it is expressed negatively

- lacktriangle Problem Instance A propositional formula ϕ in CNF
- Problem Class Is there an assignment of propositional variables to true and false such that a given formula ϕ is true
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Generator	Tester	Stable models
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Generator	Tester	Stable models
{a}.	:- not a, b.	$X_1 = \{a,b\}$
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The tester eliminates interpretations; it is expressed negatively

- lacktriangle Problem Instance A propositional formula ϕ in CNF
- Problem Class Is there an assignment of propositional variables to true and false such that a given formula ϕ is true
- Example Consider formula

$$\neg(\neg a \land b) \land \neg(a \land \neg b)$$

■ Logic Program

Generator	Tester	Stable models
{a}.	:- not a, b.	$X_1 = \{a,b\}$
{b}.	:- a, not b.	$X_2 = \{\}$

■ Note The generator puts a and b under the open world assumption

The tester eliminates interpretations; it is expressed negatively

- lacktriangle Problem Instance A propositional formula ϕ in CNF
- Problem Class Is there an assignment of propositional variables to true and false such that a given formula ϕ is true
- Example Consider formula

$$(\neg a \land b \rightarrow \bot) \land (a \land \neg b \rightarrow \bot)$$

■ Logic Program

Generator	Tester	Stable models
{a}.	:- not a, b.	$X_1 = \{a,b\}$
{b}.	:- a, not b.	$X_2 = \{\}$

■ Note The generator puts a and b under the open world assumption

The tester eliminates interpretations; it is expressed negatively

Outline

- 14 Elaboration tolerance
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 - Reviewer Assignment
 - Planning



Defining the field

```
queens.lp
```

```
\operatorname{row}(1..n).
```

- Define the field
 - n rows
 - n columns



Defining the field

queens.lp

```
row(1..n). col(1..n).
```

- Define the field
 - n rows
 - n columns



Defining the field

```
Running ...
```

Time

```
$ clingo queens.lp --const n=5
Answer: 1
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5)
SATISFIABLE
Models
```

: 0.000



```
row(1..n).
col(1..n).
{ queen(I,J) : row(I), col(J) }.
```

by placing some queens on the board



queens.lp

```
row(1..n).
col(1..n).
{ queen(I,J) : row(I), col(J) }.
```

→ Guess a solution candidateby placing some queens on the board

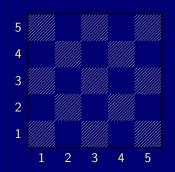


queens.lp

```
Running ...
$ clingo queens.lp --const n=5 3
Answer: 1
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5)
Answer: 2
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5) queen(1,1)
Answer: 3
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5) queen(2,1)
SATISFIABLE
```

Models : 3+

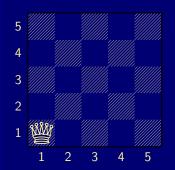
Answer: 1



```
Answer: 1
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5)
```



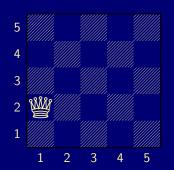
Answer: 2



```
Answer: 2
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(1,1)
```



Answer: 3



```
Answer: 3
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(2,1)
```



Placing n queens

```
queens.lp

row(1..n).
col(1..n).
{ queen(I,J) : row(I), col(J) }.
:- { queen(I,J) } != n.
```

→ Place exactly n queens on the board



Placing *n* queens

```
queens.lp
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
```

➡ Place exactly n queens on the board



Placing *n* queens directly

```
queens.lp
row(1..n).
col(1..n).
{ queen(I,J) : row(I), col(J) } = n.
```

ightharpoonup Place exactly n queens on the board



Placing *n* queens

```
Running ...
```

```
$ clingo queens.lp --const n=5 2
Answer: 1
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5) 
queen(5,1) queen(4,1) queen(3,1) queen(2,1) queen(1,1)
Answer: 2
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) 
queen(1,2) queen(4,1) queen(3,1) queen(2,1) queen(1,1)
```



Placing *n* queens

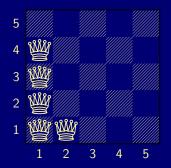
Answer: 1

```
Answer: 1
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(5,1) queen(4,1) queen(3,1) \
queen(2,1) queen(1,1)
```



Placing *n* queens

Answer: 2



```
Answer: 2
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(1,2) queen(4,1) queen(3,1) \
queen(2,1) queen(1,1)
```



```
queens.lp
```

```
row(1..n).
col(1..n).
{ queen(I,J) : row(I), col(J) }.
:- { queen(I,J) } != n.
:- queen(I,J), queen(I,J'), J != J'.
:- queen(I,J), queen(I',J), I != I'.
```

Forbid horizontal and vertical attacks



Queens

```
queens.lp
```

```
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
:- queen(I,J), queen(I,J), J != J.
:- queen(I, J), queen(I', J), I != I'.
```

Forbid horizontal and vertical attacks

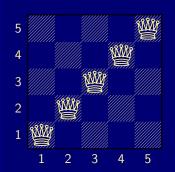


```
Running ...
```

```
$ clingo queens.lp --const n=5
Answer: 1
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5) 
queen(5,5) queen(4,4) queen(3,3) queen(2,2) queen(1,1)
```



Answer: 1



```
Answer: 1
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(5,5) queen(4,4) queen(3,3) \
queen(2,2) queen(1,1)
```



```
queens.lp
```

```
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
:- queen(I,J), queen(I,J'), J != J'.
:- queen(I,J), queen(I',J), I != I'.
```

Forbid diagonal attacks



```
queens.lp
```

```
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
:- queen(I,J), queen(I,J'), J != J'.
:- queen(I,J), queen(I',J), I != I'.
:- queen(I,J), queen(I',J'), (I,J) != (I',J'), I-J == I'-J'.
:- queen(I,J), queen(I',J'), (I,J) != (I',J'), I+J == I'+J'.
```

Forbid diagonal attacks

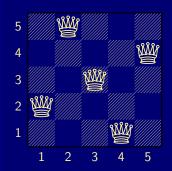


```
Running ...
```

```
$ clingo queens.lp --const n=5
Answer: 1
row(1) row(2) row(3) row(4) row(5) 
col(1) col(2) col(3) col(4) col(5) 
queen(4,5) queen(1,4) queen(3,3) queen(5,2) queen(2,1)
SATISFIABLE
Models : 1+
        : 0.000
Time
```



Answer: 1



```
Answer: 1
row(1) row(2) row(3) row(4) row(5) \
col(1) col(2) col(3) col(4) col(5) \
queen(4,5) queen(1,4) queen(3,3) \
queen(5,2) queen(2,1)
```



Optimizing

```
queens.lp
```

```
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
:- queen(I,J), queen(I,J'), J != J'.
:- queen(I,J), queen(I',J), I != I'.
:- queen(I,J), queen(I',J'), (I,J) != (I',J'), I-J == I'-J'.
:- queen([I,J], queen([I',J']), ([I,J])!= ([I',J']), [I+J]== [I'+J'].
```



Optimizing

```
queens.lp
```

```
row(1..n).
col(1..n).
\{ queen(I,J) : row(I), col(J) \}.
:- \{ queen(I,J) \} != n.
:- queen(I,J), queen(I,J'), J != J'.
:- queen(I,J), queen(I',J), <u>I != I'.</u>
:- queen(I,J), queen(I',J'), (I,J) != (I',J'), I-J == I'-J'.
:- queen([I,J], queen([I',J']), ([I,J])!= ([I',J']), [I+J]== [I'+J'].
```

- Encoding can be optimized
- Much faster to solve



Optimizing

```
queens-opt.lp
```

```
{ queen(I,1..n) } = 1 :- I = 1..n.
{ queen(1..n,J) } = 1 :- J = 1..n.
:- { queen(D-J,J) } > 1, D = 2..2*n.
:- { queen(D+J,J) } > 1, D = 1-n..n-1.
```

- Encoding can be optimized
- Much faster to solve



And sometimes it rocks

$\$ clingo -c n=5000 queens-opt-diag.lp --config=jumpy -q --stats=2



And sometimes it rocks

```
$ clingo -c n=5000 queens-opt-diag.lp --config=jumpy -q --stats=2
clingo version 4.1.0
Solving...
SATISFIARLE
Models
            : 1+
            : 3758.143s (Solving: 1905.22s 1st Model: 1896.20s Unsat: 0.00s)
Time
CPU Time
           : 3758.320s
Choices
            · 288594554
Conflicts
           : 3442
                     (Analyzed: 3442)
Restarts
                     (Average: 202.47 Last: 3442)
Model-Level : 7594728.0
Problems
                     (Average Length: 0.00 Splits: 0)
Lemmas
           . 3442
                    (Deleted: 0)
 Binary
                     (Ratio: 0.00%)
 Ternary
                     (Ratio: 0.00%)
 Conflict
           : 3442
                     (Average Length: 229056.5 Ratio: 100.00%)
                     (Average Length: 0.0 Ratio:
 Loop
                                                    0.00%)
 Other
                     (Average Length: 0.0 Ratio: 0.00%)
            : 75084857 (Original: 75069989 Auxiliary: 14868)
Atoms
Rules
            : 100129956 (1: 50059992/100090100 2: 39990/29856 3: 10000/10000)
Bodies
            : 25090103
Equivalences: 125029999 (Atom=Atom: 50009999 Body=Body: 0 Other: 75020000)
Tight
            : Yes
Variables
            : 25024868 (Eliminated: 11781 Frozen: 25000000)
Constraints : 66664 (Binary: 35.6% Ternary: 0.0% Other: 64.4%)
Backiumps
            : 3442
                     (Average: 681.19 Max: 169512 Sum: 2344658)
                     (Average: 681.19 Max: 169512 Sum: 2344658 Ratio: 100.00%)
 Executed
            : 3442
                     (Average: 0.00 Max: 0 Sum: 0 Ratio: 0.00%)
 Bounded
```



Outline

- Elaboration tolerance
- 15 ASP solving process
- Methodology
- Case studies

 - Queens
 - Traveling salesperson



The traveling salesperson problem (TSP)

- Problem Instance A set of cities and distances among them, or simply a weighted graph
- Problem Class What is the shortest possible route visiting each city once and returning to the city of origin?

Note

- TSP extends the Hamiltonian cycle problem:Is there a cycle in a graph visiting each node exactly once
- TSP is relevant to applications in logistics, planning, chip design, and the core of the vehicle routing problem



The traveling salesperson problem (TSP)

- Problem Instance A set of cities and distances among them, or simply a weighted graph
- Problem Class What is the shortest possible route visiting each city once and returning to the city of origin?
- Note
 - TSP extends the Hamiltonian cycle problem: Is there a cycle in a graph visiting each node exactly once
 - TSP is relevant to applications in logistics, planning, chip design, and the core of the vehicle routing problem



Problem instance, cities.lp

```
start(a).
city(a). city(b). city(c). city(d).
road(a,b,10). road(b,c,20). road(c,d,25). road(d,a,40).
road(b,d,30). road(d,c,25). road(c,a,35).
```



Problem encoding, tsp.1p

```
\{ travel(X,Y) \} := road(X,Y,_).
visited(Y) :- travel(X,Y), start(X).
visited(Y) :- travel(X,Y), visited(X).
:- city(X), not visited(X).
:- city(X), 2 { travel(X,Y) }.
:- city(X), 2 { travel(Y,X) }.
```



Problem encoding, tsp.1p

```
\{ travel(X,Y) \} := road(X,Y,_).
visited(Y) :- travel(X,Y), start(X).
visited(Y) :- travel(X,Y), visited(X).
:- city(X), not visited(X).
:- city(X), 2 { travel(X,Y) }.
:- city(X), 2 { travel(Y,X) }.
: ^{\prime} travel(X,Y), road(X,Y,D). [D,X,Y]
```



Problem encoding, tsp.1p

```
\{ travel(X,Y) \} := road(X,Y,_).
visited(Y) :- travel(X,Y), start(X).
visited(Y) :- travel(X,Y), visited(X).
:- city(X), not visited(X).
:- city(X), 2 { travel(X,Y) }.
:- city(X), 2 { travel(Y,X) }.
#minimize { D,X,Y : travel(X,Y), road(X,Y,D) }.
```



```
$ clingo tsp.lp cities.lp
```

```
$ clingo tsp.lp cities.lp
clingo version 5.3.1
Reading . . .
Solving...
```

```
$ clingo tsp.lp cities.lp
clingo version 5.3.1
Reading . . .
Solving ...
Answer: 1
start(a) [...] road(c.a.35)
travel(a.b) travel(b.d) travel(d.c) travel(c.a)
visited(b) visited(c) visited(d) visited(a)
Optimization: 100
```

```
$ clingo tsp.lp cities.lp
clingo version 5.3.1
Reading . . .
Solving ...
Answer: 1
start(a) [...] road(c.a.35)
travel(a.b) travel(b.d) travel(d.c) travel(c.a)
visited(b) visited(c) visited(d) visited(a)
Optimization: 100
Answer: 2
start(a) [...] road(c,a,35)
travel(a,b) travel(b,c) travel(c,d) travel(d,a)
visited(b) visited(c) visited(d) visited(a)
Optimization: 95
```

```
$ clingo tsp.lp cities.lp
clingo version 5.3.1
Reading . . .
Solving ...
Answer: 1
start(a) [...] road(c.a.35)
travel(a.b) travel(b.d) travel(d.c) travel(c.a)
visited(b) visited(c) visited(d) visited(a)
Optimization: 100
Answer: 2
start(a) [...] road(c,a,35)
travel(a,b) travel(b,c) travel(c,d) travel(d,a)
visited(b) visited(c) visited(d) visited(a)
Optimization: 95
OPTIMUM FOUND
Models
  Optimum : yes
Optimization: 95
Calls
Time : 0.005s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
CPU Time : 0.002s
```

Alternative problem encoding

```
\{ travel(X,Y) : road(X,Y,_) \} = 1 :- city(X).
\{ travel(X,Y) : road(X,Y,_) \} = 1 :- city(Y).
visited(Y) := travel(X,Y), start(X).
visited(Y) :- travel(X,Y), visited(X).
:- city(X), not visited(X).
#minimize { D,X,Y : travel(X,Y), road(X,Y,D) }.
```



Outline

- Elaboration tolerance
- 15 ASP solving process
- Methodology
- Case studies

 - Queens

 - Reviewer Assignment



- Problem Instance A set of papers and a set of reviewers along with their first and second choices of papers and conflict of interests
- Problem Class A nice assignment of three reviewers to each paper



- Problem Instance A set of papers and a set of reviewers along with their first and second choices of papers and conflict of interests
- Problem Class A "nice" assignment of three reviewers to each paper



by Ilkka Niemelä

```
paper(p1).
            reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[\ldots]
```



by Ilkka Niemelä

```
paper(p1).
            reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[\ldots]
\{ assigned(P,R) : reviewer(R) \} = 3 :- paper(P).
```



by Ilkka Niemelä

```
paper(p1). reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[\ldots]
{ assigned(P,R) : reviewer(R) } = 3 :- paper(P).
 :- assigned(P,R), coi(R,P).
 :- assigned(P,R), not classA(R,P), not classB(R,P).
 :- not 6 { assigned(P,R) : paper(P) } 9, reviewer(R).
```



```
paper(p1). reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[\ldots]
{ assigned(P,R) : reviewer(R) } = 3 :- paper(P).
 :- assigned(P,R), coi(R,P).
 :- assigned(P,R), not classA(R,P), not classB(R,P).
 :- not 6 { assigned(P,R) : paper(P) } 9, reviewer(R).
assignedB(P,R) := classB(R,P), assigned(P,R).
 :- 3 { assignedB(P,R) : paper(P) }, reviewer(R).
```



```
paper(p1). reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[\ldots]
{ assigned(P,R) : reviewer(R) } = 3 :- paper(P).
 :- assigned(P,R), coi(R,P).
 :- assigned(P,R), not classA(R,P), not classB(R,P).
 :- not 6 { assigned(P,R) : paper(P) } 9, reviewer(R).
assignedB(P,R) := classB(R,P), assigned(P,R).
 :- 3 { assignedB(P,R) : paper(P) }, reviewer(R).
#minimize { 1,P,R : assignedB(P,R), paper(P), reviewer(R) }.
```



```
paper(p1). reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[...]
\#count { P,R : assigned(P,R) : reviewer(R) } = 3 :- paper(P).
 :- assigned(P,R), coi(R,P).
 :- assigned(P,R), not classA(R,P), not classB(R,P).
 :- not 6 <= #count { P,R : assigned(P,R), paper(P) } <= 9, reviewer(R).
assignedB(P,R) := classB(R,P), assigned(P,R).
 :- 3 <= #count { P,R : assignedB(P,R), paper(P) }, reviewer(R).
#minimize { 1,P,R : assignedB(P,R), paper(P), reviewer(R) }.
```



```
paper(p1). reviewer(r1). classA(r1,p1). classB(r1,p2). coi(r1,p3).
paper(p2). reviewer(r2). classA(r2,p3). classB(r2,p4). coi(r2,p6).
[...]
#count { P,R : assigned(P,R) : reviewer(R) } = 3 :- paper(P).
 :- assigned(P,R), coi(R,P).
 :- assigned(P,R), not classA(R,P), not classB(R,P).
 :- not 6 <= #count { P,R : assigned(P,R), paper(P) } <= 9, reviewer(R).
assignedB(P,R) := classB(R,P), assigned(P,R).
 :- 3 <= #count { P,R : assignedB(P,R), paper(P) }, reviewer(R).
#minimize { 1,P,R : assignedB(P,R), paper(P), reviewer(R) }.
```



Planning

Outline

- Elaboration tolerance
- 15 ASP solving process
- Methodology
- Case studies

 - Queens

 - **Planning**



Simplified STRIPS¹ Planning

- from the initial state to the goal state

$$\mathsf{plan} \ \langle a,b \rangle \qquad \{p,\neg q,\neg r\} \overset{a}{\longrightarrow} \{\neg p,q,\neg r\} \overset{b}{\longrightarrow} \{\neg p,\neg q,r\}$$





Simplified STRIPS Planning

- Problem Instance
 - set of fluents
 - initial and goal state
 - set of actions, consisting of pre- and postconditions
 - \blacksquare number k of allowed actions
- \blacksquare Problem Class Find a plan, that is, a sequence of k actions leading from the initial state to the goal state

plan
$$\langle a,b \rangle$$
 $\{p,\neg q,\neg r\} \stackrel{a}{\longrightarrow} \{\neg p,q,\neg r\} \stackrel{b}{\longrightarrow} \{\neg p,\neg q,r\}$



Simplified STRIPS Planning

- Problem Instance
 - set of fluents
 - initial and goal state
 - set of actions, consisting of pre- and postconditions
 - \blacksquare number k of allowed actions
- \blacksquare Problem Class Find a plan, that is, a sequence of k actions leading from the initial state to the goal state
- Example
 - \blacksquare fluents $\{p, q, r\}$
 - initial state $\{p, \neg q, \neg r\}$
 - \blacksquare goal state $\{r\}$
 - \blacksquare actions $a = (\{p\}, \{q, \neg p\})$ and $b = (\{q\}, \{r, \neg q\})$
 - length 2

Simplified STRIPS Planning

- Problem Instance
 - set of fluents
 - initial and goal state
 - set of actions, consisting of pre- and postconditions
 - \blacksquare number k of allowed actions
- \blacksquare Problem Class Find a plan, that is, a sequence of k actions leading from the initial state to the goal state
- Example
 - \blacksquare fluents $\{p, q, r\}$
 - initial state $\{p, \neg q, \neg r\}$
 - \blacksquare goal state $\{r\}$
 - \blacksquare actions $a = (\{p\}, \{q, \neg p\})$ and $b = (\{q\}, \{r, \neg q\})$
 - length 2

Problem instance

```
\begin{array}{lll} \text{time}\,(1\,.\,\,k)\,. \\ \\ \text{fluent}\,(p)\,. & \text{action}\,(a)\,. & \text{action}\,(b)\,. & \text{init}\,(p)\,. \\ \\ \text{fluent}\,(q)\,. & \text{pre}\,(a,p)\,. & \text{pre}\,(b,q)\,. \\ \\ \text{fluent}\,(r)\,. & \text{add}\,(a,q)\,. & \text{add}\,(b,r)\,. & \text{query}\,(r)\,. \\ \\ & & \text{del}\,(a,p)\,. & \text{del}\,(b,q)\,. \end{array}
```



Problem encoding

```
holds(P,0) := init(P).
\{ occ(A,T) : action(A) \} = 1 :- time(T).
:- occ(A,T), pre(A,F), not holds(F,T-1).
holds(F,T) := occ(A,T), add(A,F).
holds(F,T) := holds(F,T-1), time(T), not occ(A,T) : del(A,F).
:- query(F), not holds(F,k).
```

Solving

```
clingo planning-encoding.lp planning-instance.lp -c k=2 0
```

Solving

```
$ clingo planning-encoding.lp planning-instance.lp -c k=2 0
clingo version 5.5.0
Reading from planning-encoding.lp ...
Solving...
Answer: 1
[...] occ(a,1) occ(b,2)
SATISFIABLE
```

Models : 1

: 0.001s (Solving: 0.00s) Time

: 0.001s CPU Time



Engineering: Overview

- 18 Meta programming
- 19 Controlling
- 20 Multi-shot solving
- 21 Theory solving
- 22 Heuristic-driven solving



Do it yourself!

 Roland Kaminski, Javier Romero, Torsten Schaub, Philipp Wanko: How to build your own ASP-based system?!
 CoRR abs/2008.06692 (2020)



Outline

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Meta encoding, or ASP in ASP

```
conjunction(B) :- literal_tuple(B),
        hold(L) : literal_tuple(B, L), L > 0;
    not hold(L) : literal_tuple(B,-L), L > 0.

body(normal(B)) :- rule(_,normal(B)), conjunction(B).

body(sum(B,G)) :- rule(_,sum(B,G)),
    #sum { W,L : hold(L), weighted_literal_tuple(B, L,W), L > 0 ;
        W,L : not hold(L), weighted_literal_tuple(B,-L,W), L > 0 } >= G.

hold(A) : atom_tuple(H,A) :- rule(disjunction(H),B), body(B).
{ hold(A) : atom_tuple(H,A) } :- rule( choice(H),B), body(B).

#show.
#show T : output(T,B), conjunction(B).
```

An example, running

■ Logic program ezy.lp

```
{a}.
b :- a.
c :- not a.
```

Running

```
$ clingo ezy.lp 0
clingo version 5.5.0
Reading from ezy.lp
Solving...
Answer: 1
c
Answer: 2
a b
```



An example, running

■ Logic program ezy.lp

```
{a}.
b :- a.
c :- not a.
```

Running

```
$ clingo ezy.lp 0
clingo version 5.5.0
Reading from ezy.lp
Solving...
Answer: 1
c
Answer: 2
a b
SATISFIABLE
```



An example, running reified

■ Logic program ezy.lp

```
{a}.
b :- a.
c :- not a.
```

Running reified

```
$ clingo --output=reify ezy.lp | clingo - meta.lp o
clingo version 5.5.0
Reading from - ...
Solving...
Answer: 1
c
Answer: 2
a b
SATISFIABLE
```



An example, running reified

■ Logic program ezy.lp

```
{a}.
b :- a.
c :- not a.
```

■ Running reified

```
$ clingo --output=reify ezy.lp | clingo - meta.lp 0
clingo version 5.5.0
Reading from - ...
Solving...
Answer: 1
c
Answer: 2
a b
SATISFIABLE
```



Outline

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Taming the ASP system, imperatively

- Three alternative ways of combining ASP with other languages, either via
 - embedded script
 - module import
 - application class
- We use Python, although other choices exist



An example

■ Input program example.lp

```
num(3).
num(6).
div(N,@divisors(N)) :- num(N).
```

Resulting program

```
num(3).
num(6).
div(3,(1;3)).
div(6,(1;2;3;6)).
```



An example

■ Input program example.lp

```
num(3).
num(6).
div(N,@divisors(N)) :- num(N).
```

■ Resulting program

```
num(3).
num(6).
div(3,(1;3)).
div(6,(1;2;3;6)).
```



Embedded script (embedded.lp)

```
#script (python)
import clingo
def divisors(a):
    a = a.number
    for i in range(1, a+1):
        if a % i == 0:
            yield clingo.Number(i)
#end.
```



Embedded script, running

```
$ clingo example.lp embedded.lp
clingo version 5.5.0
Reading from example.lp ...
Solving...
Answer: 1
num(3) num(6) div(3,1) div(3,3) \
div(6,1) div(6,2) div(6,3) div(6,6)
SATISFIABLE
```



Module import (module.py)

```
import clingo
class ExampleApp:
    @staticmethod
    def divisors(a):
        a = a.number
        for i in range(1, a+1):
            if a % i == 0:
              yield clingo.Number(i)
    def run(self):
        ctl = clingo.Control()
        ctl.load("example.lp")
        ctl.ground([("base", [])], context=self)
        ctl.solve(on_model=print)
if __name__ == "__main__":
    ExampleApp().run()
```



Embedded script, running

```
$ python module.py
num(3) num(6) div(3,1) div(3,3) \
div(6,1) div(6,2) div(6,3) div(6,6)
```



Application class (app.py)

```
import sys
import clingo
class ExampleApp(clingo.Application):
    program_name = "example"
    version = "1.0"
    @staticmethod
    def divisors(a):
        a = a.number
        for i in range(1, a+1):
            if a % i == 0:
                vield clingo.Number(i)
    def main(self, ctl, files):
        for path in files: ctl.load(path)
        if not files:
            ctl.load("-")
        ctl.ground([("base", [])], context=self)
        ctl.solve()
if __name__ == "__main__":
    clingo.clingo_main(ExampleApp(), sys.argv[1:])
```



Application class, running

```
$ python app.py example.lp
example version 1.0
Reading from example.lp
Solving...
Answer: 1
num(3) num(6) div(3,1) div(3,3) \
div(6,1) div(6,2) div(6,3) div(6,6)
SATISFIABLE
```



What to use when...?

embedded script

- suitable for small amendments to the logic program, anything on the term level during grounding
- perform calculations that are hard or inconvenient to express in ASP

■ module import

- convenient way to use *clingo* as part of a larger project
- provides high level functions to control grounding and solving
- surrounding application is in charge of the control flow and ASP is used to perform specific computations

application class

- aims at building custom systems based on *clingo*
- similar to module import but with more customization capabilities

constitutes the cornerstone of recent *clingo*-based systems such as *clingcon*, *clingo*[DL], *eclingo*, and *telingo*

Outline

- 18 Meta programming
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- 22 Heuristic-driven solving



Motivation

■ Multi-shot solving allows for solving continuously changing logic programs in an operative way

■ Single-shot solving: ground | solve

Multi-shot solving: ground | solve

Agents, Assisted Living, Robotics, Planning, Query-answering, etc

clingo = ASP + Control

Extend ASP with dedicated directives

Provide powerful API (here: Python)



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Structuring logic programs

■ Program directive

```
#program <name> [ (<parameters>) ]
```

where

- <name> is a term
- (<parameters>) is a tuple of terms
- Example #program play(p,t).
- Default #program base.



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An example (chemistry.lp)

```
a(1).
#program acid(k).
b(k).
c(X,k) :- a(X).
#program base.
a(2).
```



The example, processing (control-base.py)

```
import clingo
ctl = clingo.Control()
ctl.load("chemistry.lp")
ctl.ground([("base", [])])
ctl.solve(on_model=print)
```

```
a(1).
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$ python control-base.py
a(1) a(2)
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The example, processing (control-acid.py)

```
import clingo
ctl = clingo.Control()
ctl.load("chemistry.lp")
ctl.ground([("acid",[42])])
ctl.solve(on_model=print)
```

```
a(1).
#program acid(k).
b(k).
c(X,k) :- a(X).
#program base.
a(2).
```

```
$ python control-acid.py
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b(k).
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#program base.
a(2).
```

```
$ python control-acid.py
b(42)
```



External atoms

■ External directive

```
#external <atom> [ : <body> ]
```

where

```
■ <atom> [ : <body> ] is a (conditional) literal
```

- Example #external mark(X,Y,p,t) : field(X,Y).
- Note External atoms are
 - protected from program simplifications
 - assigned truth values via API (default: false)

and can be

- overwritten by adding rules defining the atom
- permanently set to false



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- permanently set to false



An example (chemistry-external.lp)

```
#program acid(k).
b(k).
c(X,k) :- a(X).
#program base.
a(2).

#program acid(k).
#external d(X,k) : c(X,k).
e(X,k) :- d(X,k).
```

Note Grounding both base and acid(42) yields two externals



a(1).

An example (chemistry-external.lp)

```
#program acid(k).
b(k).
c(X,k) :- a(X).
#program base.
a(2).

#program acid(k).
#external d(X,k) : c(X,k).
e(X,k) :- d(X,k).
```

Note Grounding both base and acid(42) yields two externals



a(1).

An example (chemistry-external.lp)

```
#program acid(k).
b(k).
c(X,k) :- a(X).
#program base.
a(2).

#program acid(k).
#external d(X,k) : c(X,k).
e(X,k) :- d(X,k).
```

Note Grounding both base and acid(42) yields two externals



a(1).

The example, processing (control-external.py)

```
ctl = clingo.Control()
ctl.load("chemistry-external.lp")
ctl.ground([("base", []),("acid",[42])])
ctl.solve(on_model=print)
ctl.assign_external(Function("d", [2,42]), True)
ctl.solve(on_model=print)
```

```
$ python control-external.py
a(1) a(2) c(1,42) c(2,42) b(42)
a(1) a(2) c(1,42) c(2,42) b(42) d(2,42) e(2,42)
```



The example, processing (control-external.py)

```
ctl = clingo.Control()
ctl.load("chemistry-external.lp")
ctl.ground([("base", []),("acid",[42])])
ctl.solve(on_model=print)
ctl.assign_external(Function("d", [2,42]), True)
ctl.solve(on_model=print)
```

```
$ python control-external.py
a(1) a(2) c(1,42) c(2,42) b(42)
a(1) a(2) c(1,42) c(2,42) b(42) d(2,42) e(2,42)
```





```
#program base.
p(0).
#program step (t).
p(t) :- p(t-1).
#program check (t).
#external query(t). % added in python below
:- not p(42), query(t).
```





```
#program base.
p(0).
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#external query(t). % added in python below
:- not p(42), query(t).
```



Incremental solving



Incremental solving, zoom on register_options

```
def register_options(self, options: ApplicationOptions):
    Register program options.
    group = "Inc-Example Options"
    options.add(
        group, "imin",
        "Minimum number of steps [{}]".format(self._conf.imin),
        parse_int(self._conf, "imin", min_value=0),
        argument = " < n > ")
    options.add(
        group, "imax",
        "Maximum number of steps [{}]".format(self._conf.imax),
        parse_int(self._conf, "imax", min_value=0, optional=True),
        argument = " < n > ")
    options.add(
        group, "istop",
        "Stop criterion [{}]".format(self._conf.istop),
        parse_stop(self._conf, "istop"))
```

Check it out!

```
UNIX> python inc.py --help
[...]
Inc-Example Options:
   --imin=<n> : Minimum number of steps [1]
   --imax=<n> : Maximum number of steps [None]
   --istop=<arg> : Stop criterion [SAT]
```



Incremental solving, zoom on main

```
def main(self, ctl: Control, files: Iterable[str]):
    The main function implementing incremental solving.
    if not files:
        files = \lceil "-" \rceil
    for file in files:
        ctl.load(file_)
    ctl.add("check", ["t"], "#external query(t).")
    conf = self conf
    step = 0
    ret: Optional[SolveResult] = None
    while ((conf.imax is None or step < conf.imax) and
           (ret is None or step < conf.imin or (
               (conf.istop == "SAT" and not ret.satisfiable) or
               (conf.istop == "UNSAT" and not ret.unsatisfiable) or
               (conf.istop == "UNKNOWN" and not ret.unknown)))):
        parts = []
        parts.append(("check", [Number(step)]))
        if step > 0:
            ctl.release_external(Function("query", [Number(step - 1)]))
            parts.append(("step", [Number(step)]))
        else:
            parts.append(("base", []))
        ctl.ground(parts)
        ctl.assign_external(Function("query", [Number(step)]), True)
        ret, step = cast(SolveResult, ctl.solve()), step + 1
```



Let's run it!

```
UNIX > python inc.py tohE.lp tohI.lp
inc-example version 1.0
Reading from tohE.lp ...
Solving...
[...]
Solving...
Answer: 1
move (4,b,1)
              move(3,c,2) move(4,c,3) move(2,b,4)
move(4,a,5)
             move(3,b,6) \quad move(4,b,7) \quad move(1,c,8) \setminus
move(4,c,9)
              move(3,a,10) move(4,a,11) move(2,c,12) 
move (4.b.13)
              move(3,c,14)
                            move (4, c, 15)
SATISFIABLE
Models
              : 1+
Calls
              : 16
```



Optimization

- Imagine some Blocksworld planning problem ...
- Code snippet

```
ngoal(T) := not on(B,L,T), goal_on(B,L), time(T).
:- ngoal(n).
```

where n is a fixed horizon

Optimization

```
_minimize(1,T) :- ngoal(T).
```



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ngoal(T) := not on(B,L,T), goal_on(B,L), time(T).
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```

where n is a fixed horizon

Optimization

```
_{\text{minimize}}(1,T) := \text{ngoal}(T).
```



Optimization

```
Example to show branch and bound based optimization using multi-shot solving.
import sys
from typing import Optional. Iterable, cast
from clingo import Model, Control, SolveResult, SymbolType, Application, Number, clingo_main
class OptApp(Application):
   Example application.
   program_name: str = "opt-example"
   version: str = "1.0"
   _bound: Optional[int]
   def __init__(self):
        self._bound = None
   def _on_model(self, model: Model):
        self._bound = 0
        for atom in model.symbols(atoms=True):
            if (atom.match("_minimize", 2) and
                    atom.arguments[0].type is SymbolType.Number):
                self._bound += atom.arguments[0].number
   def main(self, ctl: Control, files: Iterable[str]):
        Main function implementing branch and bound optimization.
       if not files:
            files = ["-"]
       for file, in files:
            ctl.load(file_)
        ctl.add("bound", ["b"].
                ":- #sum { V, I: _minimize(V, I) } >= b.")
       ctl.ground([("base", [])])
        while cast(SolveResult, ctl.solve(on_model=self._on_model)).satisfiable:
            print("Found new bound: {}".format(self._bound))
            ctl.ground([("bound", [Number(cast(int, self._bound))])])
       if self._bound is not None:
            print("Optimum found")
clingo_main(OptApp(), sys.argv[1:])
```



Optimization, zoom on main

```
def main(self, ctl: Control, files: Iterable[str]):
    Main function implementing branch and bound optimization.
    if not files:
        files = \lceil "-" \rceil
    for file in files:
        ctl.load(file_)
    ctl.add("bound", ["b"],
            ":- \#sum \{V,I: \_minimize(V,I)\} >= b."
    ctl.ground([("base", [])])
    while cast(SolveResult, ctl.solve(on_model=self._on_model)).satisfiable:
        print("Found new bound: {}".format(self._bound))
        ctl.ground([("bound", [Number(cast(int, self._bound))])])
    if self._bound is not None:
        print("Optimum found")
```



Optimization, zoom on _on_model



Let's run it!

```
UNIX> python opt.py tohB.lp tohI.lp -c n=17
opt-example version 1.0
Reading from tohB.lp ...
Solving ...
Answer: 1
move(4,b,1) move(3,c,2)
                          move(4,a,3)
                                       move(4,c,4) move(2,b,5) \
move(4.a.6) move(3.b.7)
                          move(4.c.8)
                                       move(4.b.9)
                                                    move(1,c,10) \
move(4,c,11) move(3,a,12)
                          move(4.a.13) move(2.c.14) move(4.b.15)
move(3.c.16) move(4.c.17)
Found new bound: 17
Solving...
Answer: 1
move(4.b.1)
             move(3.c.2)
                          move(4.c.3)
                                       move(2,b,4)
                                                    move(4.a.5) \
move(3,b,6)
             move(4,c,7)
                          move(4,b,8) move(1,c,9)
                                                    move(4,c,10) \
move(3.a.11) move(4.a.12) move(2.c.13) move(4.b.14) move(3.c.15)
move (4,c,16)
Found new bound: 16
Solving...
Answer: 1
move(4,b,1)
             move(3,c,2)
                          move(4,c,3)
                                       move(2,b,4)
                                                    move(4,a,5) \
move(3.b.6)
             move(4.b.7)
                          move(1,c,8)
                                       move(4.c.9)
                                                    move(3.a.10) \
move(4,a,11) move(2,c,12)
                          move(4,b,13) move(3,c,14) move(4,c,15)
Found new bound: 15
Solving ...
Optimum found
```



UNSATISFIABLE

Outline

- 18 Meta programming
- 19 Controlling
- 20 Multi-shot solving
- 21 Theory solving
- 22 Heuristic-driven solving



- Input ASP = DB + KRR + LP + SAT
- Output ASPmT = DB+KRR+LP+S
- ASP solving: ground | solve
- Challenge Logic programs with elusive theory atoms
- Application areas



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- Output ASPmT = DB+KRR+LP+S
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- Input ASP = DB + KRR + LP + SAT
- \blacksquare Output ASPmT = DB+KRR+LP+SMT
- ASP solving: ground | solve
- Challenge Logic programs with elusive theory atoms
- Application areas



- Input ASP = DB + KRR + LP + SAT
- Output ASPmT = DB+KRR+LP+SMT **NO!**
- ASP solving: ground | solve
- Challenge Logic programs with elusive theory atoms
- Application areas



- Input ASP = DB + KRR + LP + SAT
- \blacksquare Output ASPmT = (DB+KRR+LP+SAT)mT
- ASP solving: *ground* | *solve*
- Challenge Logic programs with elusive theory atoms
- Application areas



- Input ASP = DB + KRR + LP + SAT
- \blacksquare Output ASPmT = (DB+KRR+LP+SAT)mT
- ASP solving: ground | solve
- Challenge Logic programs with elusive theory atoms
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- Input ASP = DB + KRR + LP + SAT
- Output ASPmT = (DB+KRR+LP+SAT)mT
- ASP solving modulo theories: ground % theories | solve % theories
- Challenge Logic programs with elusive theory atoms
- Application areas



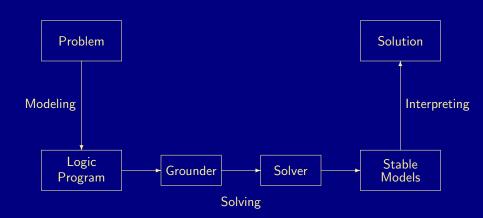
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- ASP solving modulo theories: ground % theories | solve % theories
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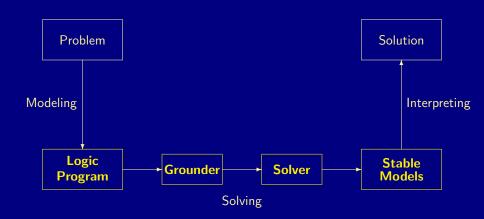
- Input ASP = DB + KRR + LP + SAT
- Output ASPmT = (DB+KRR+LP+SAT)mT
- ASP solving modulo theories: ground % theories | solve % theories
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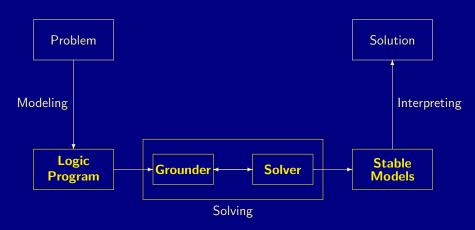
ASP solving process





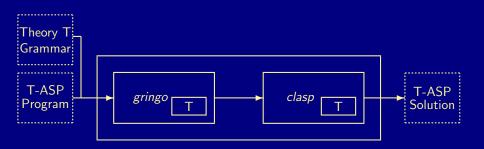








clingo's approach

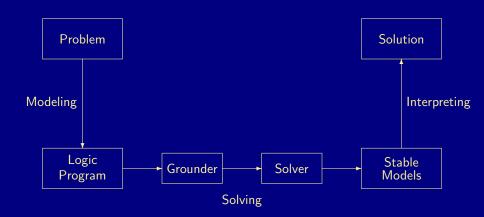




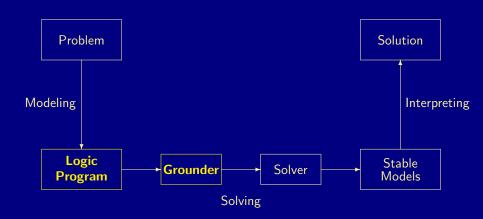
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 - Theory language
 - I heory propagation
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Linear constraints

```
#theory csp {
    linear term {
                                        show term {
      + : 5, unary;
                                         / : 1, binary, left
      - : 5, unary;
      * : 4, binary, left;
      + : 3, binary, left;
      - : 3, binary, left
                                        minimize_term {
                                          + : 5, unary;
                                          - : 5, unary;
    dom term {
                                          * : 4, binary, left;
                                          + : 3, binary, left;
      + : 5, unary;
                                          - : 3, binary, left;
      - : 5, unary;
      .. : 1, binary, left
                                          @ : 0, binary, left
    &dom/0 : dom_term, {=}, linear_term, any;
    &sum/0 : linear_term, {<=,=,>=,<,>,!=}, linear_term, any;
    &show/0 : show term. directive:
    &distinct/0 : linear_term, any;
    &minimize/0 : minimize_term, directive
```

The example has exactly one solution

$$\{ s \mapsto 9, e \mapsto 5, n \mapsto 6, d \mapsto 7, m \mapsto 1, o \mapsto 0, r \mapsto 8, y \mapsto 2 \}$$



Each letter corresponds exactly to one digit and all variables have to be pairwisely distinct

The example has exactly one solution

$$\{ s \mapsto 9, e \mapsto 5, n \mapsto 6, d \mapsto 7, m \mapsto 1, o \mapsto 0, r \mapsto 8, y \mapsto 2 \}$$



```
digit(1,3,s).
                digit(2,3,m).
                                digit(sum,4,m).
digit(1,2,e).
                digit(2,2,0).
                                digit(sum,3,0).
digit(1,1,n).
               digit(2,1,r).
                                digit(sum,2,n).
digit(1,0,d).
               digit(2,0,e).
                                digit(sum,1,e).
                                digit(sum,0,y).
```

```
digit(1,3,s).
                digit(2,3,m).
                                digit(sum,4,m).
                                digit(sum,3,0).
digit(1,2,e).
               digit(2,2,0).
digit(1,1,n). digit(2,1,r).
                               digit(sum,2,n).
digit(1,0,d). digit(2,0,e).
                               digit(sum,1,e).
                                 digit(sum,0,v).
base (10).
exp(E) :- digit(\_,E,\_).
power (1,0).
power (B*P,E): - base (B), power (P,E-1), exp(E), E>0.
number(N) :- digit(N,_,_), N!= sum.
high(D) := digit(N,E,D), not digit(N,E+1,_).
```

```
digit(1,3,s).
               digit(2,3,m).
                               digit(sum,4,m).
digit(1,2,e). digit(2,2,o).
                              digit(sum,3,0).
digit(1,1,n). digit(2,1,r).
                              digit(sum,2,n).
digit(1,0,d). digit(2,0,e).
                              digit(sum,1,e).
                                digit(sum,0,v).
base (10).
exp(E) := digit(_,E,_).
power (1,0).
power (B*P,E): - base (B), power (P,E-1), exp(E), E>0.
number(N) :- digit(N,_,_), N!= sum.
high(D) := digit(N,E,D), not digit(N,E+1,_).
&dom \{0...9\} = X :- digit(_,_,X).
&sum { M*D : digit(N,E,D), power(M,E), number(N);
     -M*D : digit(sum,E,D), power(M,E)
                                                 } = 0.
&sum { D } > 0 :- high(D).
&distinct { D : digit(_,_,D) }.
&show { D : digit(_,_,D) }.
```

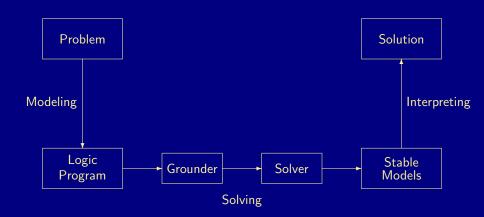
```
digit(1,3,s).
                digit(2,3,m).
                                 digit(sum,4,m).
digit(1,2,e).
                digit(2,2,0).
                                 digit(sum,3,0).
digit(1,1,n).
                digit(2,1,r).
                                 digit(sum,2,n).
digit(1,0,d).
                digit(2,0,e).
                                 digit(sum,1,e).
                                 digit(sum,0,y).
base (10).
\exp(0). \exp(1). \exp(2). \exp(3). \exp(4).
power (1,0).
power(10,1). power(100,2). power(1000,3). power(10000,4).
number(1). number(2).
high(s). high(m).
\& dom \{0..9\} = s. \& dom \{0..9\} = m. \& dom \{0..9\} = e. [...] \& dom \{0..9\} = y.
&sum{ 1000*s: 100*e: 10*n: 1*d:
       1000*m: 100*o: 10*r: 1*e:
     -10000*m: -1000*o: -100*n: -10*e: -1*v } = 0.
& sum{s} > 0. & sum{m} > 0.
&distinct{s; m; e; o; n; r; d; y}.
&show{s; m; e; o; n; r; d; y}.
```

```
UNIX > clingcon sendmoremoney.lp 0
clingcon version 5.0.0
Reading from smm.clp
Solving...
Answer: 1
base (10) \exp(0) \exp(1) \exp(2) \exp(3) \exp(4)
high(m) high(s) number(1) number(2)
power(1,0) power(10,1) power(100,2) power(1000,3) power(10000,4)
digit(1,0,d) digit(1,1,n) digit(1,2,e) digit(1,3,s)
digit(2,0,e) digit(2,1,r) digit(2,2,o) digit(2,3,m)
digit(sum,0,y) digit(sum,1,e) [...] digit(sum,4,m)
Assignment:
d=7 e=5 m=1 n=6 o=0 r=8 s=9 v=2
SATISFIABLE
Models : 1
Calls : 1
Time : 0.001s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
CPU Time
            : 0.001s
```

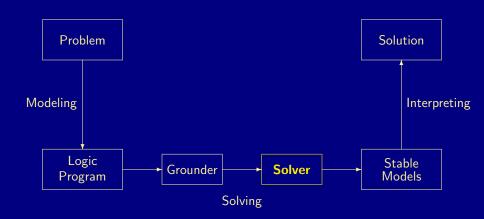
Outline

- 18 Meta programming
- 19 Controlling
- 20 Multi-shot solving
- 21 Theory solving
 - Theory language
 - Theory propagation
- 22 Heuristic-driven solving

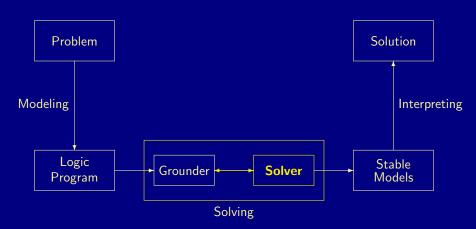














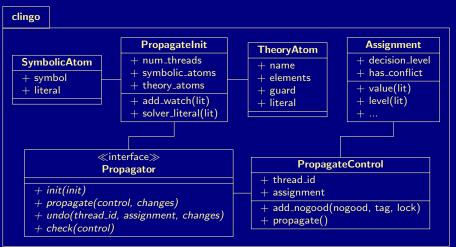
Conflict-driven constraint learning

modulo theories

```
initialize
                                              // register theory propagators and initialize watches
    dool
       propagate completion, loop, and recorded nogoods
                                                                  // deterministically assign literals
      if no conflict then
         if all variables assigned then
           if some \delta \in \Delta_T is violated for T \in \mathbb{T} then record \delta // theory propagator's check
(C)
           else return variable assignment
                                                                           // T-stable model found
         else
(P)
            propagate theories T \in \mathbb{T}
                                                // theory propagators may record theory nogoods
           if no nogood recorded then decide
                                                       // non-deterministically assign some literal
      else
         if top-level conflict then return unsatisfiable
         else
            analyze
                                                // resolve conflict and record a conflict constraint
(U)
            backiump
                                                 undo assignments until conflict constraint is unit
```



Propagator interface





The dot propagator

```
#script (python)
import sys
import time
class Propagator:
    def init(self. init):
        self.sleep = .1
        for atom in init.symbolic_atoms:
            init.add watch(init.solver literal(atom.literal))
    def propagate(self, ctl, changes):
        for 1 in changes:
            sys.stdout.write(".")
            sys.stdout.flush()
            time.sleep(self.sleep)
        return True
    def undo(self, solver_id, assign, undo):
        for 1 in undo:
            sys.stdout.write("\b \b")
            sys.stdout.flush()
            time.sleep(self.sleep)
def main(prg):
    prg.register_propagator(Propagator())
    prg.ground([("base", [])])
    prg.solve()
    sys.stdout.write("\n")
#end
```



Outline

- 18 Meta programming
- 19 Controlling
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- Observation Sometimes it is advantageous to take a more application-oriented approach by including domain-specific information
 - domain-specific knowledge can be added for improving propagation
 - domain-specific heuristics can be used for making better choices
- Idea Incorporation of domain-specific heuristics by extending
 - input language and/or solver options for expressing domain-specific heuristics
 - solving capacities for integrating domain-specific heuristics



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CDCL-style solving

```
loop
                                           // deterministically assign literals
    propagate
    if no conflict then
         if all variables assigned then return solution
         else decide
                                 // non-deterministically assign some literal
    else
         if top-level conflict then return unsatisfiable
         else
                             // analyze conflict and add conflict constraint
               backjump // unassign literals until conflict constraint is unit
```



Heuristic directive

```
#heuristic a: I_1, \ldots, I_n. [k@p, m]
```

where

- \blacksquare a is an atom, and l_1, \ldots, l_n are literals
- k and p are integers
- m is a heuristic modifier

Heuristic modifiers

```
init for initializing the heuristic value of a with k
factor for amplifying the heuristic value of a by factor k
level for ranking all atoms; the rank of a is k
sign for attributing the sign of k as truth value to a
```

Example

```
#heuristic occurs(A,T) : action(A), time(T). [T, factor]
```



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level for ranking all atoms; the rank of a is k
sign for attributing the sign of k as truth value to a
true/false combine level and sign

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■ Example

#heuristic occurs(mv,5) : action(mv), time(5). [5, factor]



```
time(1..k).
holds(P,0) :- init(P).
{ occ(A,T) : action(A) } = 1 :- time(T).
:- occ(A,T), pre(A,F), not holds(F,T-1).
holds(F,T) :- occ(A,T), add(A,F).
holds(F,T) :- holds(F,T-1), time(T), not occ(A,T) : del(A,F).
:- query(F), not holds(F,k).
```



```
time(1..k).
holds(P,0) := init(P).
\{ \operatorname{occ}(A,T) : \operatorname{action}(A) \} = 1 :- \operatorname{time}(T).
:- occ(A,T), pre(A,F), not holds(F,T-1).
holds(F,T) := occ(A,T), add(A,F).
holds(F,T) := holds(F,T-1), time(T), not occ(A,T) : del(A,F).
:- query(F), not holds(F,k).
#heuristic occurs(A,T) : action(A), time(T). [2, factor]
```



```
time(1..k).
holds(P,0) := init(P).
\{ \operatorname{occ}(A,T) : \operatorname{action}(A) \} = 1 :- \operatorname{time}(T).
:- occ(A,T), pre(A,F), not holds(F,T-1).
holds(F,T) := occ(A,T), add(A,F).
holds(F,T) := holds(F,T-1), time(T), not occ(A,T) : del(A,F).
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#heuristic occurs(A,T) : action(A), time(T). [1, level]
```



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```



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holds(F,T) := holds(F,T-1), time(T), not occ(A,T) : del(A,F).
:- query(F), not holds(F,k).
#heuristic holds(F,T-1) : holds(F,T). [t-T+1, true]
#heuristic holds(F,T-1) : not holds(F,T) [t-T+1, false]
                             fluent(F), time(T).
```



Heuristic options

■ Alternative for specifying structure-oriented heuristics in *clasp*

Engage heuristic modifications (in both settings!)

```
--heuristic=Domain
```



Heuristic options

■ Alternative for specifying structure-oriented heuristics in *clasp*

```
--dom-mod=<arg>: Default modification for domain heuristic

<arg>: <mod>[,<pick>]

<mod>: Modifier

{1=level|2=pos|3=true|4=neg|

5=false|6=init|7=factor}

<pick>: Apply <mod> to

{0=all|1=scc|2=hcc|4=disj|

8=min|16=show} atoms
```

Engage heuristic modifications (in both settings!)

```
--heuristic=Domain
```



Heuristic options

■ Alternative for specifying structure-oriented heuristics in *clasp*

■ Engage heuristic modifications (in both settings!)

```
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Inclusion-minimal stable models

- Consider a logic program containing a mimimize statement of form
 - \blacksquare #minimize $\{a_1,\ldots,a_n\}$
- Computing one inclusion-minimal stable model can be done either via
 - lacksquare #heuristic a_i [1,false]. for $i=1,\ldots,n$, or
 - --dom-mod=5,16
- Computing all inclusion-minimal stable model can be done
 - by adding --enum-mod=domRec to the two options



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Applications: Overview

- 23 Train scheduling
- 24 Robotic intra-logistics



Outline

23 Train scheduling

24 Robotic intra-logistics



- Increasing railway traffic demands global and flexible ways for scheduling trains in order to use railway networks to capacity
- Difficulty arises from dependencies among trains induced by connections and shared resources
- Train scheduling combines three distinct tasks
 - Routing
 - Conflict detection and resolution
 - Scheduling
- Solution operational at Swiss Federal Railway using clingo[DL]
 - ASP
 - Difference constraints
 - (Hybrid) Optimization
 - Heuristic directives
 - Multi-shot solving



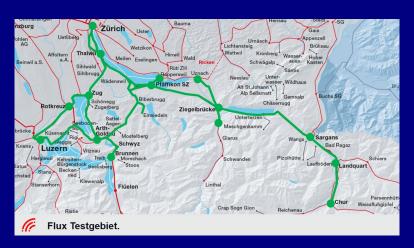
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Benchmark



We optimally solved the train scheduling problem on real-world railway networks spanning about 150 km with up to 467 trains within 5 ***Rutes**sco

Outline

- 23 Train scheduling
- 24 Robotic intra-logistics



- Objective How to develop robust and scalable AI technology for dealing with complex dynamic application scenarios?
- What's needed? a fruit fly!
 Robotic intra-logistics
- Why?

```
rich multi-faceted, full of variations
```

scalable layout, objects, granularity

measurable makespan, energy, quality of service

integrative mapf, data, constraints, decisions

■ relevant industry 4.0

■ What for? — enabling research and teaching



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Robotic intra-logistics

- Robotics systems for logistics and warehouse automation based on many
 - mobile robots
 - movable shelves
- Main tasks: order fulfillment, i.e.
 - routing
 - order picking
 - replenishment
- Many competing industry solutions:
 - Amazon, Dematic, Genzebach, Gray Orange, Swisslog
- https://youtu.be/TUx-ljgB-5Q





What's (not) in the picture?

- Objects floor, robots, shelves, products, people, etc.
- Relations positions, carries/d, capacity, orientation, durations, etc.
- Actions
 move, pickup, putdown, pick, charge, restock, etc.
- Objectives deadlines, throughput, exploitation, energy management, human machine interaction, etc.



Making robots dance

via temporal and dynamic ASP

■ Visit https://potassco.org/asprilo



Outline

- 25 Potassco
- 26 Take home messages



Potassco

- Potassco Systems http://potassco.org
 - Academic branch
 - Freely available systems
 - Open source license (MIT)
- Potassco Solutions http://potassco.com
 - Service branch
 - Consulting
 - Engineering

- Maintenance
- Training

Sites Germany (HQ@Potsdam), Australia, Austria, China, Cyprus, Finland, France, Japan, Portugal, Spain, Turkey



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Outline

25 Potassco

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The benefits of ASP

It's yours!

- + Transparency
- + Flexibility
- + Maintainability
- + Reliability
- + Generality
- + Effectiveness
- + Optimality
- + Availability

ASP is a technology, products emerge from co-operations



Solver



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Potassco



Modeling + Grounding + Solving



Modeling + Grounding + Solving

$$ASP = DB+LP+KR+SAT$$



Modeling + Grounding + Solving $ASP = DB + LP + KR + SMT^{n}$



Modeling + Grounding + Solving

$$ASP = DB+LP+KR+SMT^n$$

https://potassco.org



Modeling + Grounding + Solving

$$ASP = DB+LP+KR+SMT^n$$

https://potassco.org

And it's fun!



- [1] M. Gebser, R. Kaminski, B. Kaufmann, M. Lindauer, M. Ostrowski, J. Romero, T. Schaub, and S. Thiele. Potassco User Guide. University of Potsdam, 2 edition, 2015.
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